

# PASCAL

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A Parallel Algorithmic SCALable Framework  
for N-body Problems

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Euro-Par 2017

# Outline

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- Introduction
- PASCAL Framework
  - Space Partitioning Trees
  - Tree Traversal
  - Prune/Approximate Generators
- Optimizations & Parallelization
- Experiments & Results
- Conclusions & Future Work

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# N-body calculations

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$$\forall q \in Q : F(q) = \sum_{r \in (Q - \{q\})} C \frac{r - q}{\|r - q\|^3} \quad \textit{Force computation}$$

$$\forall q \in Q : \text{AllNN}(q) = \operatorname{argmin}_{r \in R} d(q, r) \quad \textit{Nearest neighbors}$$

$$\forall q \in Q : \text{KDE}(q) = \frac{1}{|R|} \sum_{r \in R} K(q, r) \quad \textit{Kernel density estimation}$$

$$\forall q \in Q : \text{Range}(q) = \sum_{r \in R} I(\text{dist}(q, r)) \leq h \quad \textit{Range count}$$

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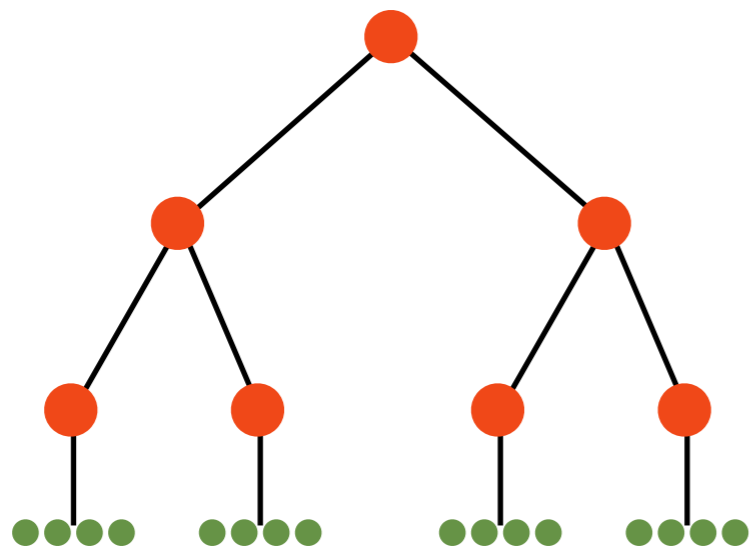
Consider pairs of points – naïvely  $O(N^2)$

# Commonality: Optimal approximation algorithms

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$$\forall q \in Q : F(q) = \sum_{r \in (Q - \{q\})} C \frac{r - q}{\|r - q\|^3} \quad \textit{Force computation}$$

- Hierarchical tree-based approximation algorithms for force computations, *e.g.*, Barnes-Hut or FMM



Evaluate interactions  
→ Tree traversals

Store aggregate data at nodes, *e.g.*, bounding box, mass

# N-body problems in other domains

Problem	Operators	Kernel Function
All Nearest Neighbors	$\forall, \arg \min$	$\ x_q - x_r\ $
All Range Search	$\forall, \cup \arg$	$I(h_{min} < \ x_q - x_r\  < h_{max})$
All Range Count	$\forall, \Sigma$	$I(h_{min} < \ x_q - x_r\  < h_{max})$
Naive Bayes Classifier	$\forall, \arg \max$	$(1/\sqrt{2\pi \Sigma_k })e^{-\frac{1}{2}(x_i-\mu_k)^T \Sigma_k^{-1}(x_i-\mu_k)} P(C_k)$
Mixture Model E-step	$\forall, \forall$	$(1/\sqrt{2\pi \Sigma_k })e^{-\frac{1}{2}(x_i-\mu_k)^T \Sigma_k^{-1}(x_i-\mu_k)}$
K-means E-step	$\forall, \arg \min$	$\ x_q - x_r\ $
Mixture Model Log-likelihood	$\Sigma, \log \Sigma$	$(1/\sqrt{2\pi \Sigma_k })e^{-\frac{1}{2}(x_i-\mu_k)^T \Sigma_k^{-1}(x_i-\mu_k)}$
Kernel Density Estimation	$\forall, \Sigma$	$\phi(\frac{\ x_q - x_r\ }{h})$
Kernel Density Bayes Classifier	$\forall, \arg \max \Sigma$	$\phi(\frac{\ x_q - x_r\ }{h}) P(C_k)$
2-point (cross-)correlation	$\Sigma, \Sigma$	$I(\ x_q - x_r\  < h)$
Nadaraya-Watson Regression	$\forall, \Sigma$	$y_r \phi(\frac{\ x_q - x_r\ }{h})$
Thermodynamic Average	$\Sigma, \Sigma$	$\phi(\ x_q - x_r\ )$
Largest-span set	$\max, \dots, \max$	$\Sigma(\ x_q - x_r\ )$
Closest Pair	$\arg \min, \arg \min$	$\ x_q - x_r\ $
Minimum Spanning Tree	$\forall, \arg \min$	$\ x_q - x_r\ $
Coulombic Interaction	$\forall, \Sigma$	$\frac{\alpha_q \alpha_r}{\ x_q - x_r\ }$
Average Density	$\Sigma, \Sigma$	$I(\ x_q - x_r\  < h)$
Wave function	$\forall, \Pi$	$\phi(\ x_q - x_r\ )$
Hausdorff Distance	$\max, \min$	$\ x_q - x_r\ $
Intrinsic (fractal) Dimension	$\Sigma, \Sigma$	$I(\ x_q - x_r\  < h)$

Each problem has a set of **operators** and a **kernel function**



# Why N-body methods?

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- One of the original seven dwarfs or motifs
- FMM listed among the top 10 algorithms having the greatest influence in 20<sup>th</sup> century
- EM is one of the top 10 algorithms having the highest impact in data mining
- Applications
  - Machine learning
  - Computer vision
  - Computational geometry
  - Scientific computing ...

# Key Ideas and Findings

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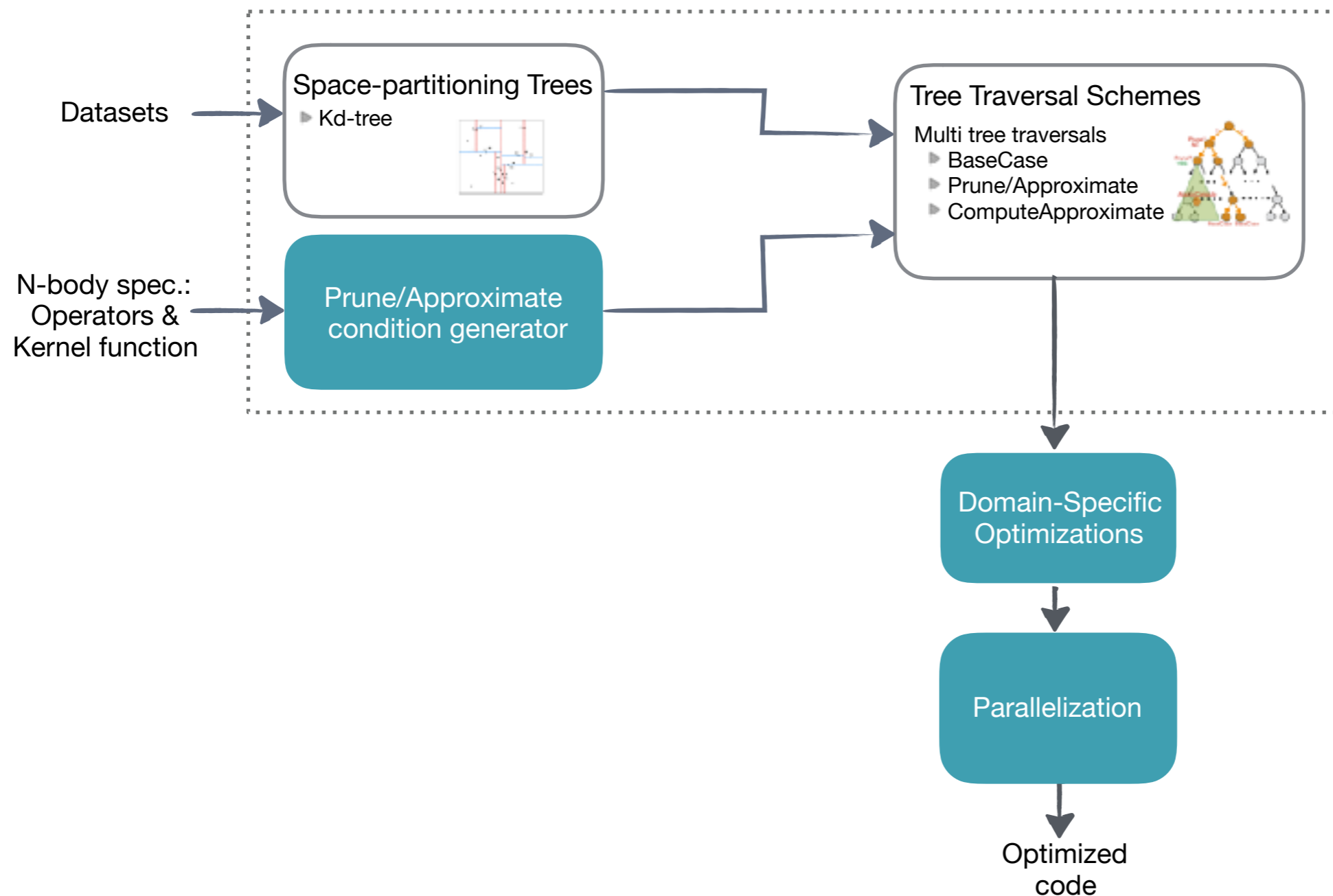
- An algorithmic framework for N-body problems
  - Automatically generates prune & approximation conditions
  - Results in  $O(N \log N)$  and  $O(N)$  algorithms
  - Domain-specific optimizations and parallelization
- Show 10-230x speedup on 6 different algorithms compared to state-of-art libraries/softwarewares
- Out-of-the-box new optimal algorithms
  - $O(N \log N)$  EM algorithm for GMM's
  - $O(N)$  algorithm for Hausdorff distance

# Outline

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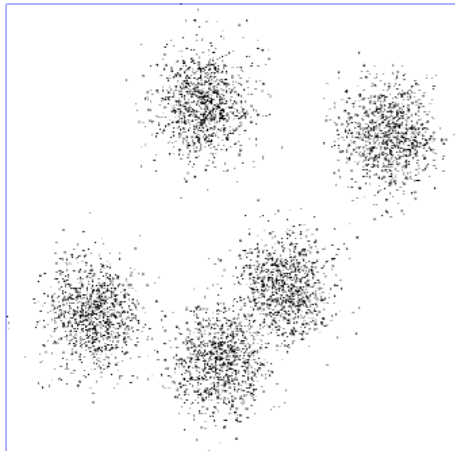
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# PASCAL Framework



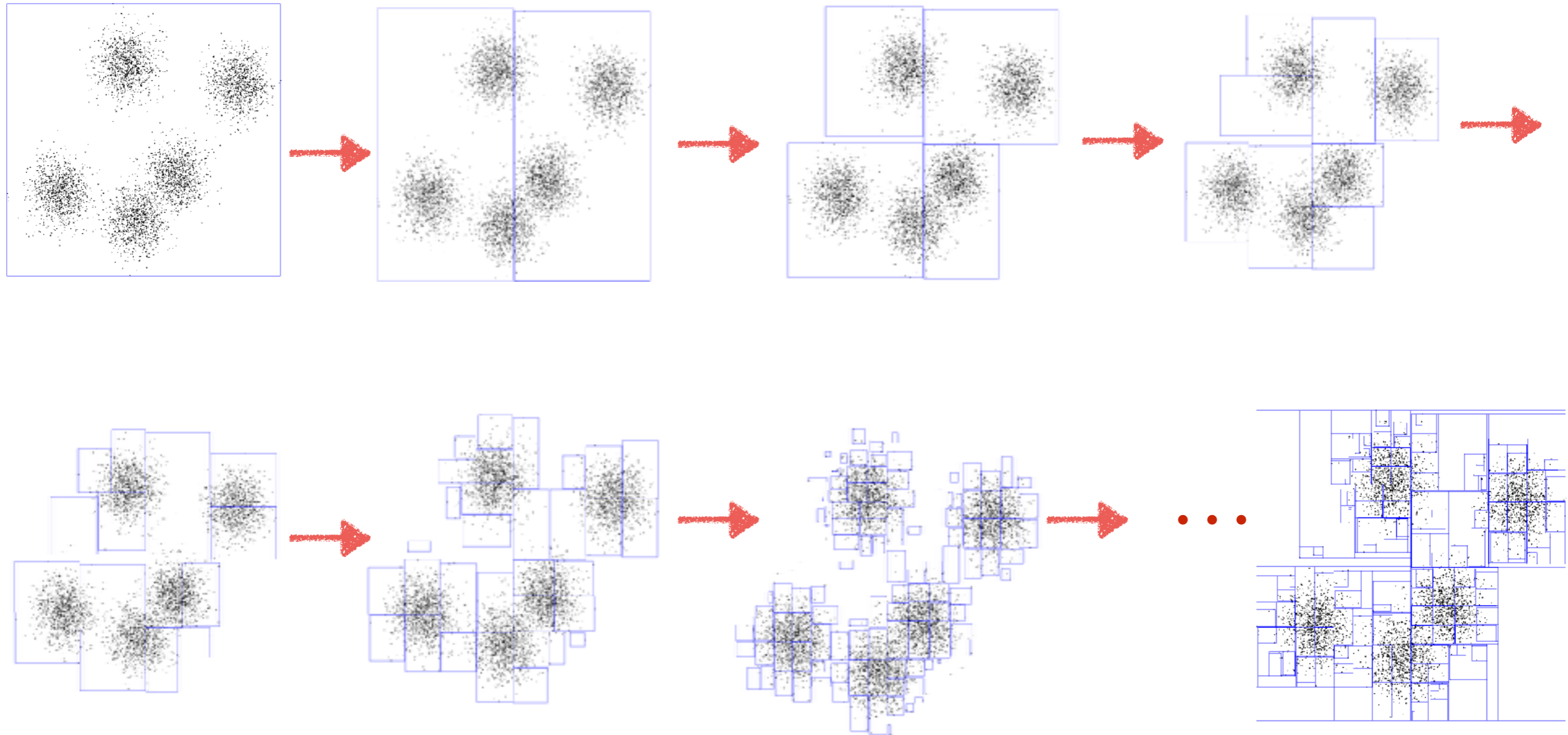
# Tree Construction

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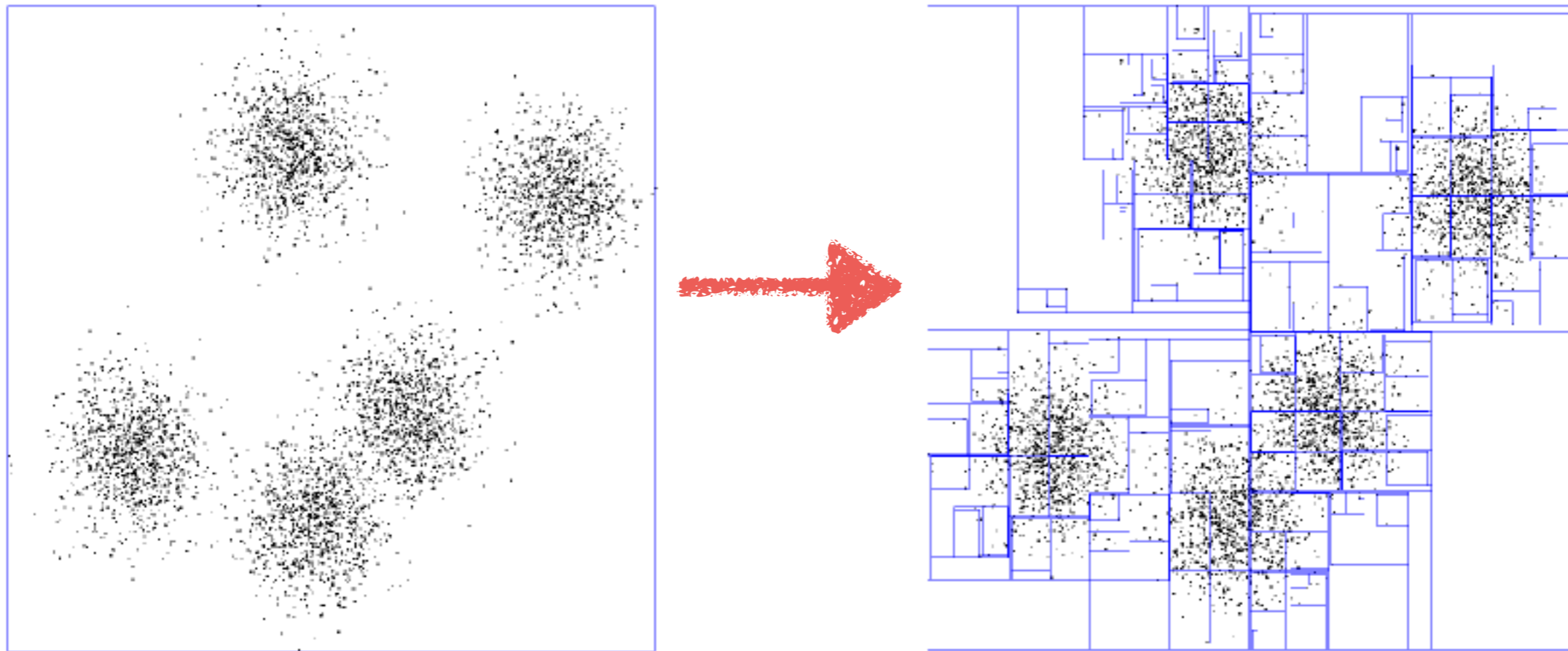
Recursively divide space until each box has **at most  $q$  points**.

# Tree Construction



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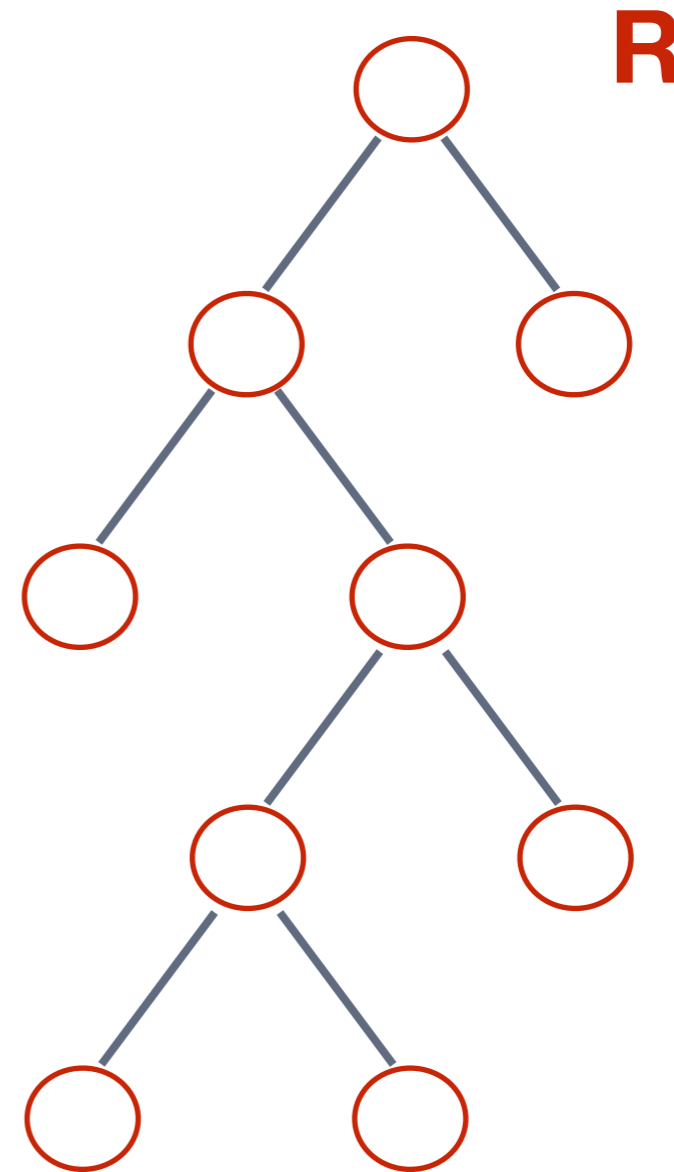
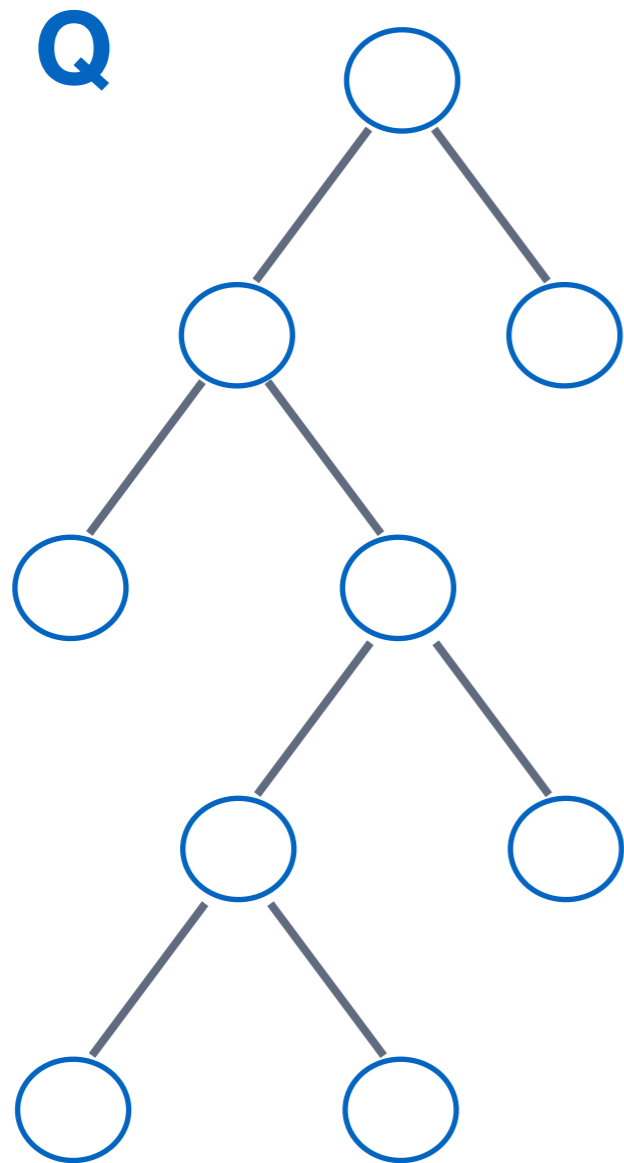
# Tree Construction



Recursively divide space until each box has **at most  $q$  points**.

# Tree Traversal

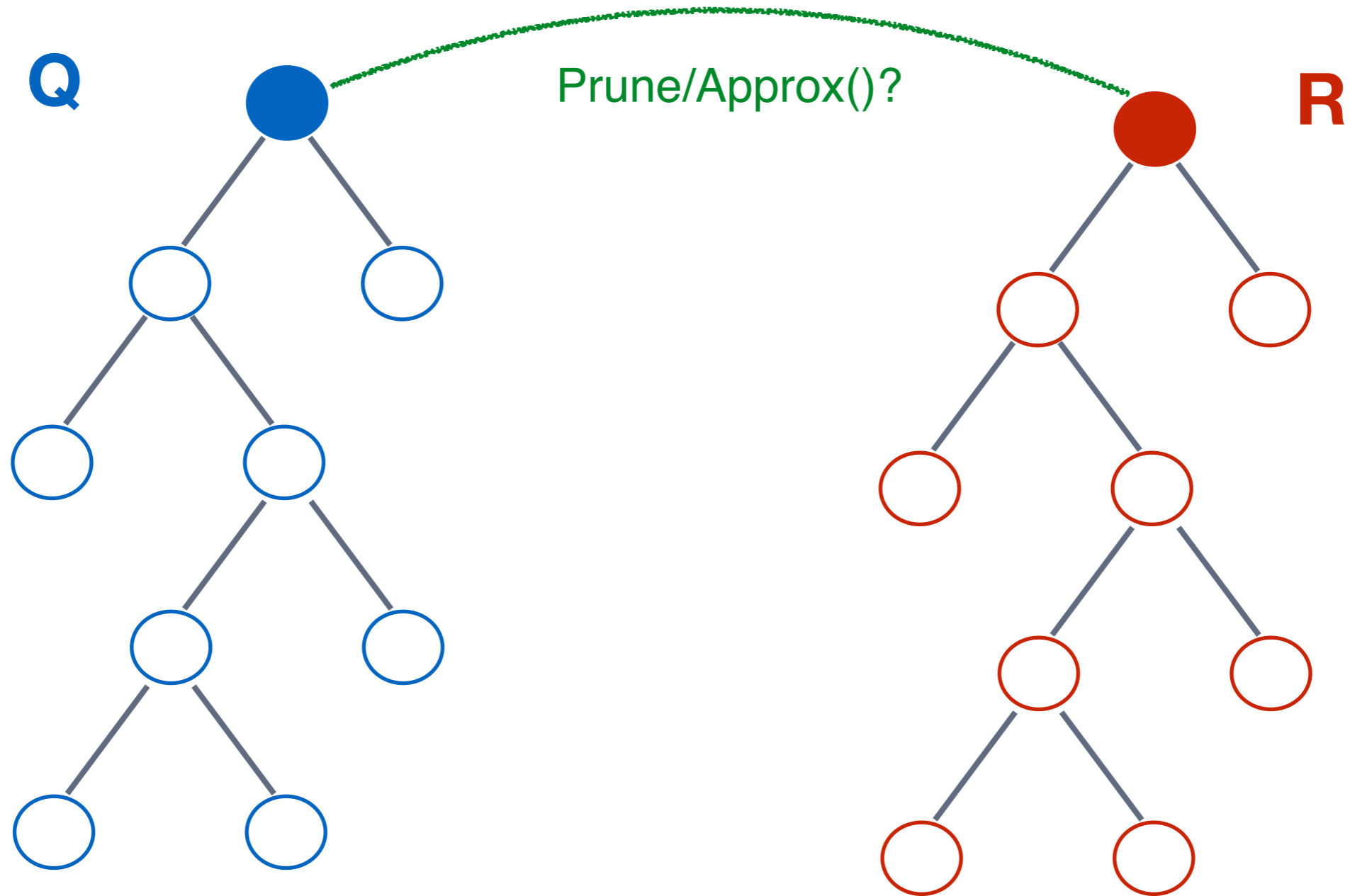
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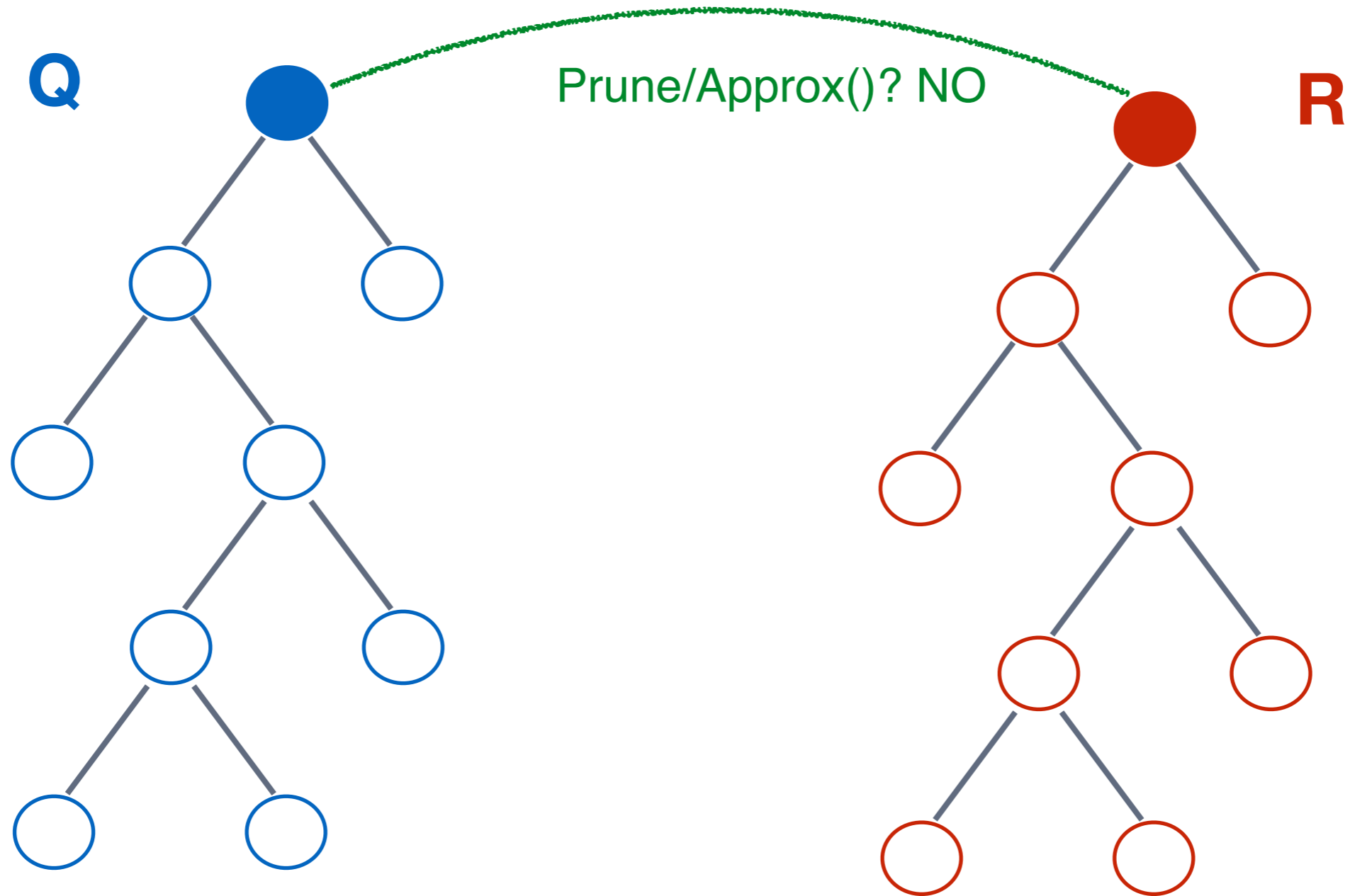
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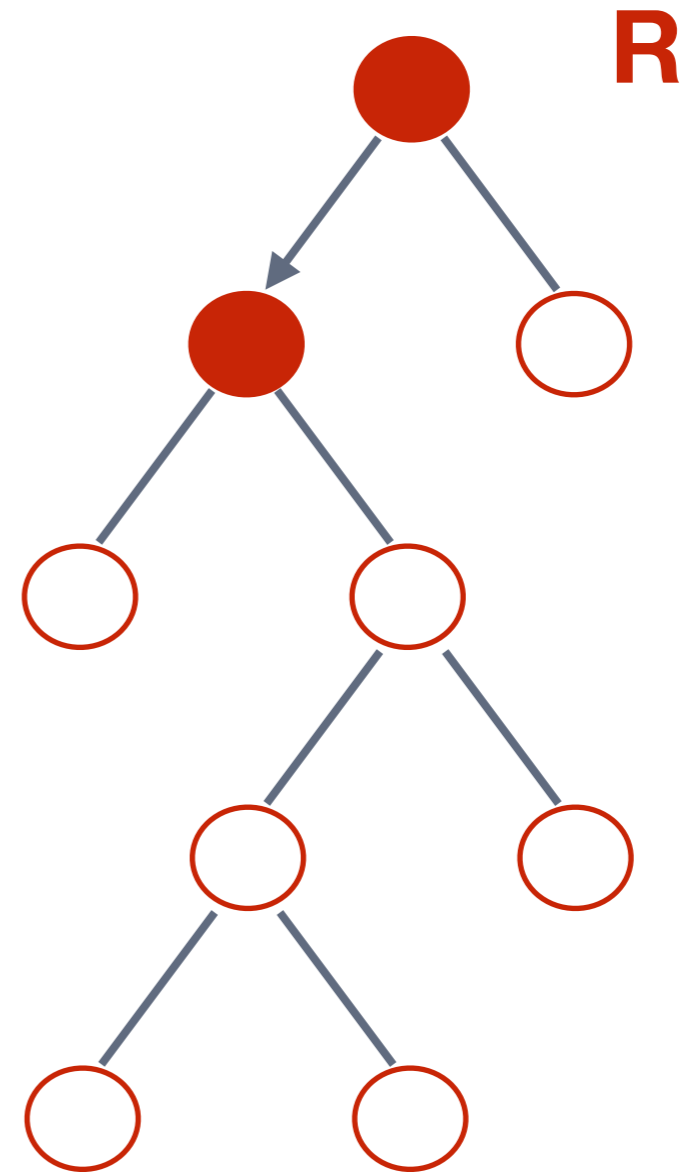
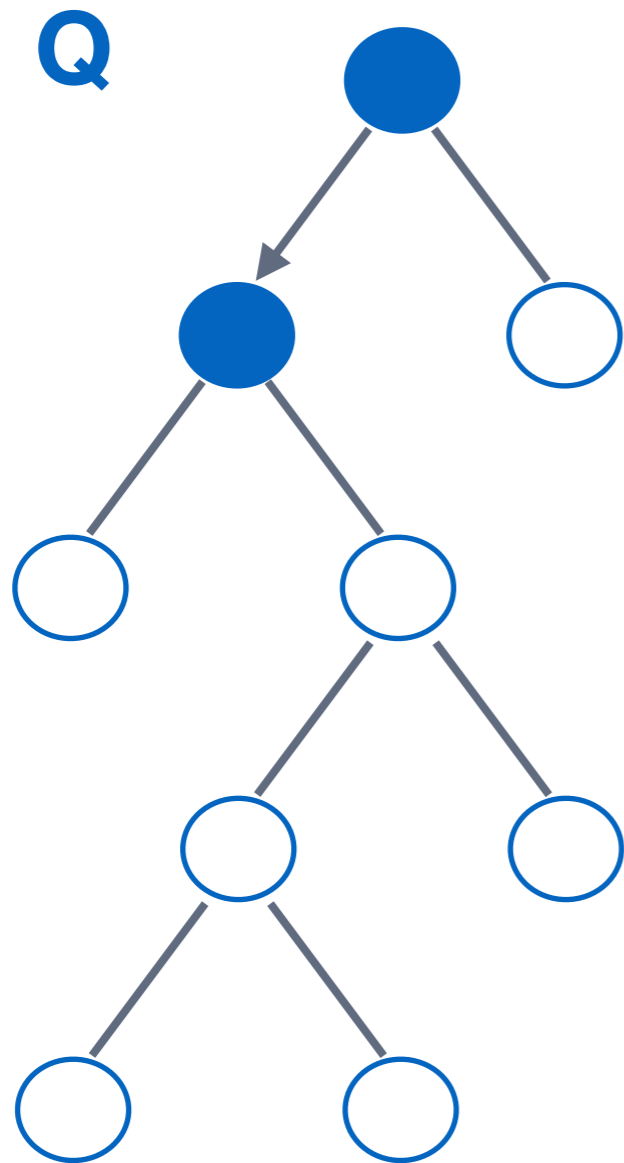
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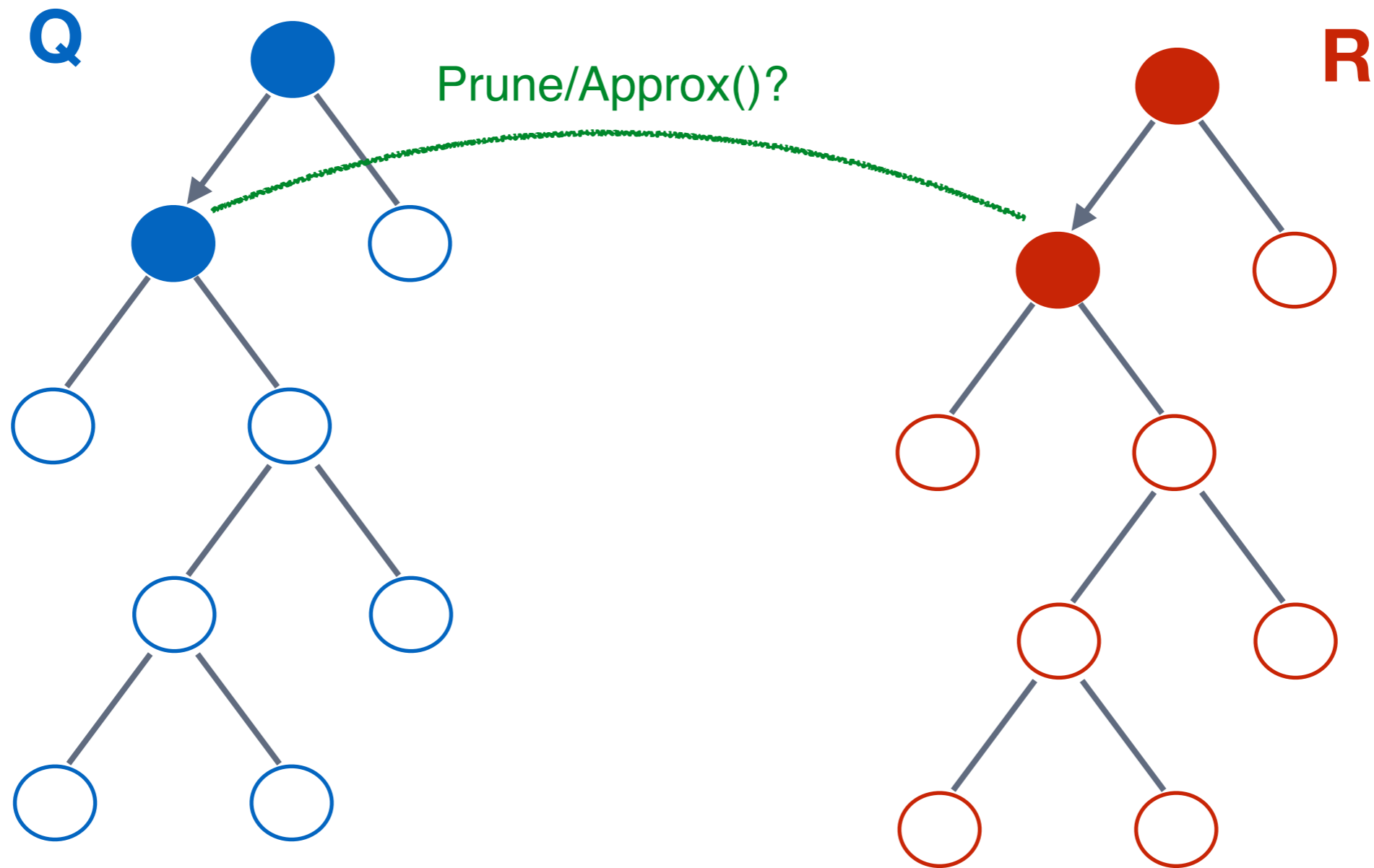
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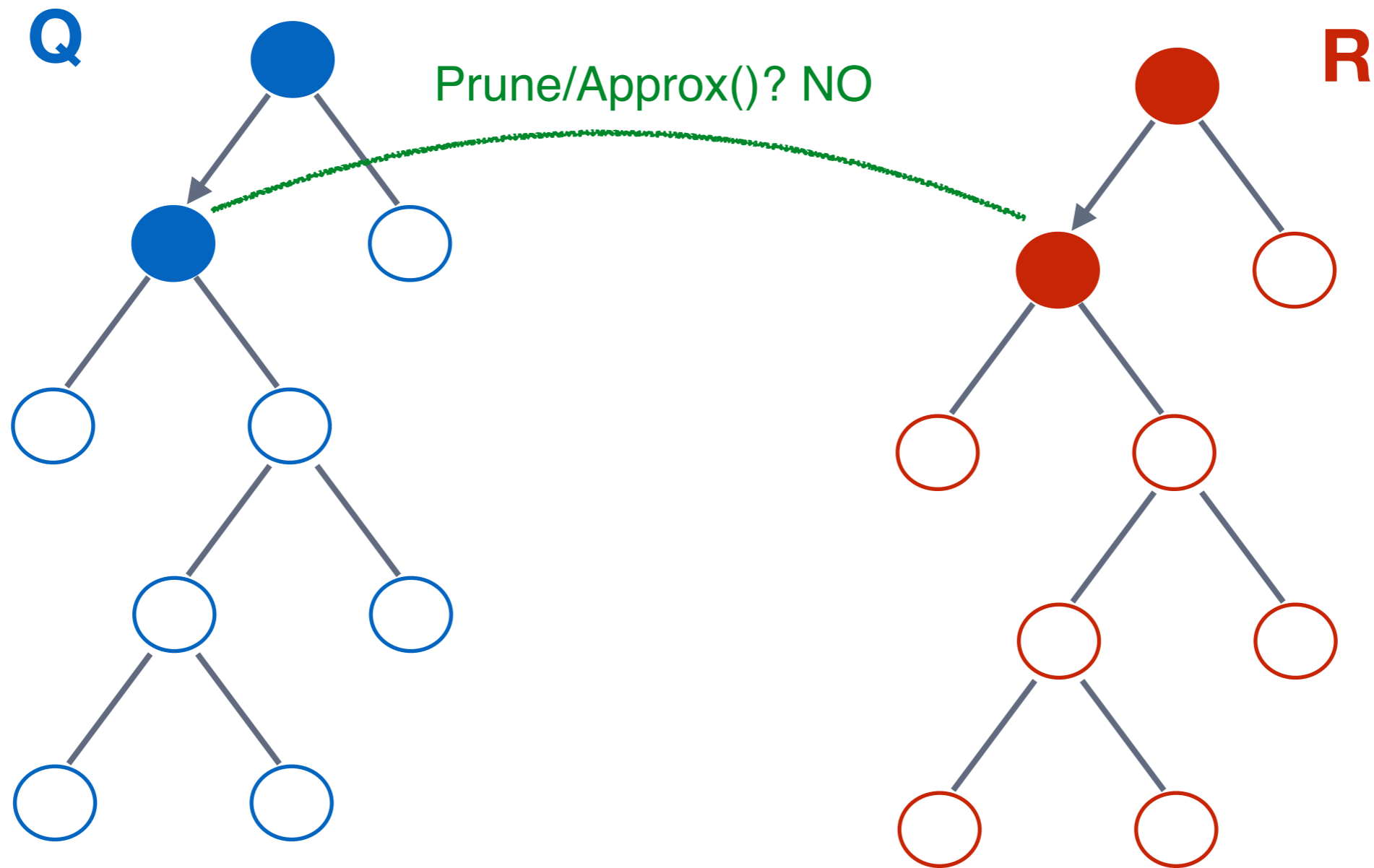
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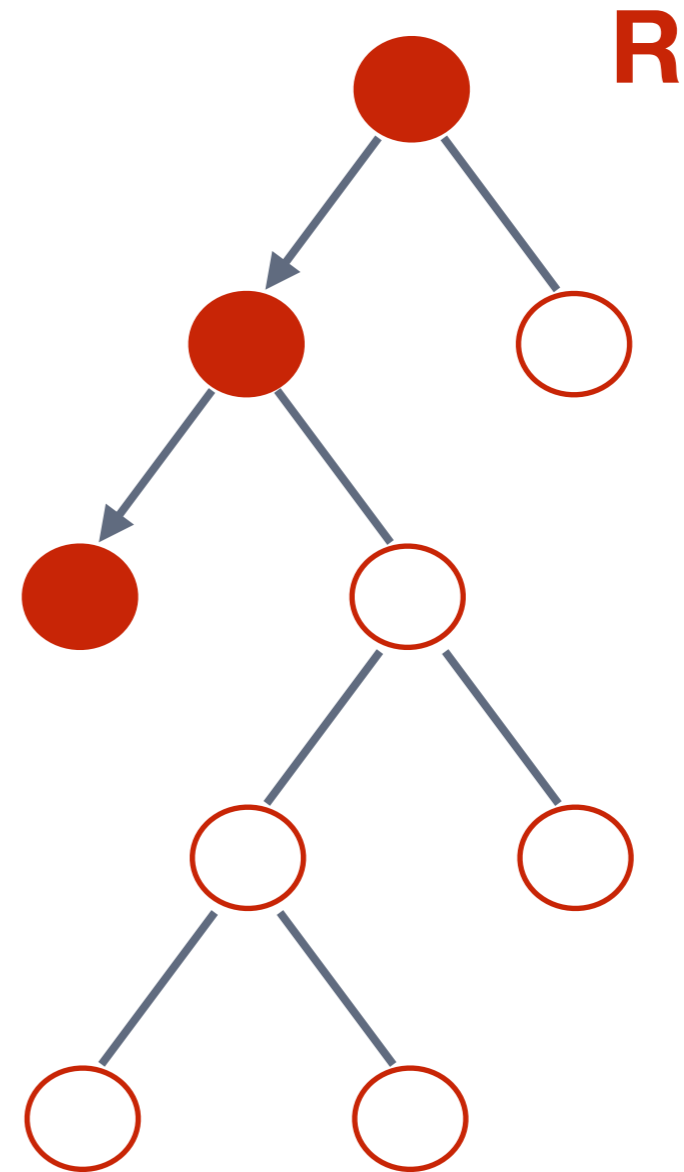
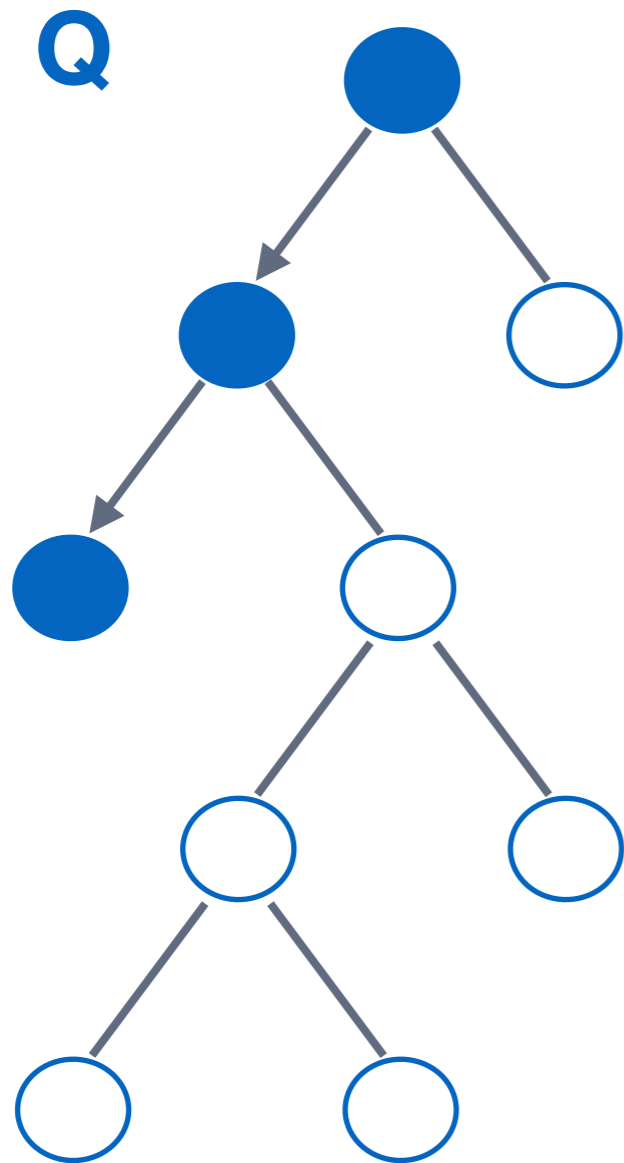
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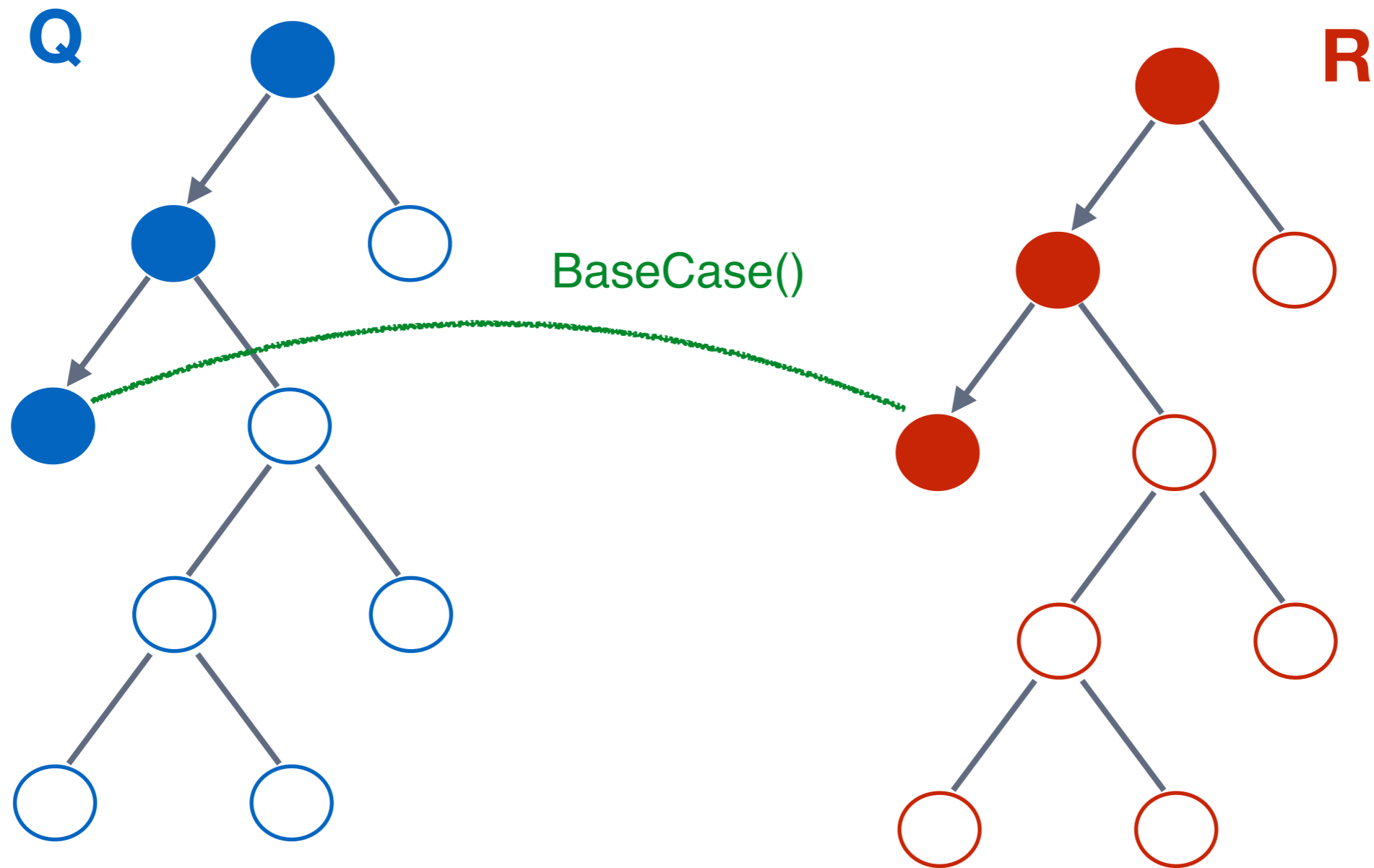


# Tree Traversal

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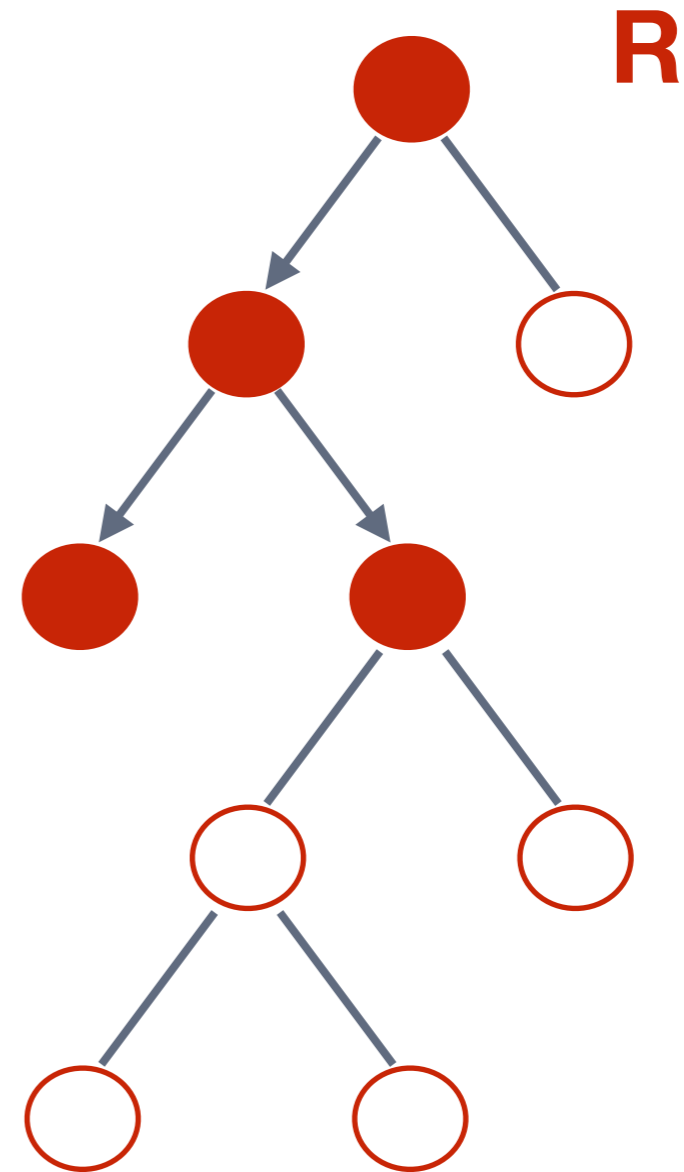
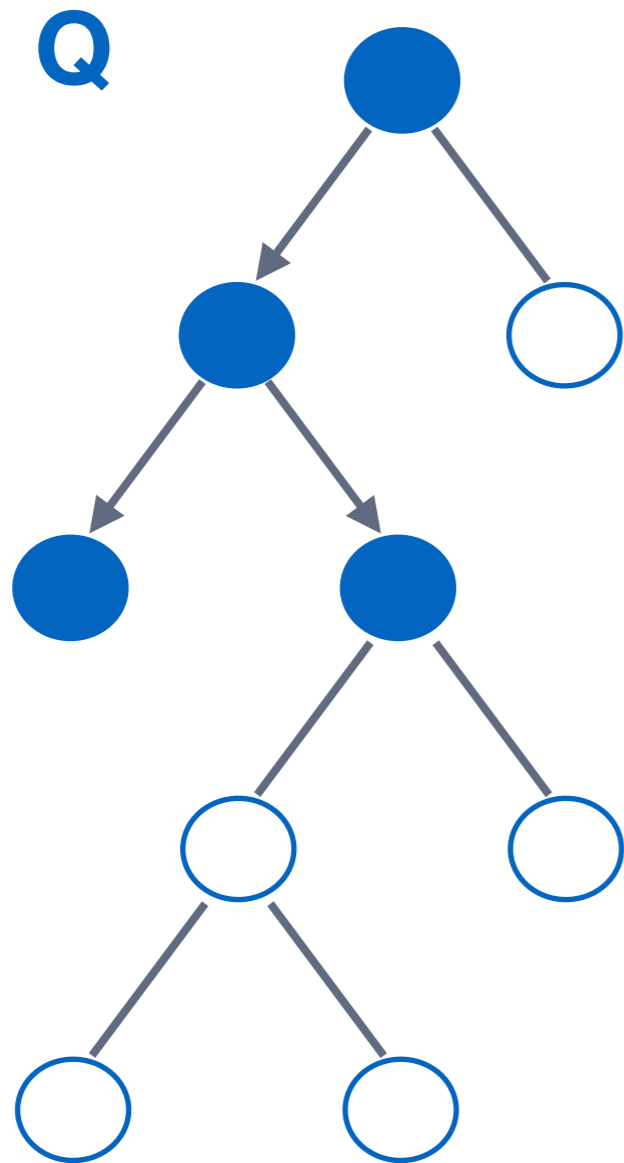
# Tree Traversal



Direct  $Q_L \otimes R_L \rightarrow O(q^2)$

# Tree Traversal

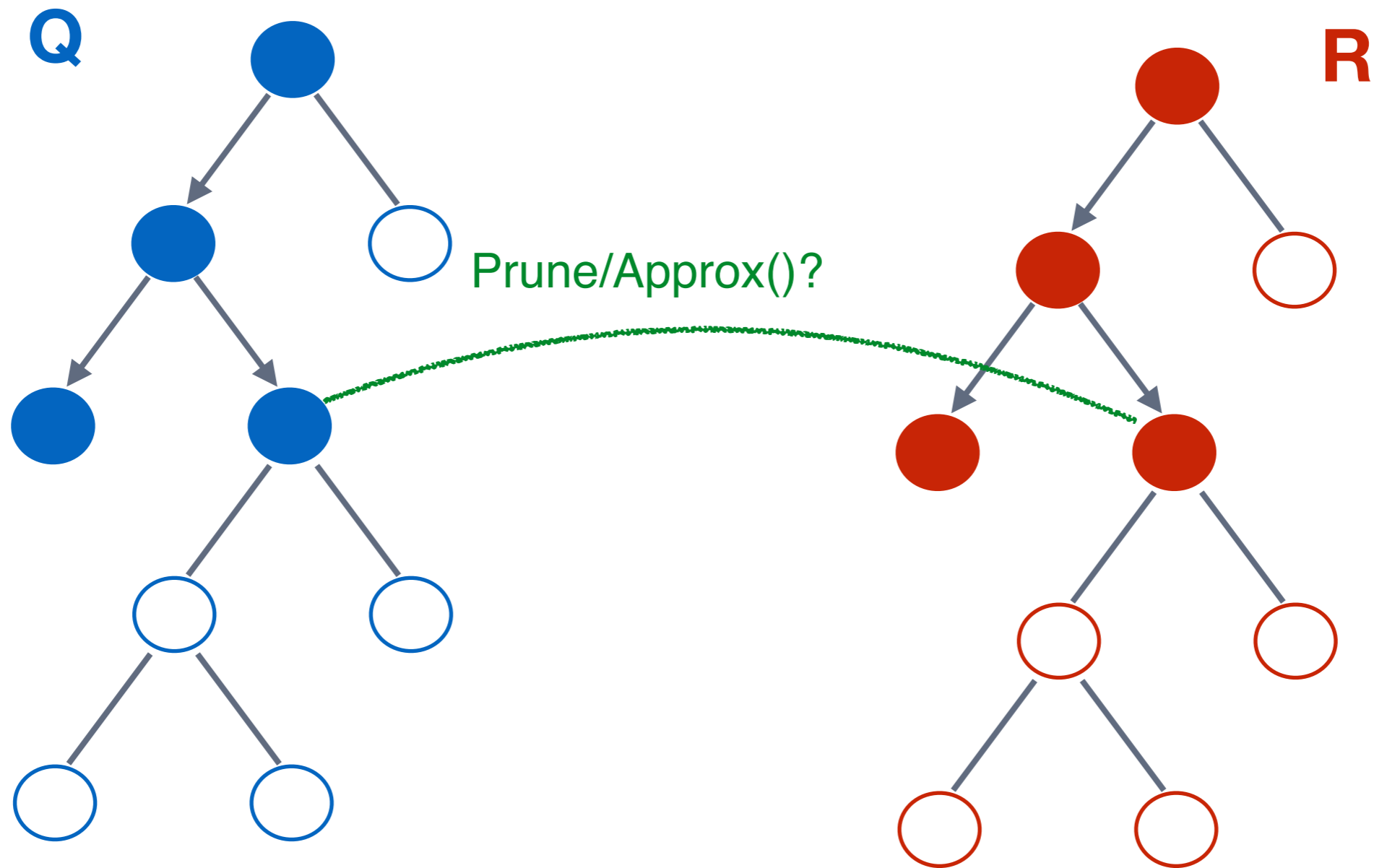
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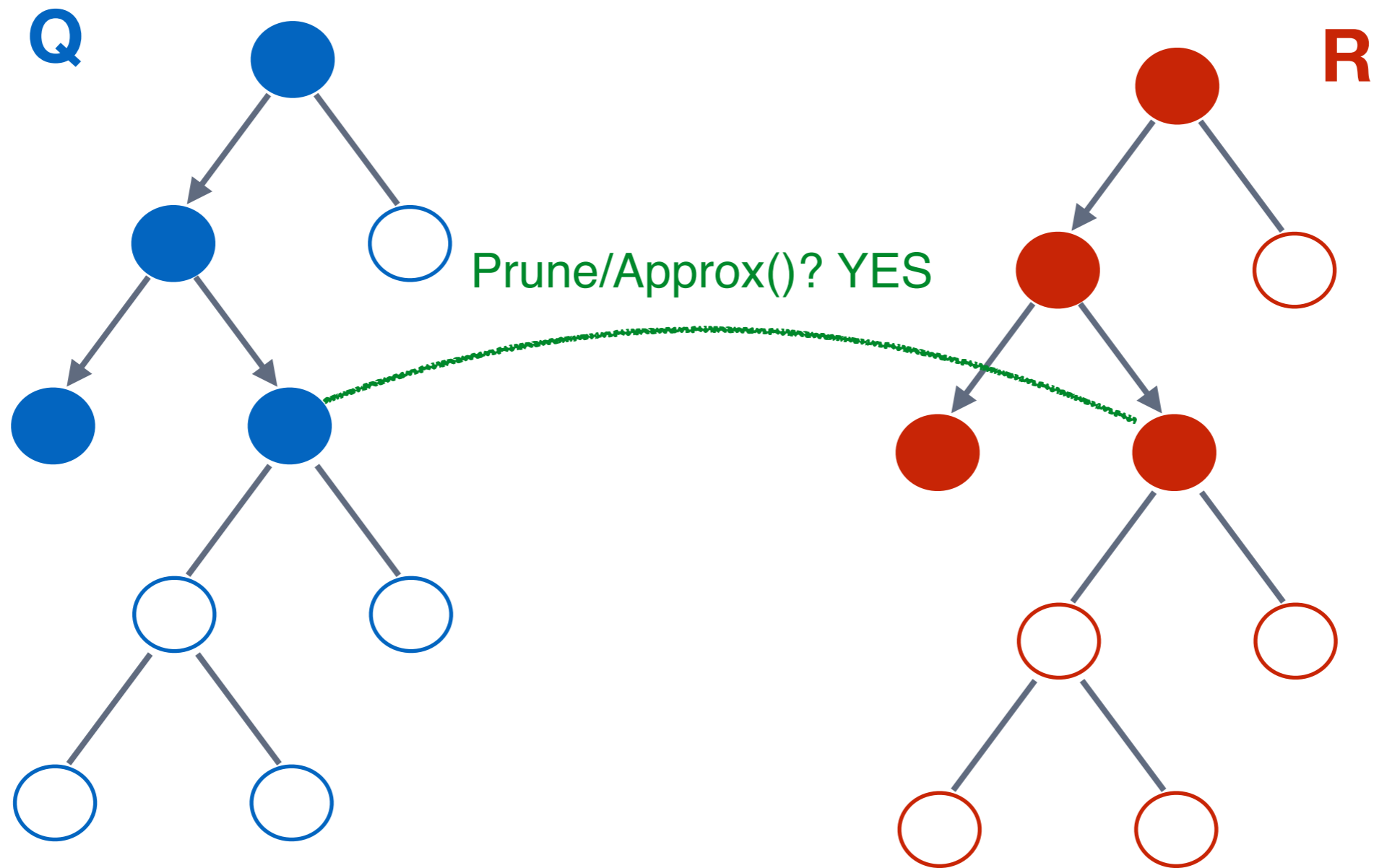
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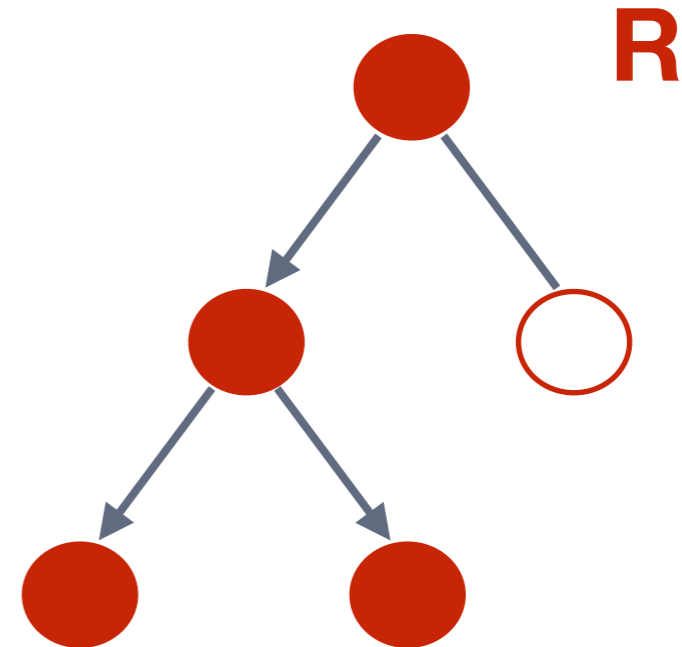
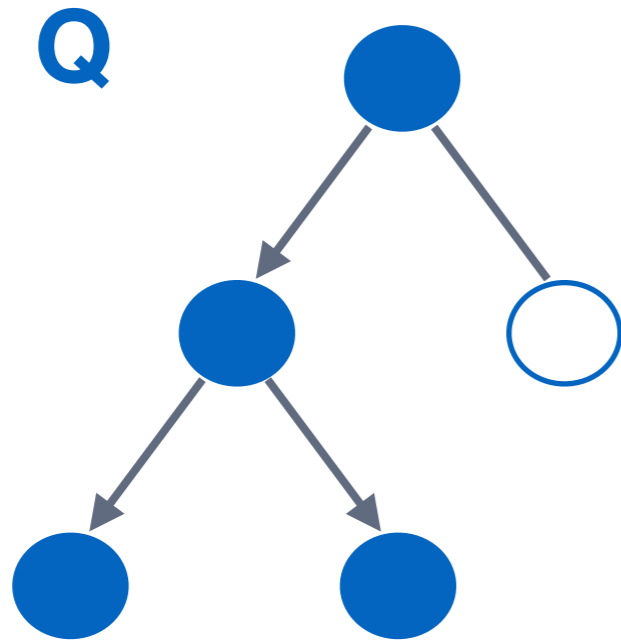
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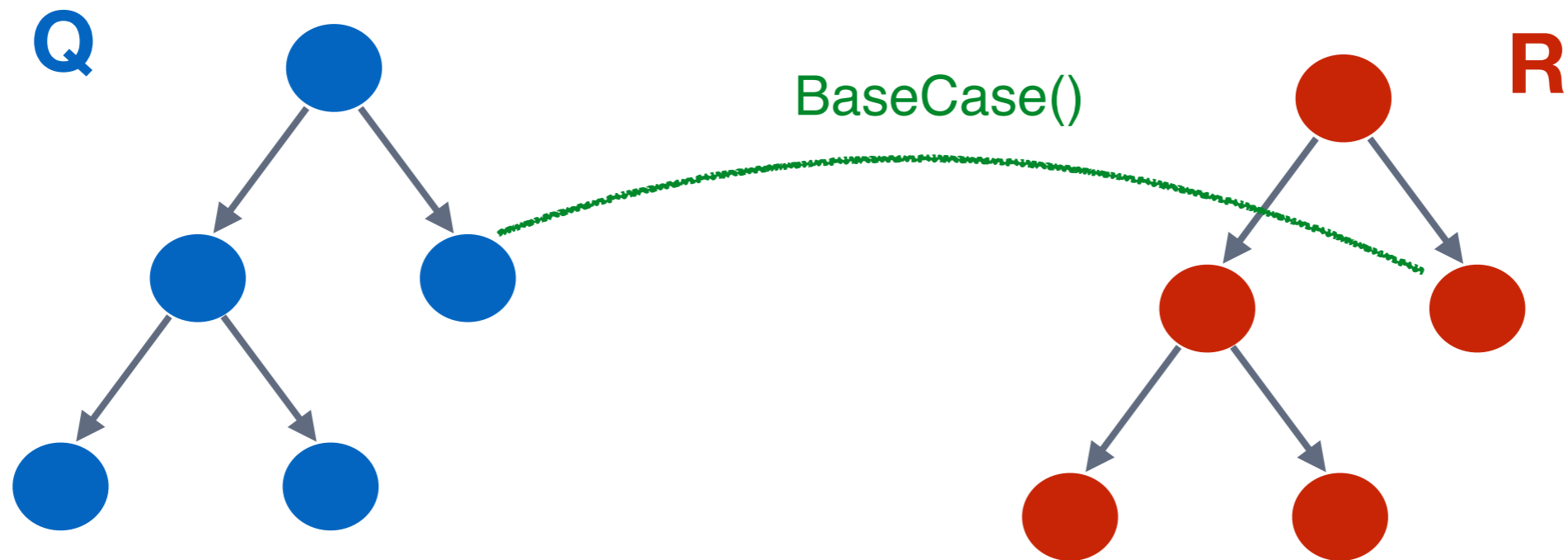
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If Prune/Approx() is true, discard the entire subtree for pruning problems

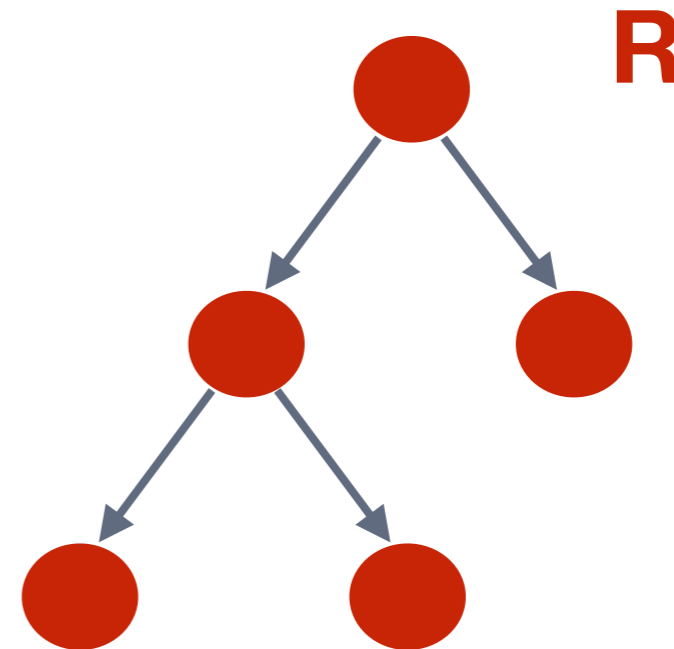
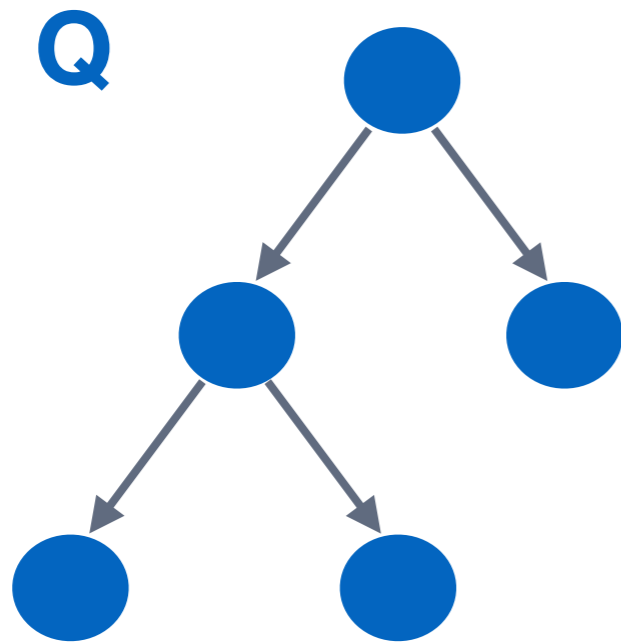
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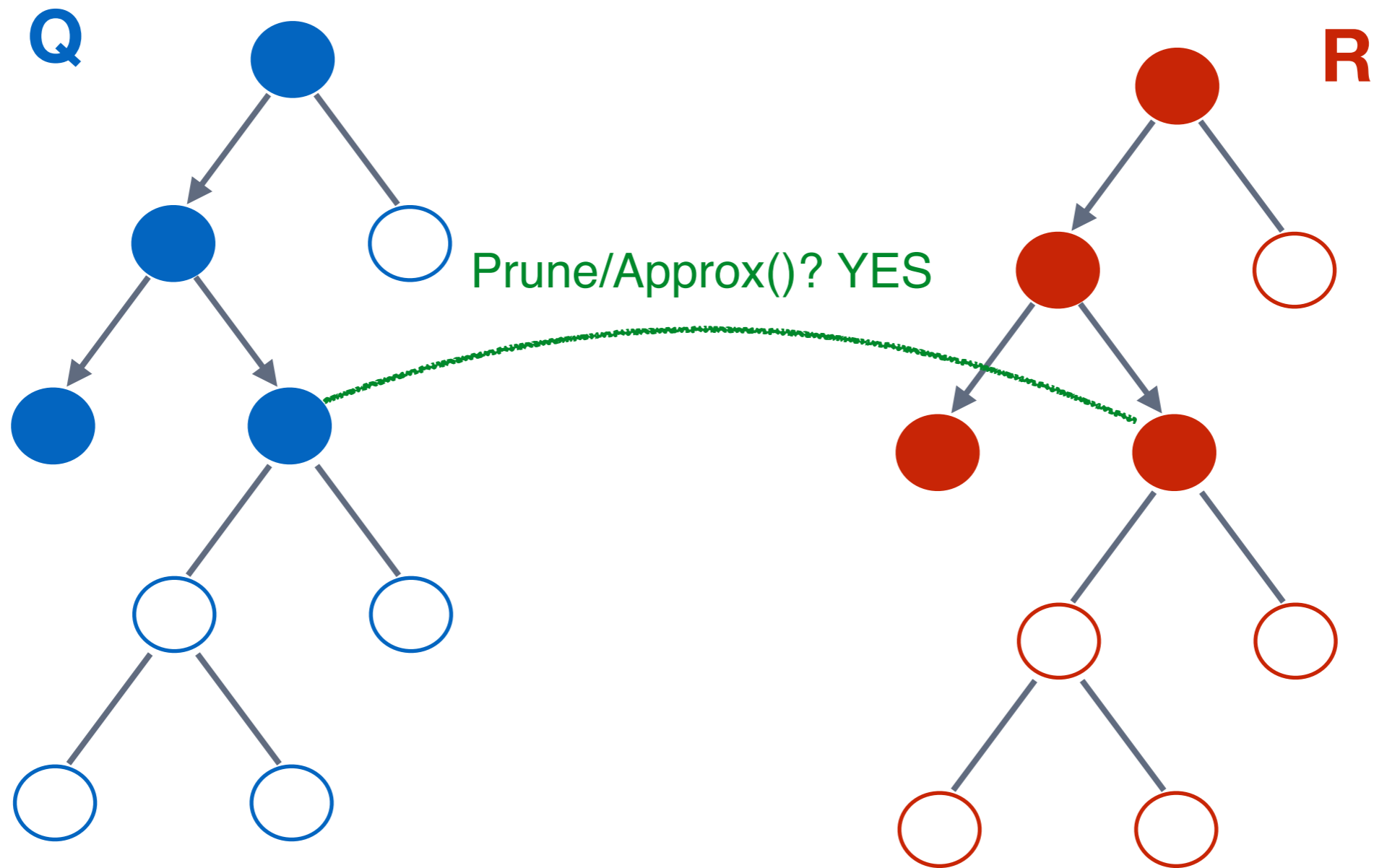
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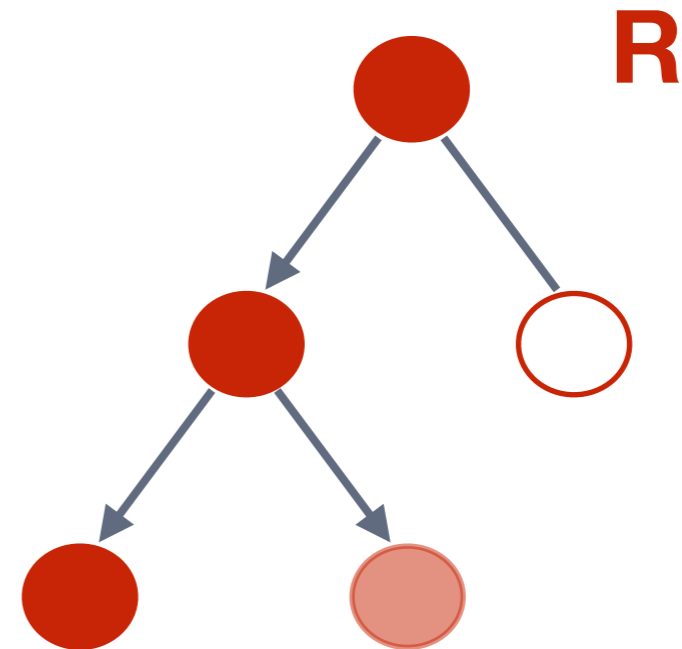
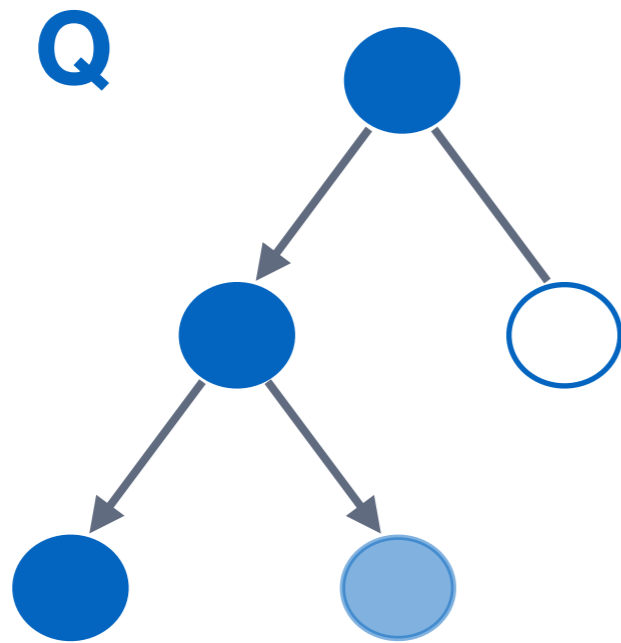
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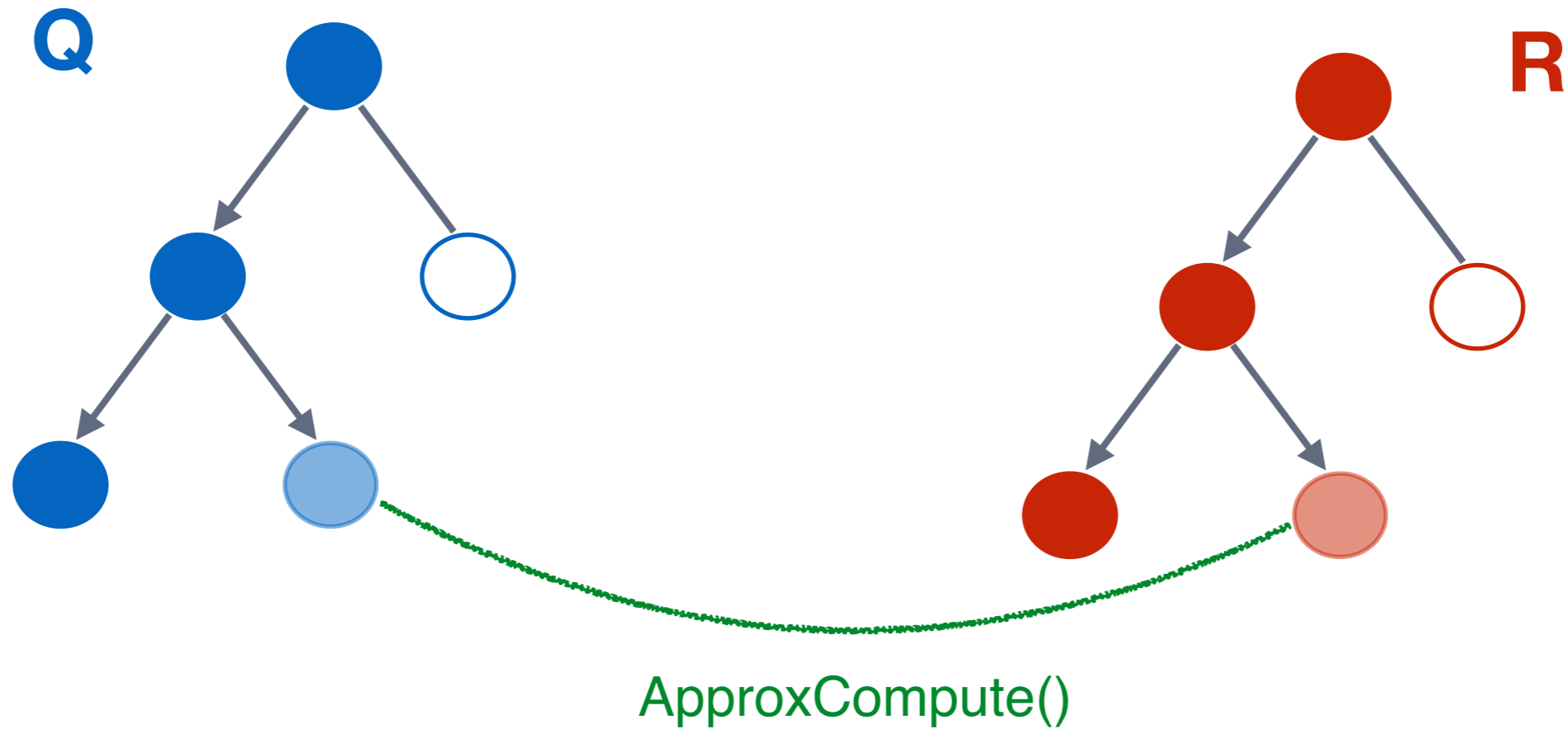
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If Prune/Approx() is true, replace the subtree with the centroid for approximation problems

# Tree Traversal

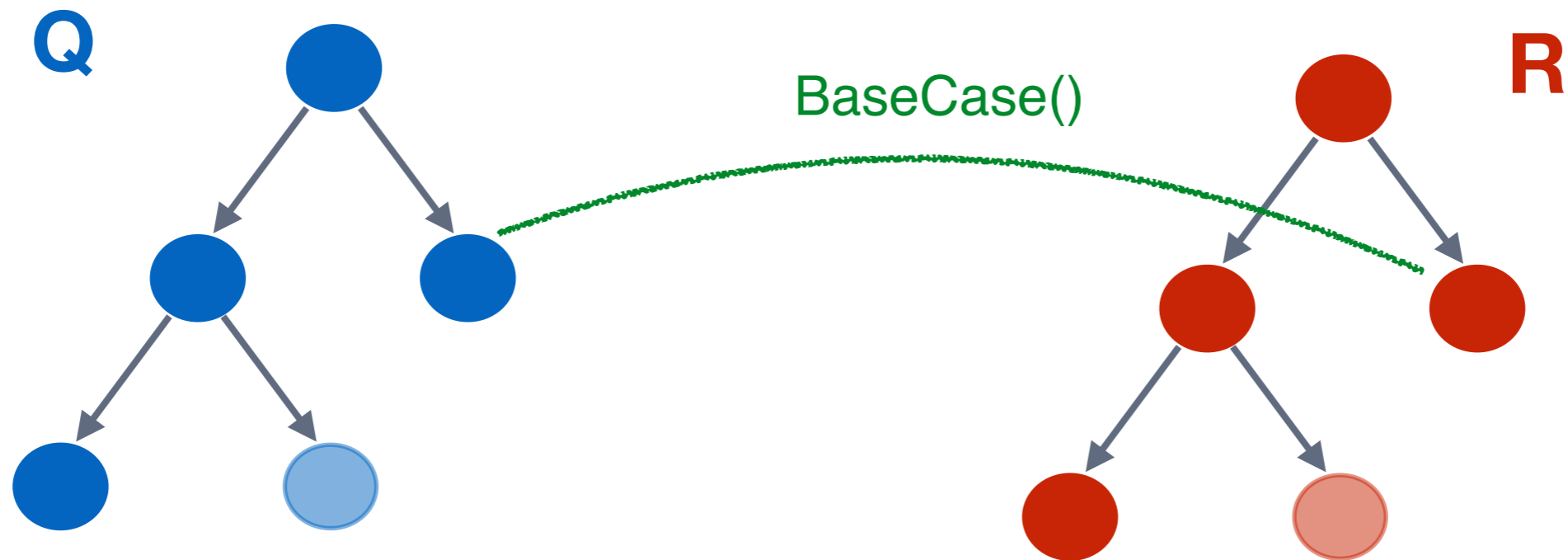
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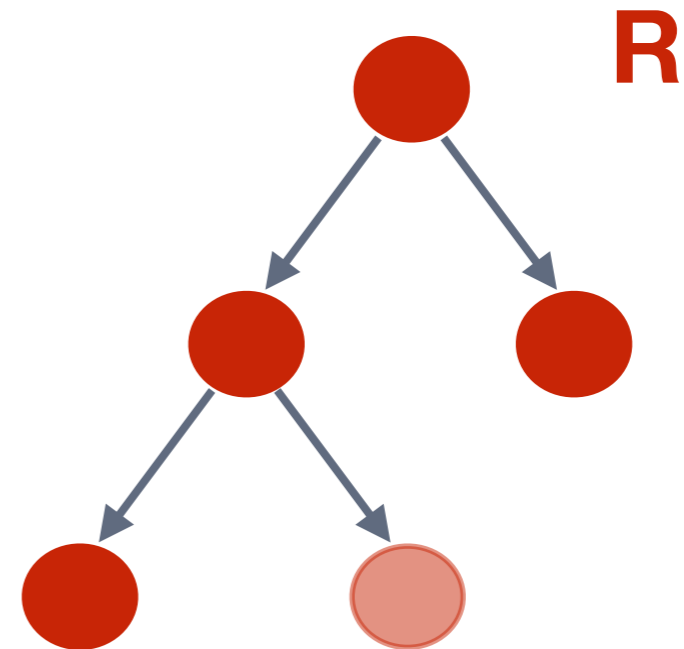
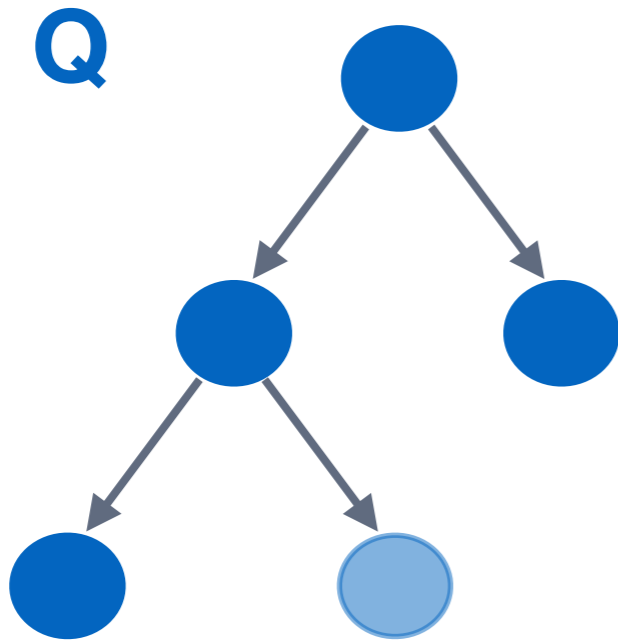
# Tree Traversal

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# Tree Traversal

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# Prune/Approximate Condition Generator

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- Prune e.g., *Hausdorff Distance*  $\max_q, \min_r \|x_q - x_r\|$

# Hausdorff Distance

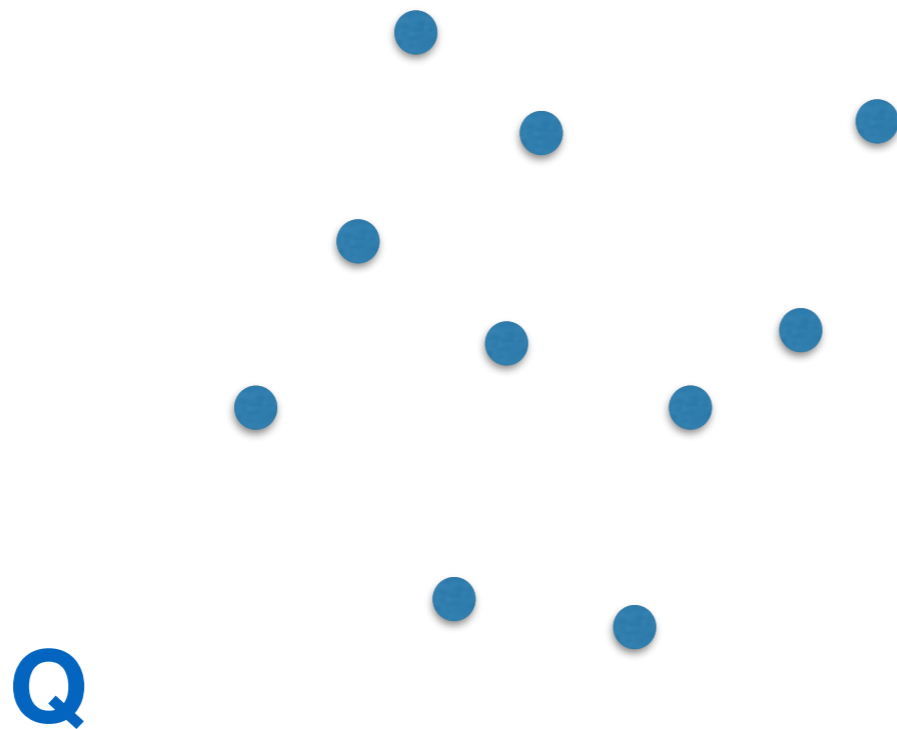
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$$\max_q, \min_r \|x_q - x_r\|$$

# Hausdorff Distance

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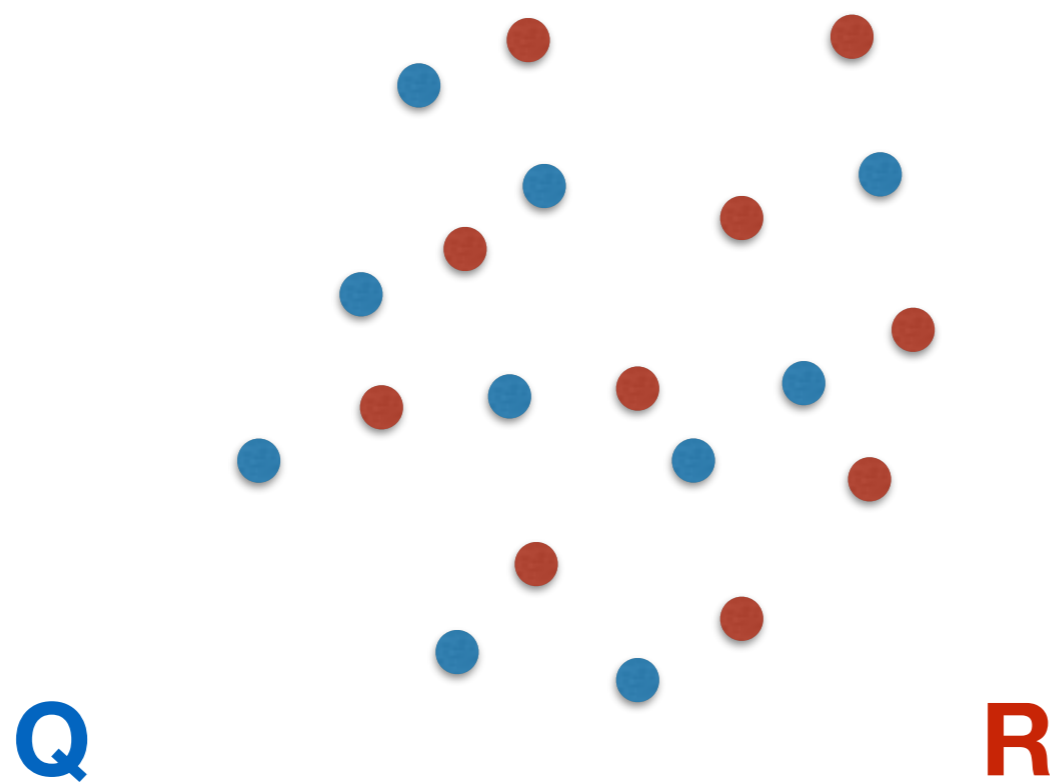
$$\max_q, \min_r \|x_q - x_r\|$$



# Hausdorff Distance

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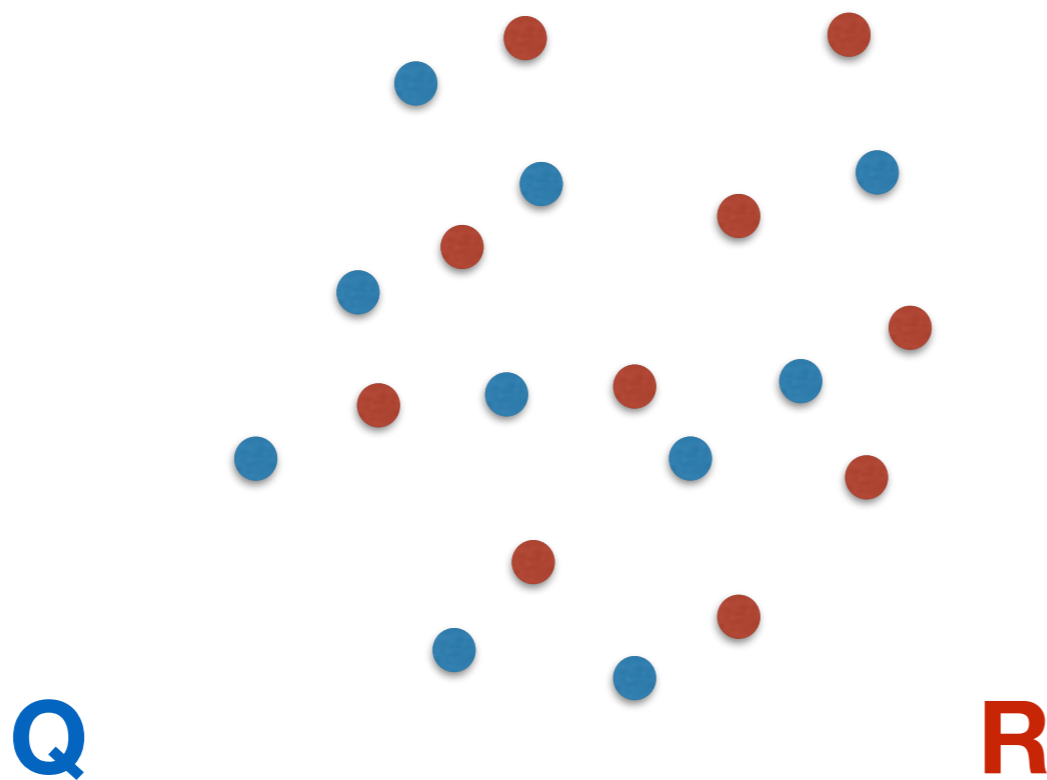
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# Hausdorff Distance

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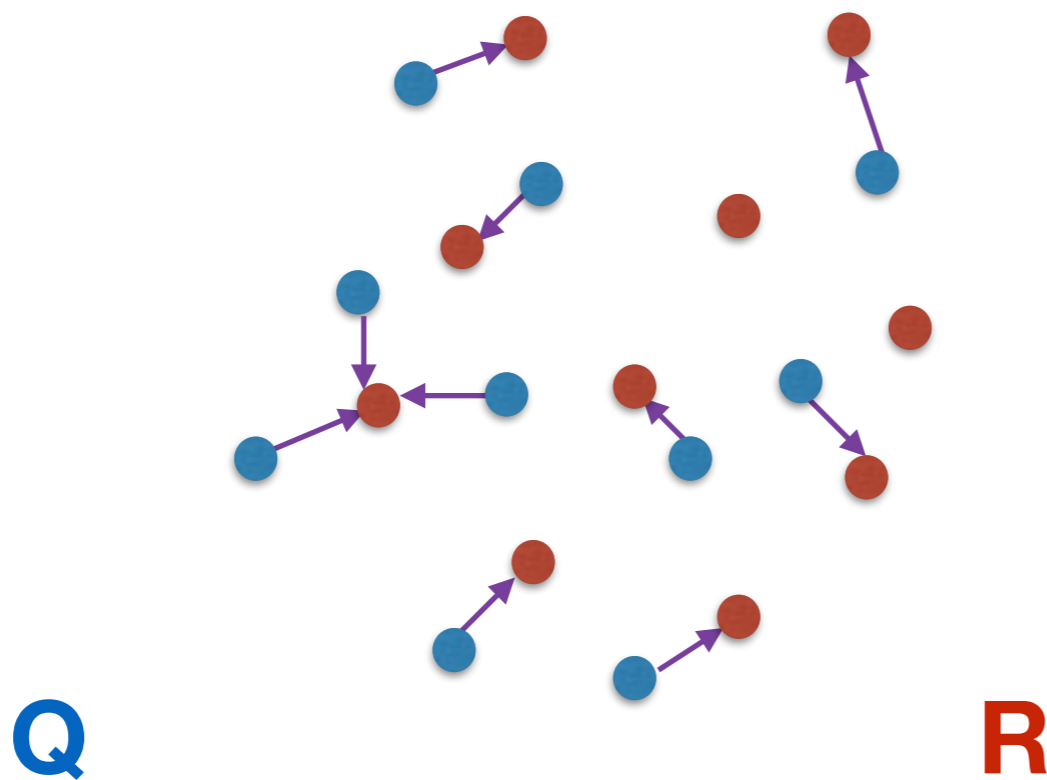
$$\max_q, \min_r \|x_q - x_r\|$$



# Hausdorff Distance

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$$\max_q, \min_r \|x_q - x_r\|$$

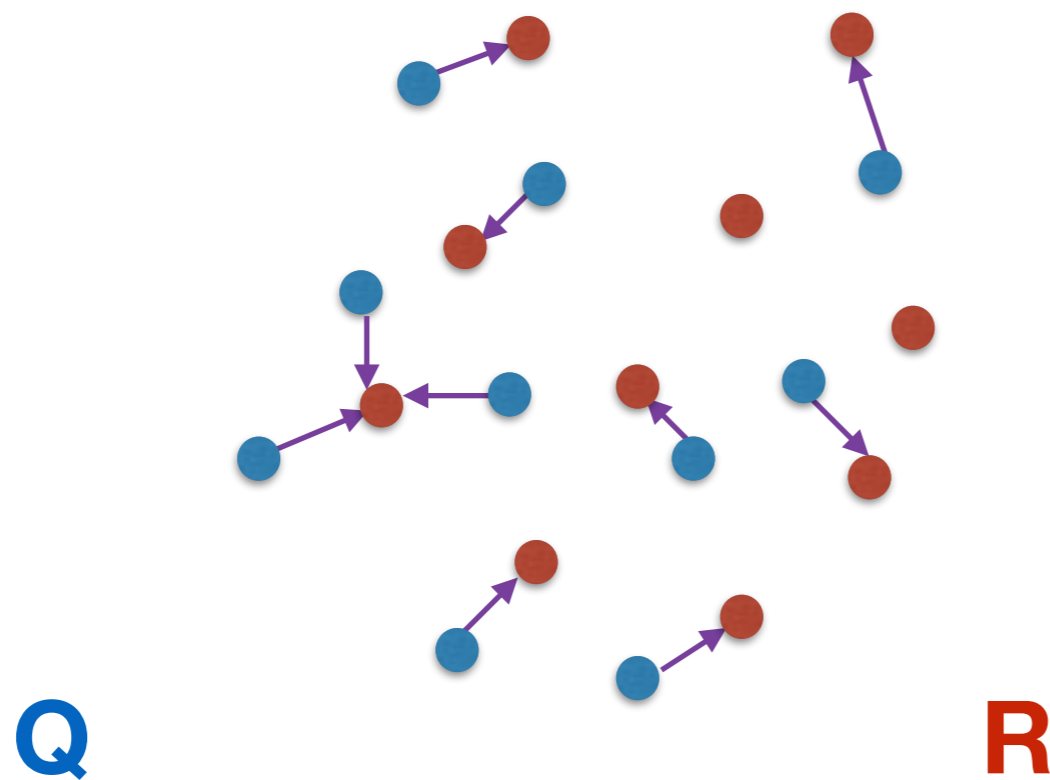




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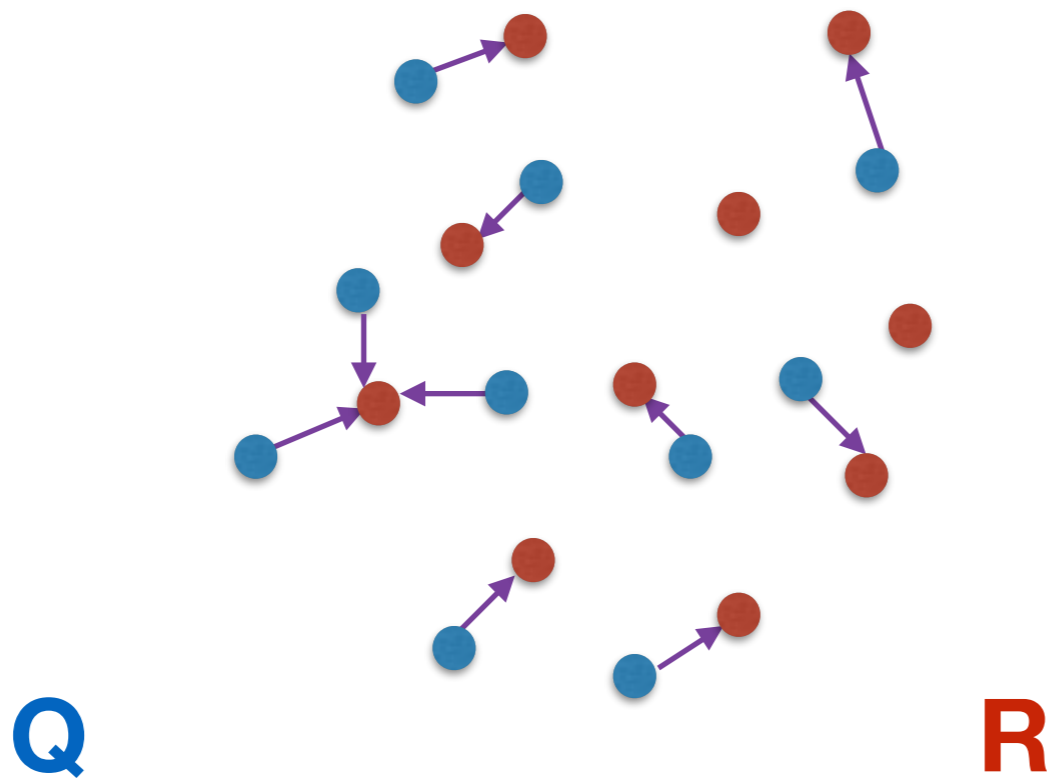
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# Hausdorff Distance

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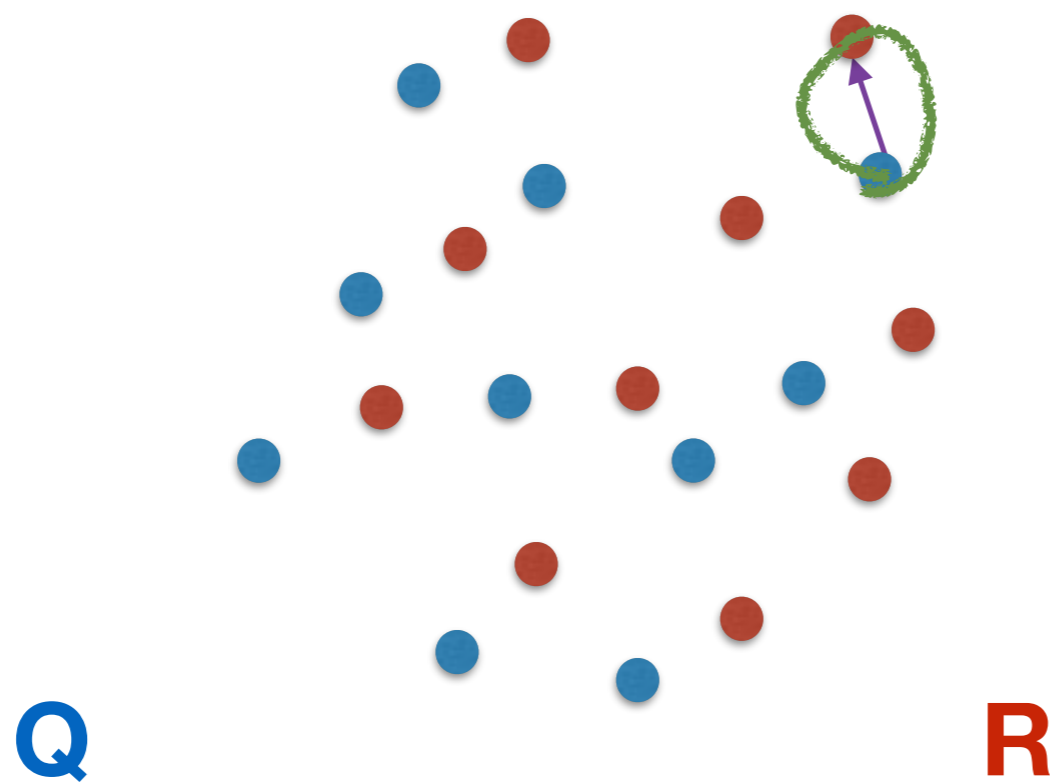
$$\max_q \min_r \|x_q - x_r\|$$



# Hausdorff Distance

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$$\max_q \min_r \|x_q - x_r\|$$



# Prune/Approximate Condition Generator

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- Prune e.g., *Hausdorff Distance*  $\max_q, \min_r \|x_q - x_r\|$
- Approximation e.g., *Expectation Maximization (EM)*

E-step  $\forall q, \forall r, \frac{\pi_k \mathcal{N}(x_n | \mu_k, \Sigma_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(x_n | \mu_j, \Sigma_j)}$

M-step

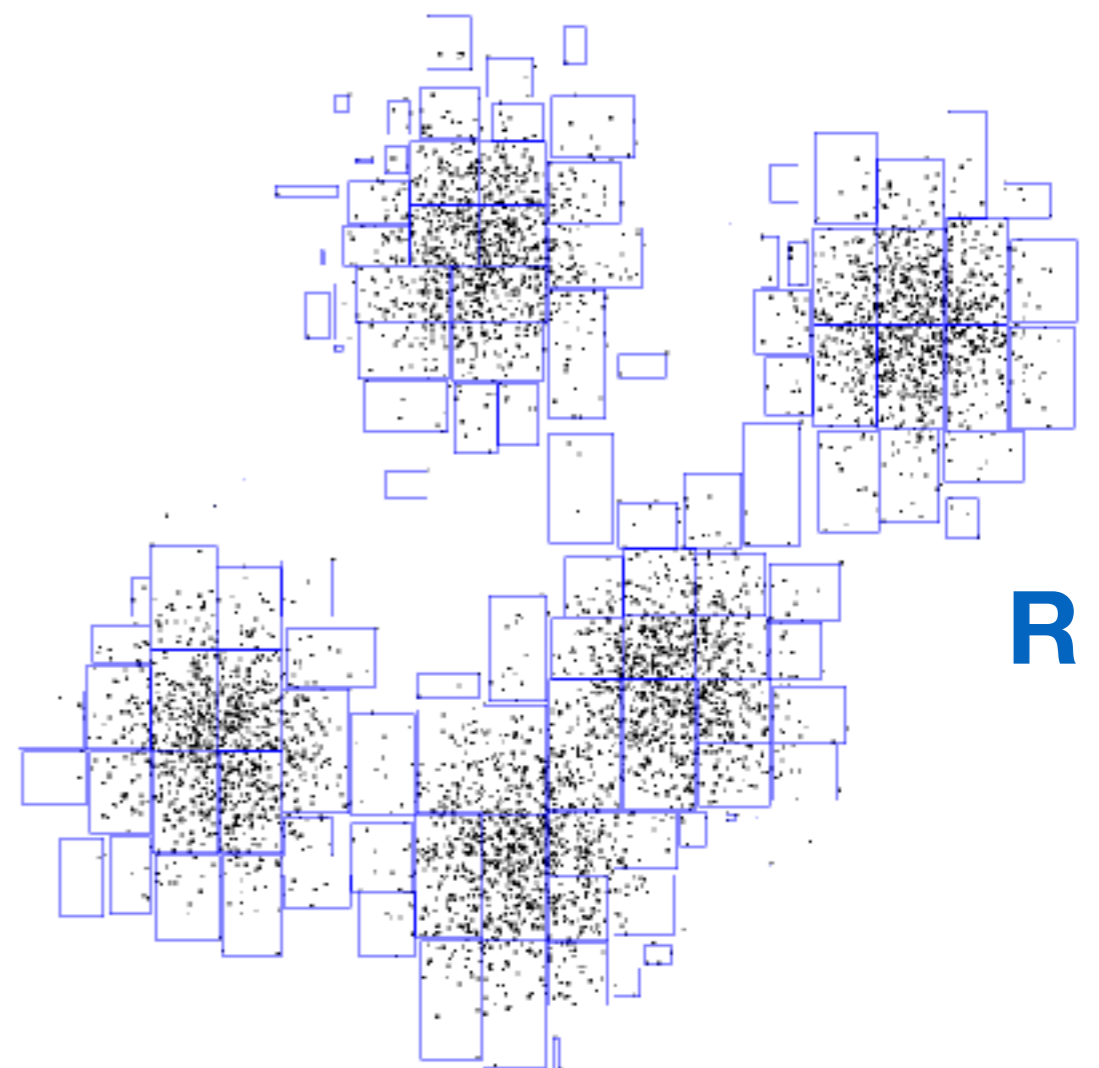
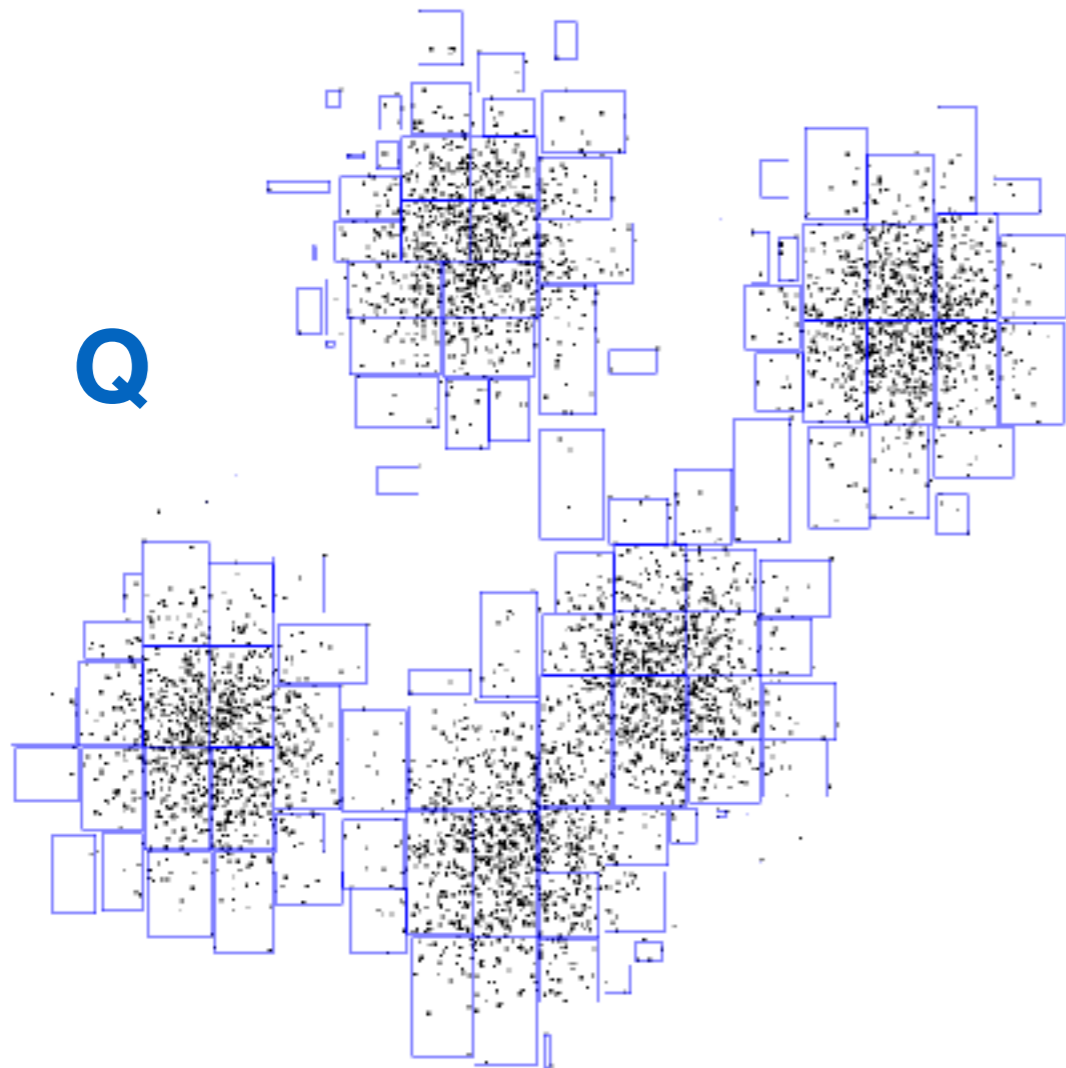
Log-likelihood  $\sum_{n=1}^N \log \sum_{k=1}^K \pi_k \mathcal{N}(x_n | \mu_k, \Sigma_k)$

# Approximate Condition for EM

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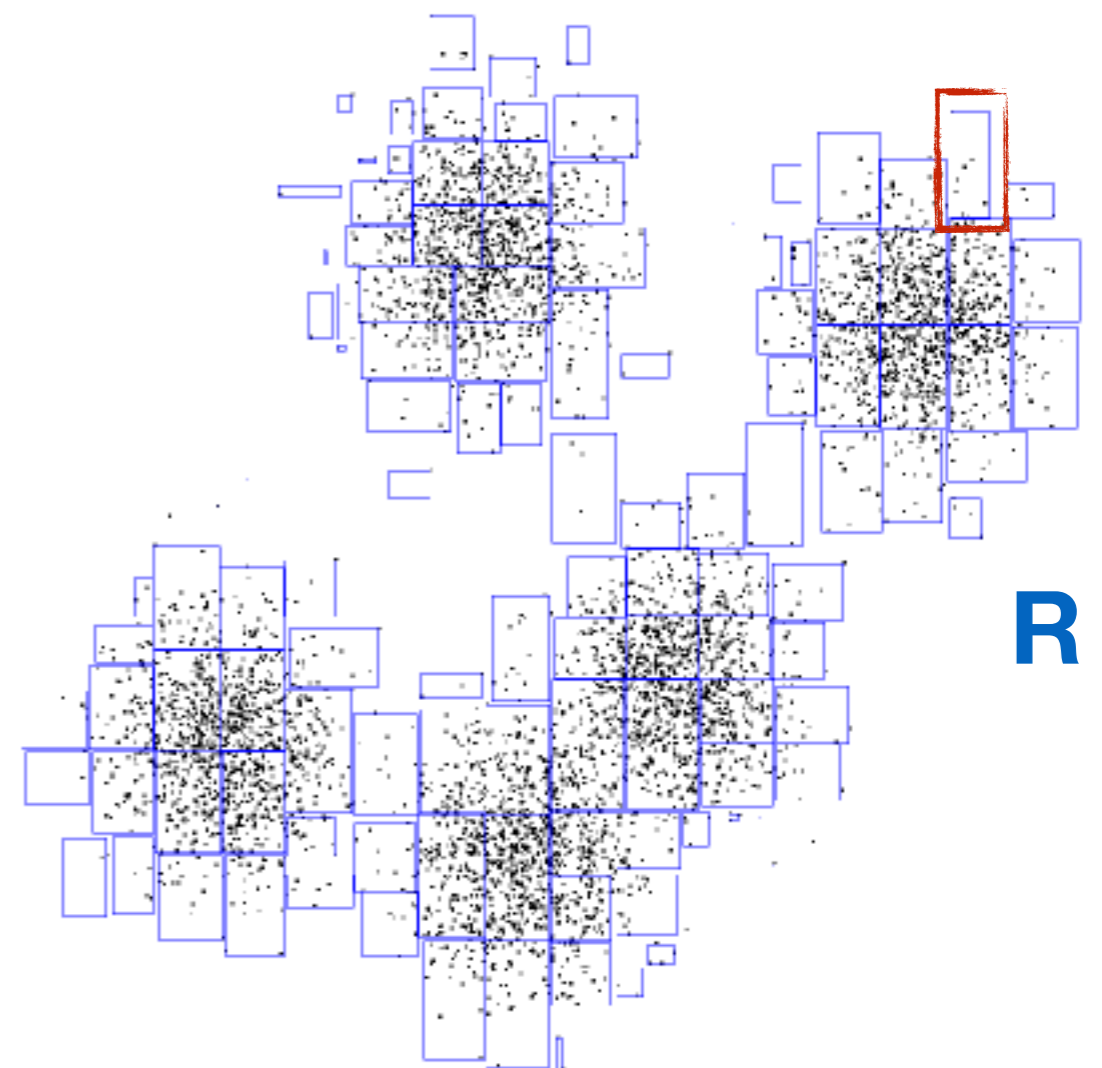
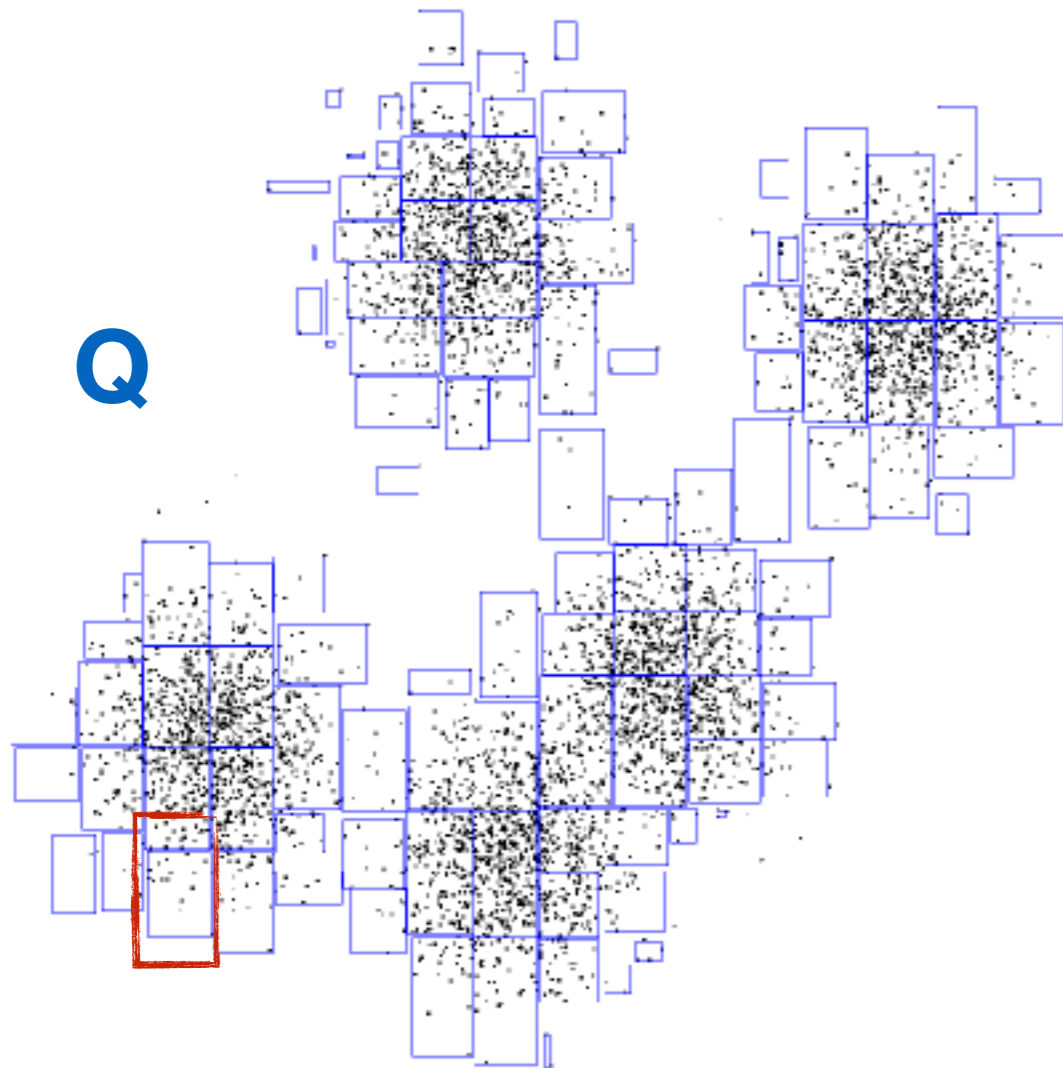
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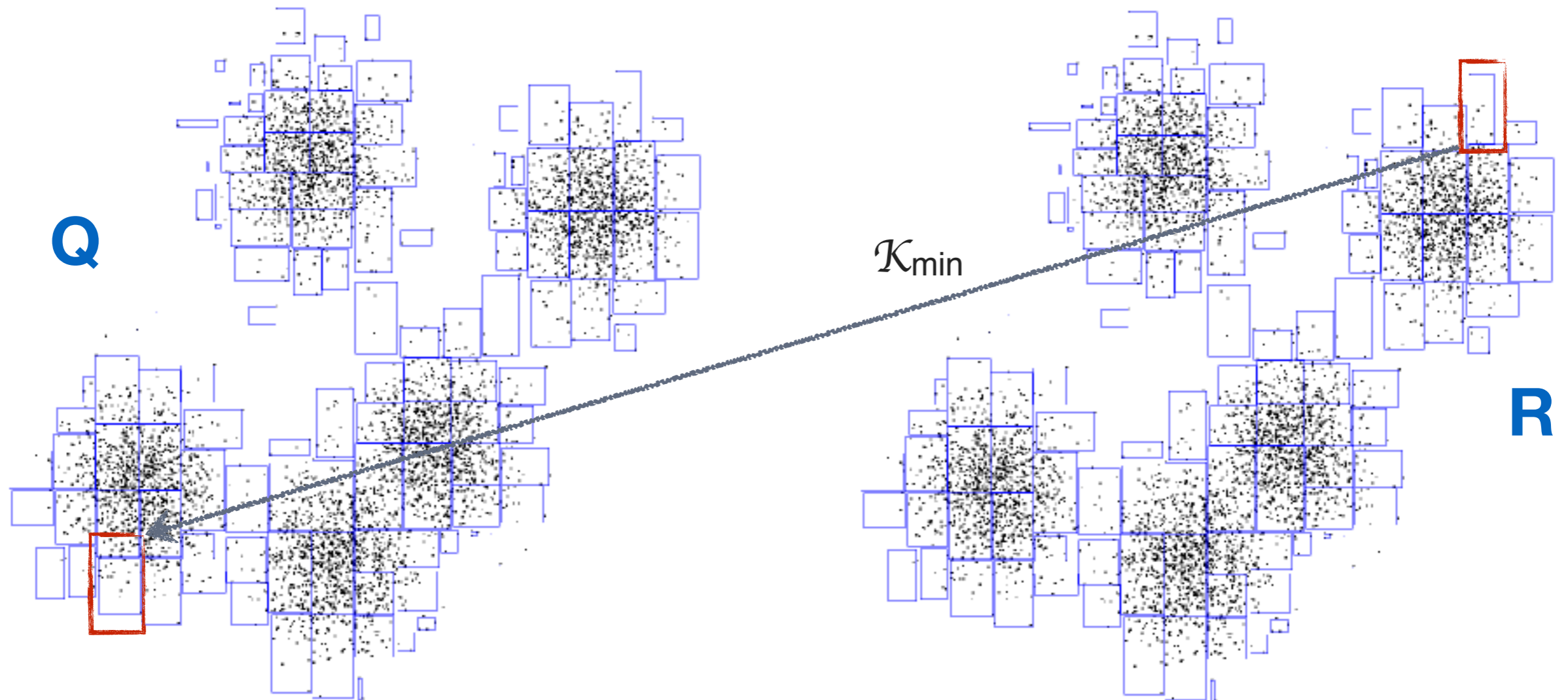
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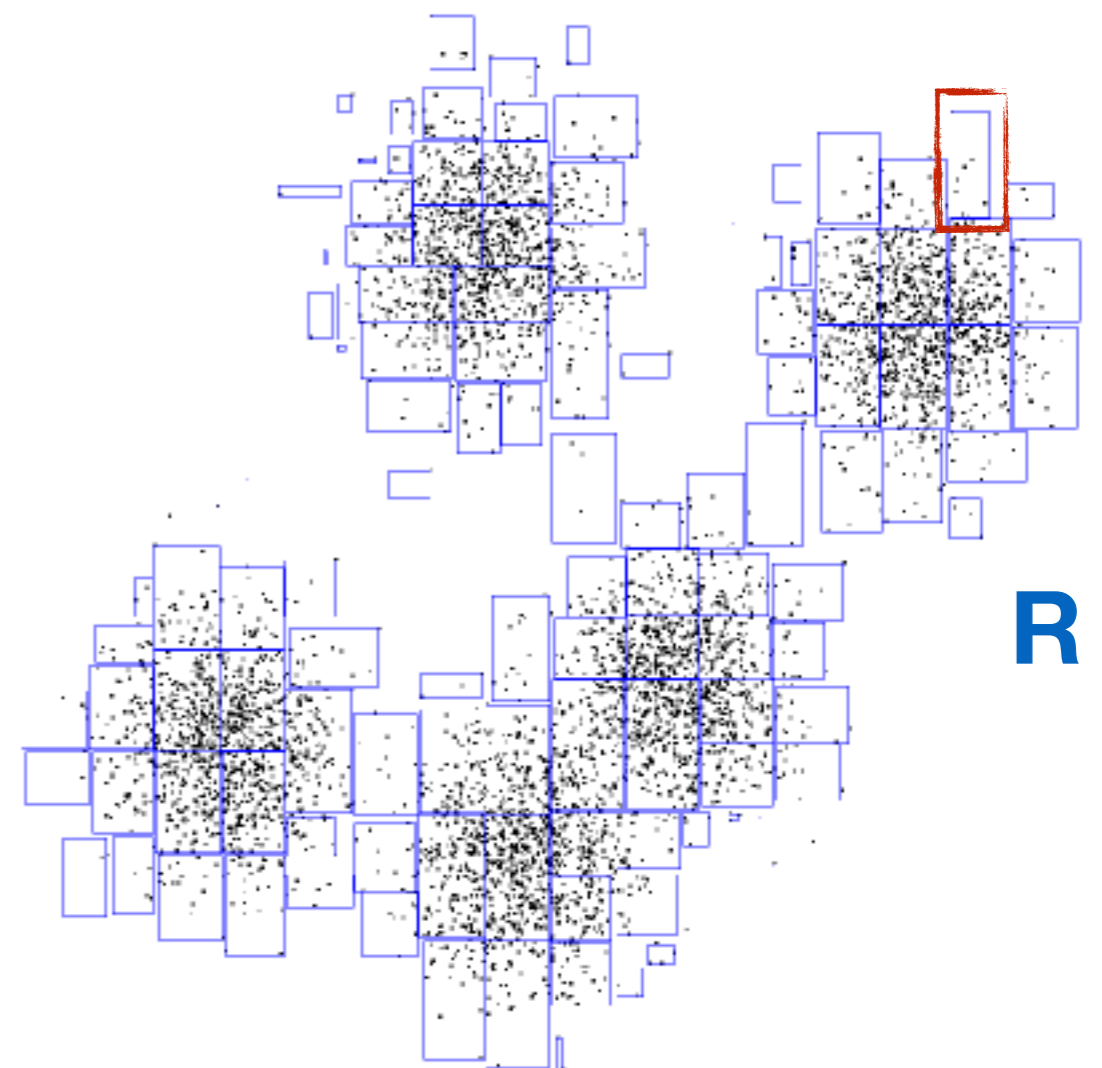
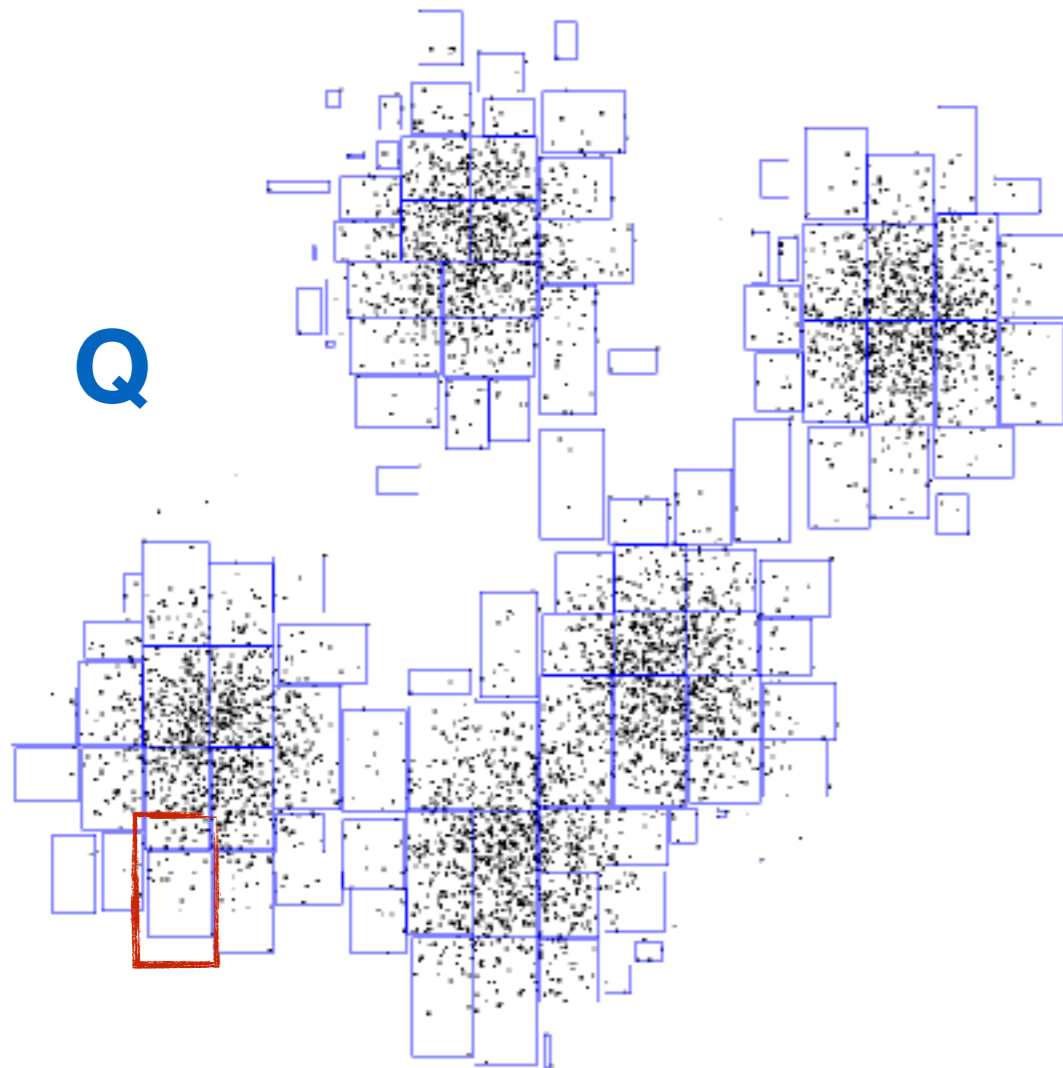
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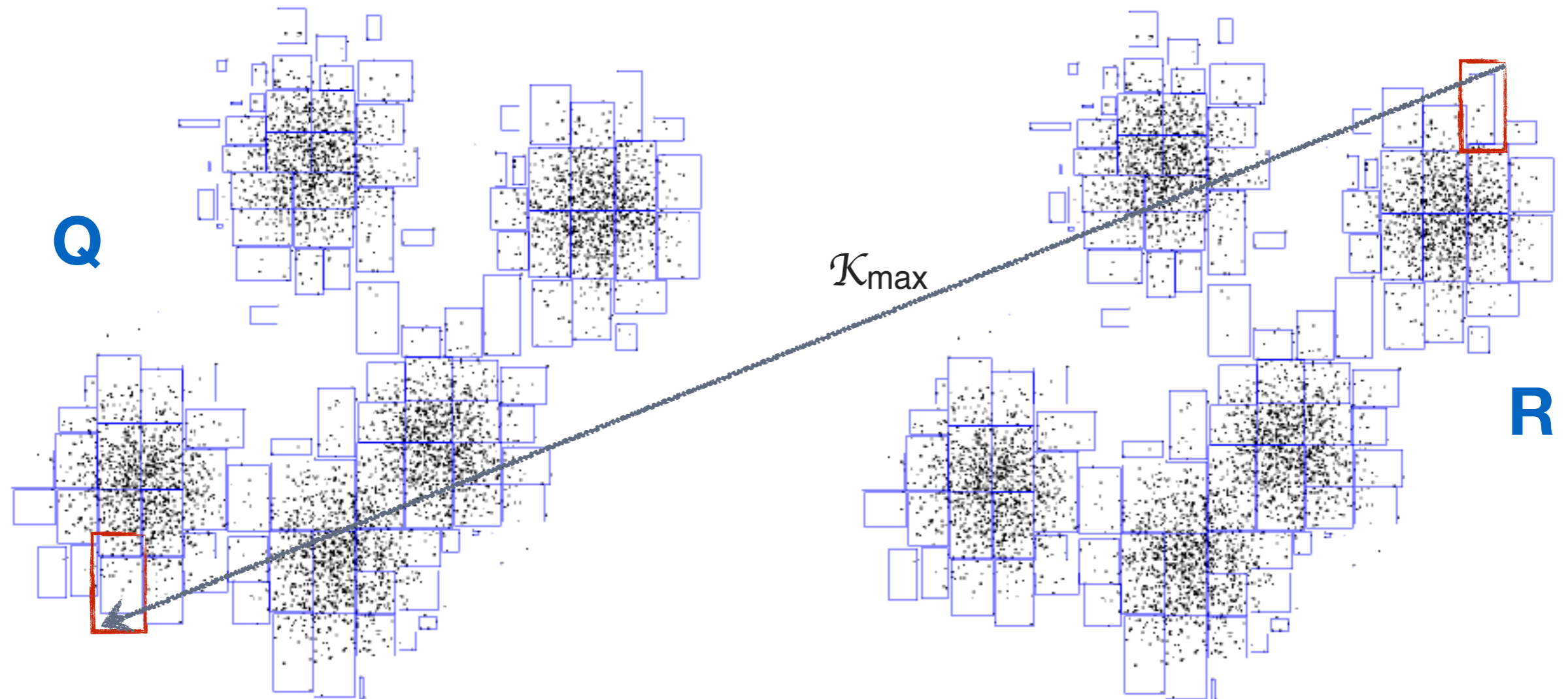
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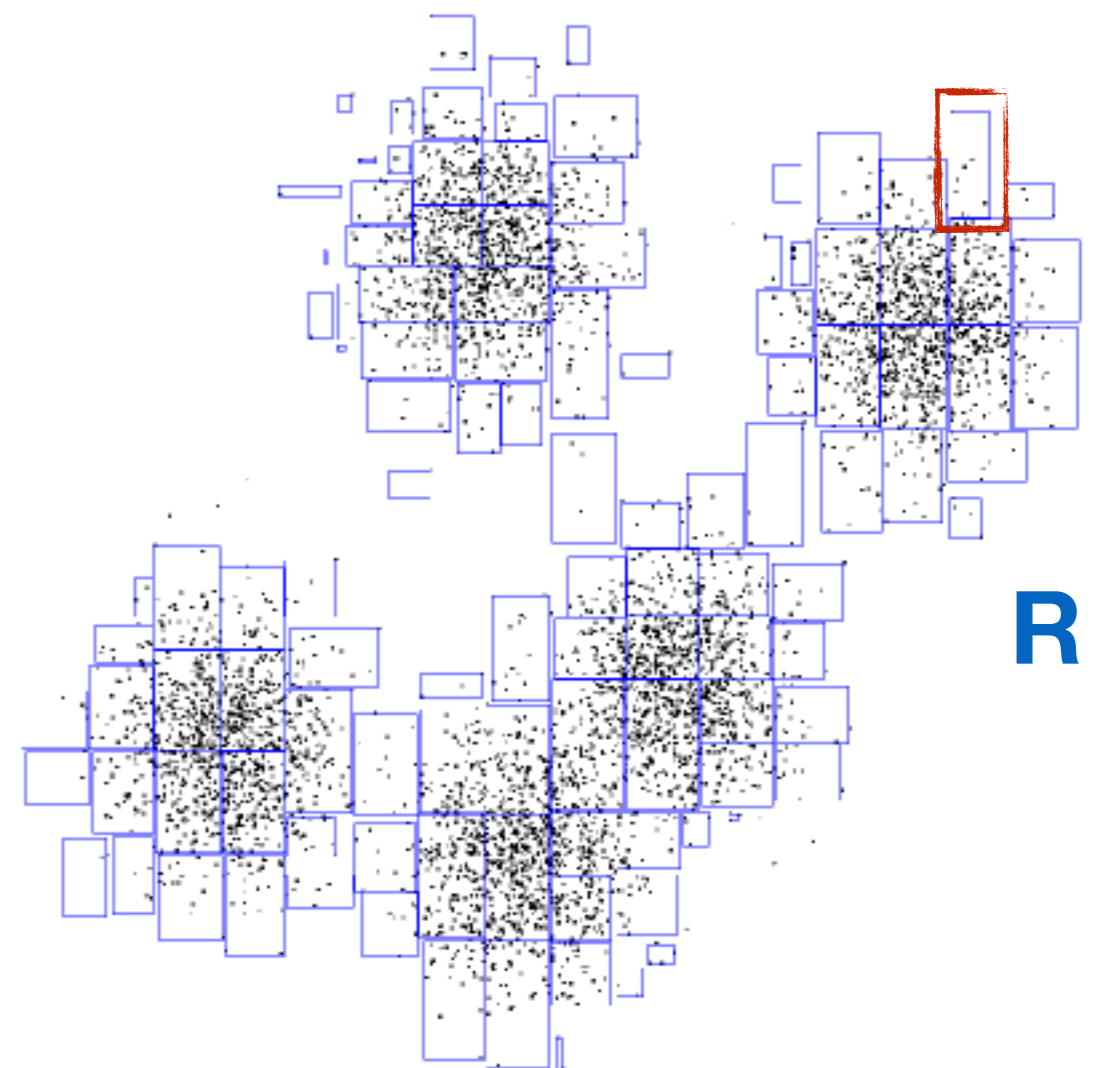
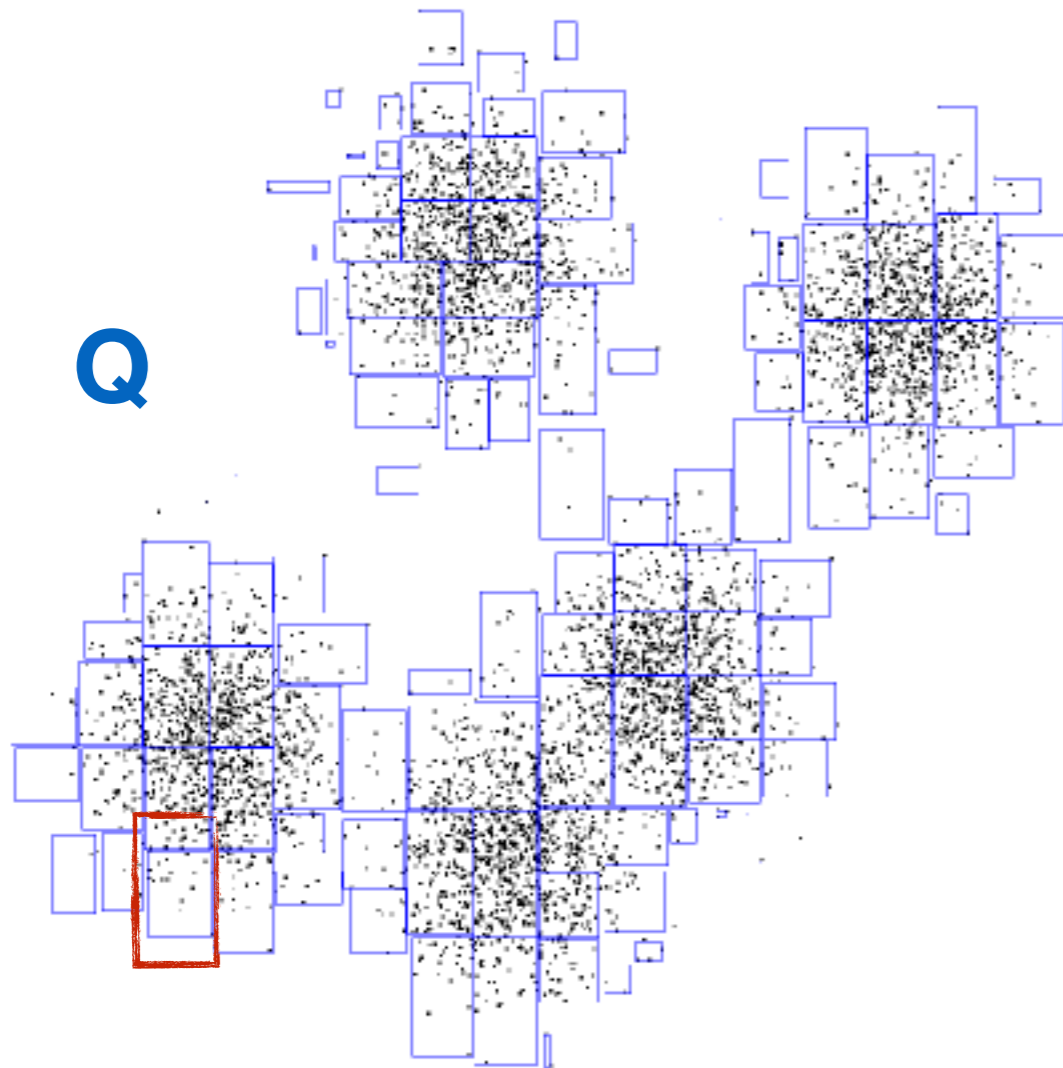
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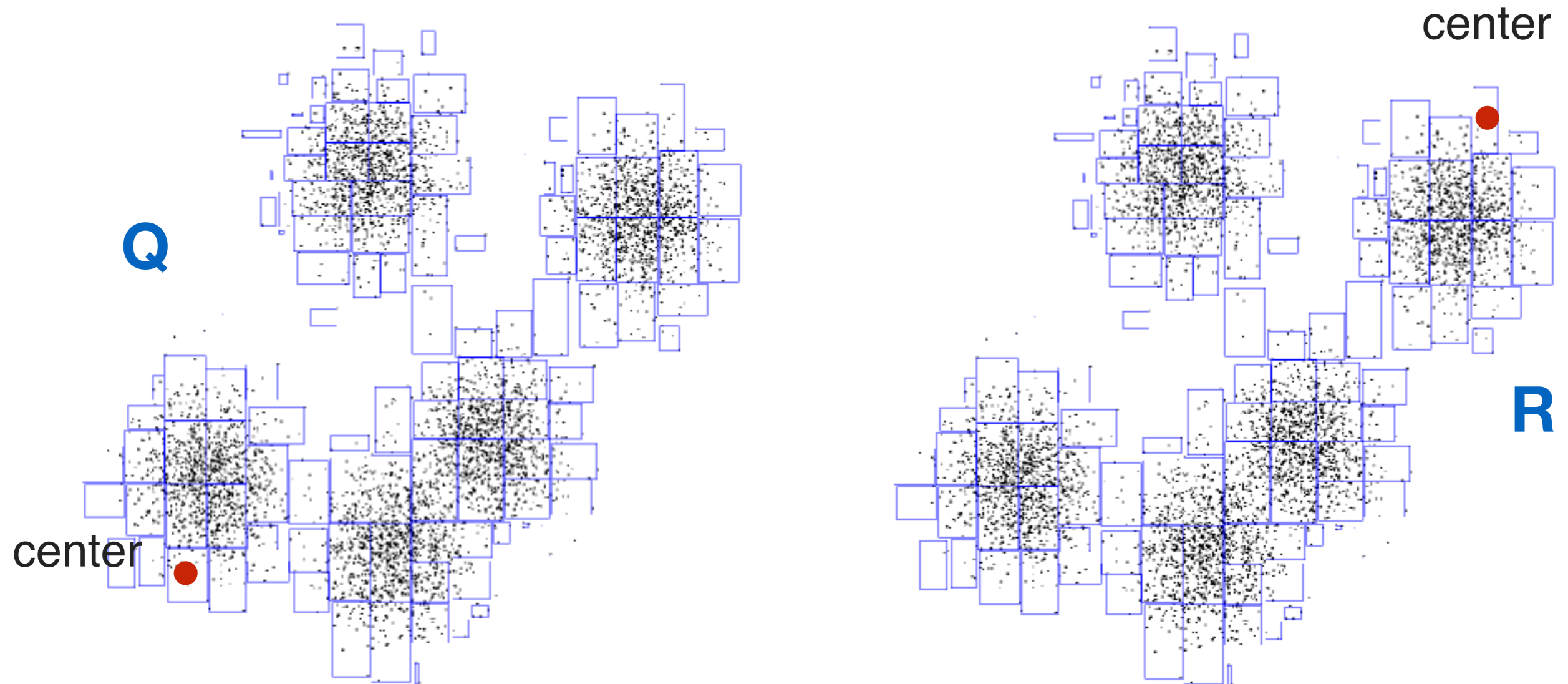
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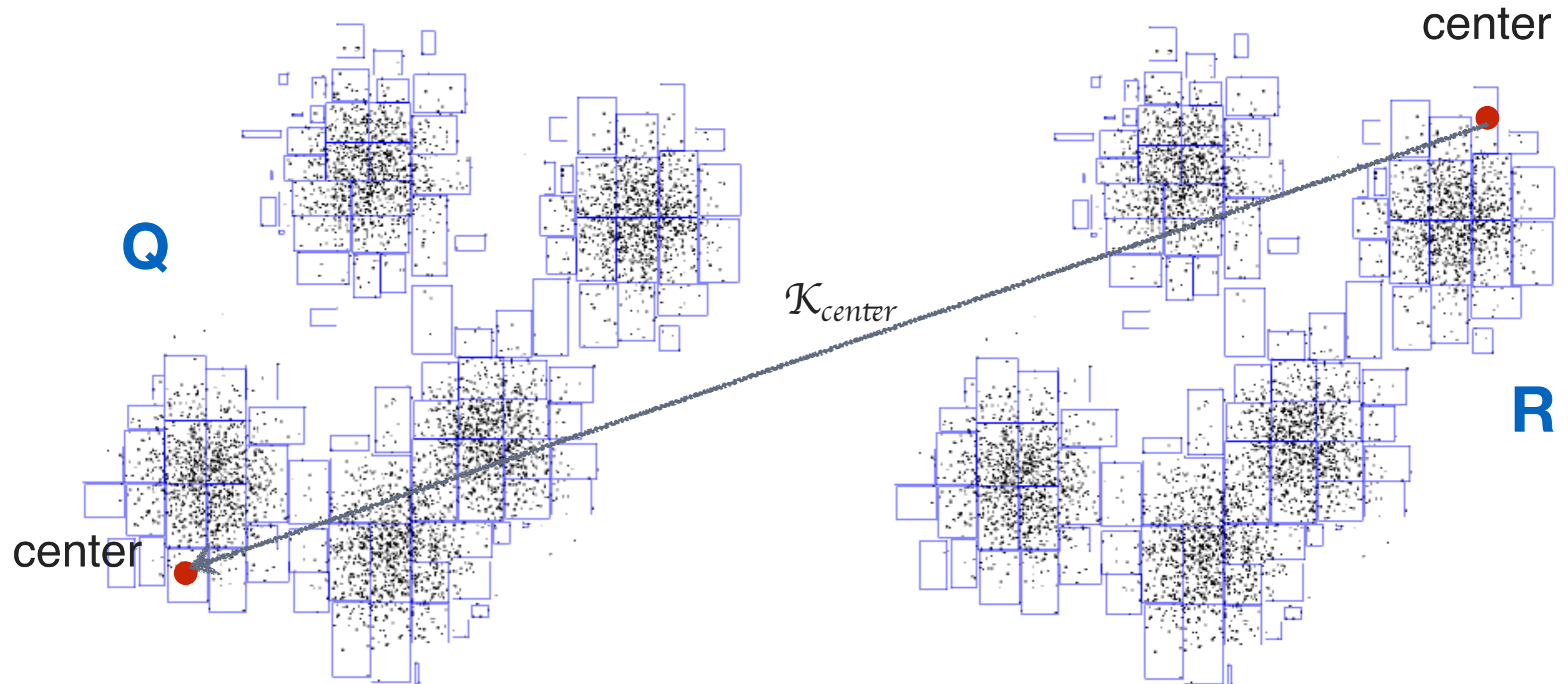
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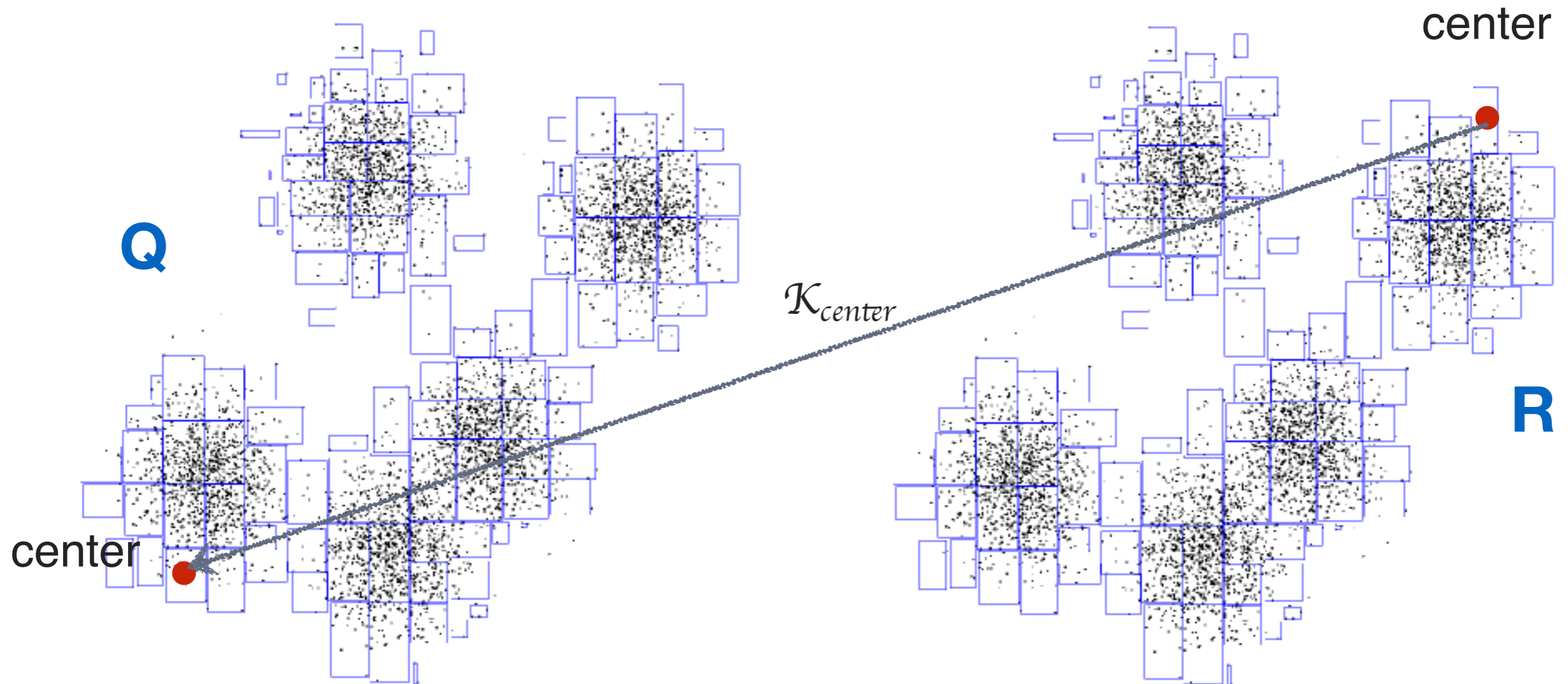
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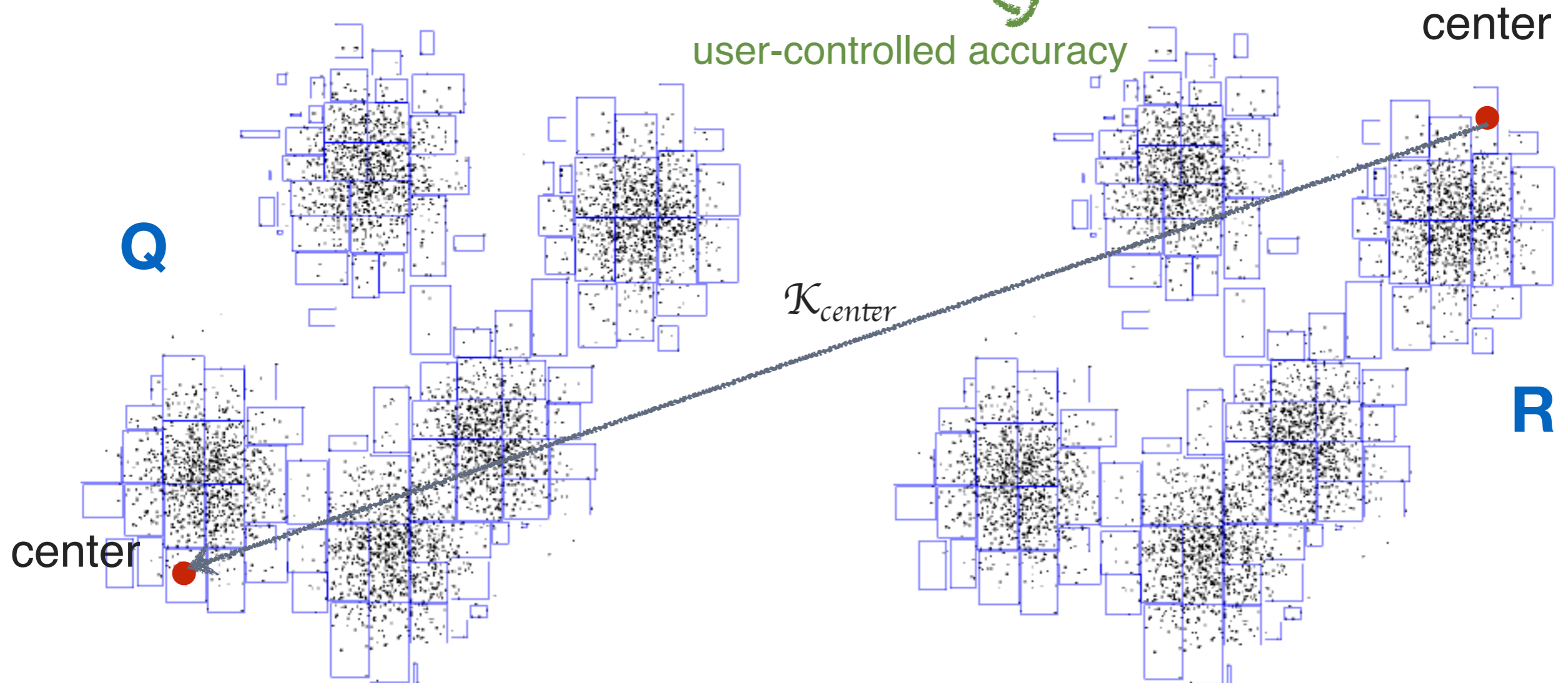
$$\mathcal{K}_{\max} - \mathcal{K}_{\min} < \beta \times \mathcal{K}_{\text{center}}$$



# Approximate Condition for EM

$$\mathcal{K}_{\max} - \mathcal{K}_{\min} < \beta \times \mathcal{K}_{\text{center}}$$

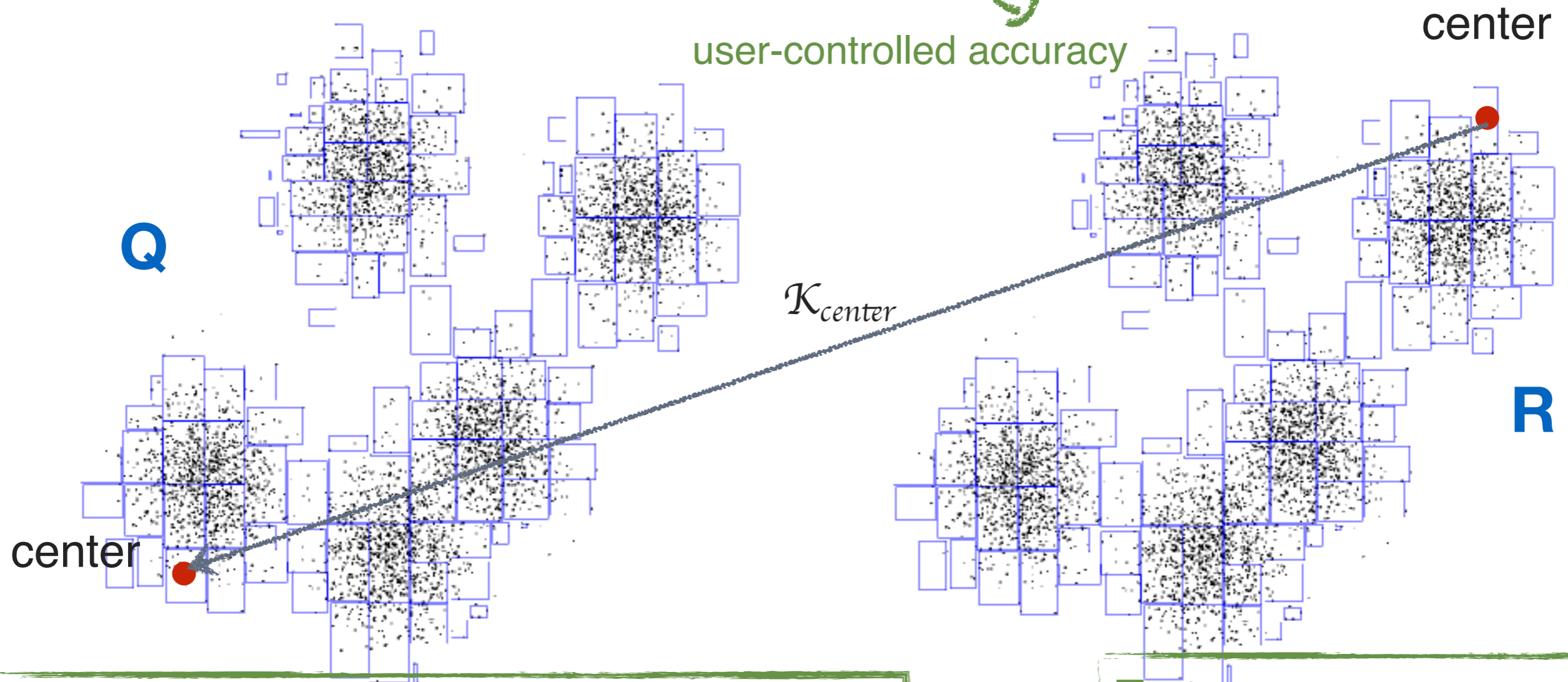
user-controlled accuracy



# Approximate Condition for EM

$$\mathcal{K}_{\max} - \mathcal{K}_{\min} < \beta \times \mathcal{K}_{\text{center}}$$

user-controlled accuracy



log likelihood:

$$\log \sum_{i=1}^K \pi_i \mathcal{N}(x_{\max} | \theta_i) - \log \sum_{i=1}^K \pi_i \mathcal{N}(x_{\min} | \theta_i) < \alpha \left| \log \left( \sum_{i=1}^K \pi_i \mathcal{N}(x_{\text{mean}} | \theta_i) \right) \right|$$

E-step:

$$(r_{i,\max} - r_{i,\min}) < \beta r_{i,\text{mean}} (i = 1, \dots, K)$$

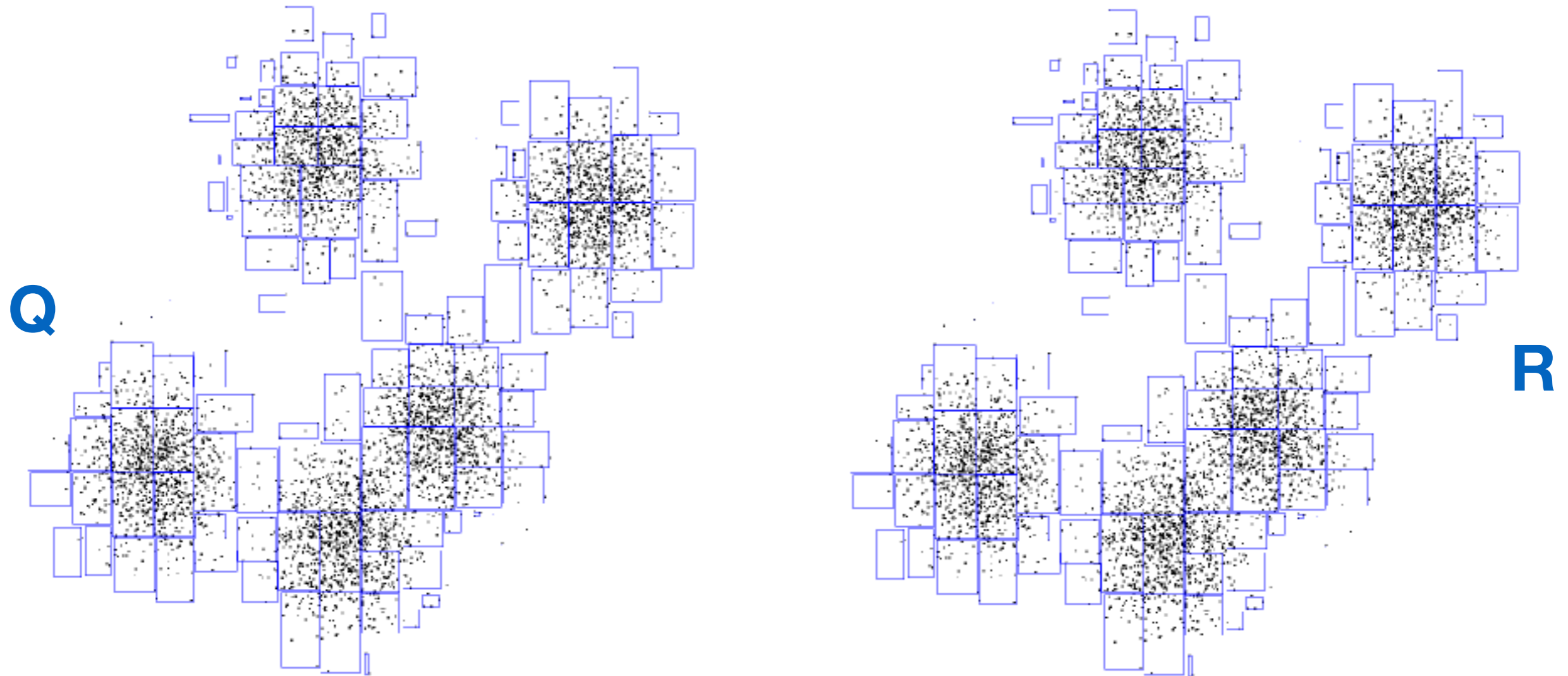


Prune Condition for Hausdorff  
distance:  $\max_q, \min_r \|x_q - x_r\|$

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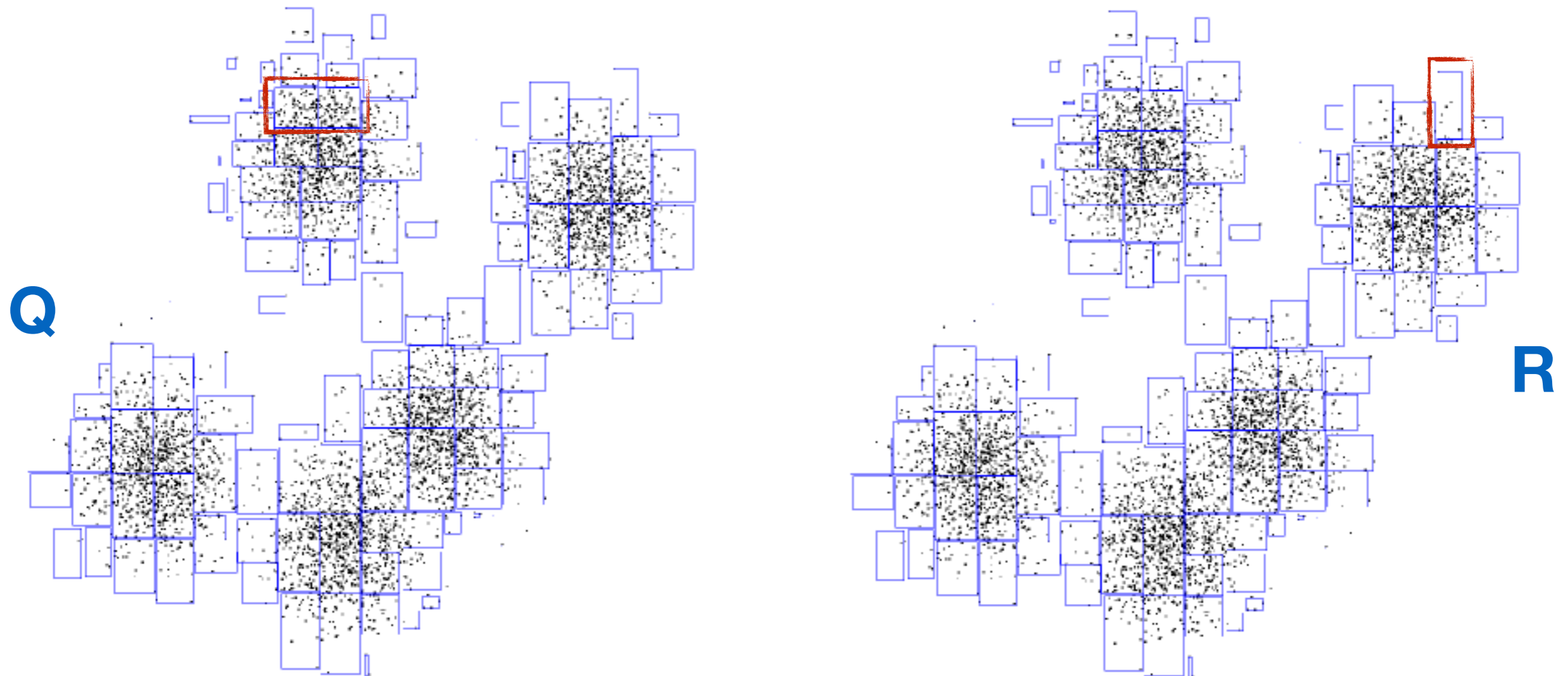
# Prune Condition for Hausdorff distance: $\max_q, \min_r \|x_q - x_r\|$

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# Prune Condition for Hausdorff distance: $\max_q, \min_r \|x_q - x_r\|$

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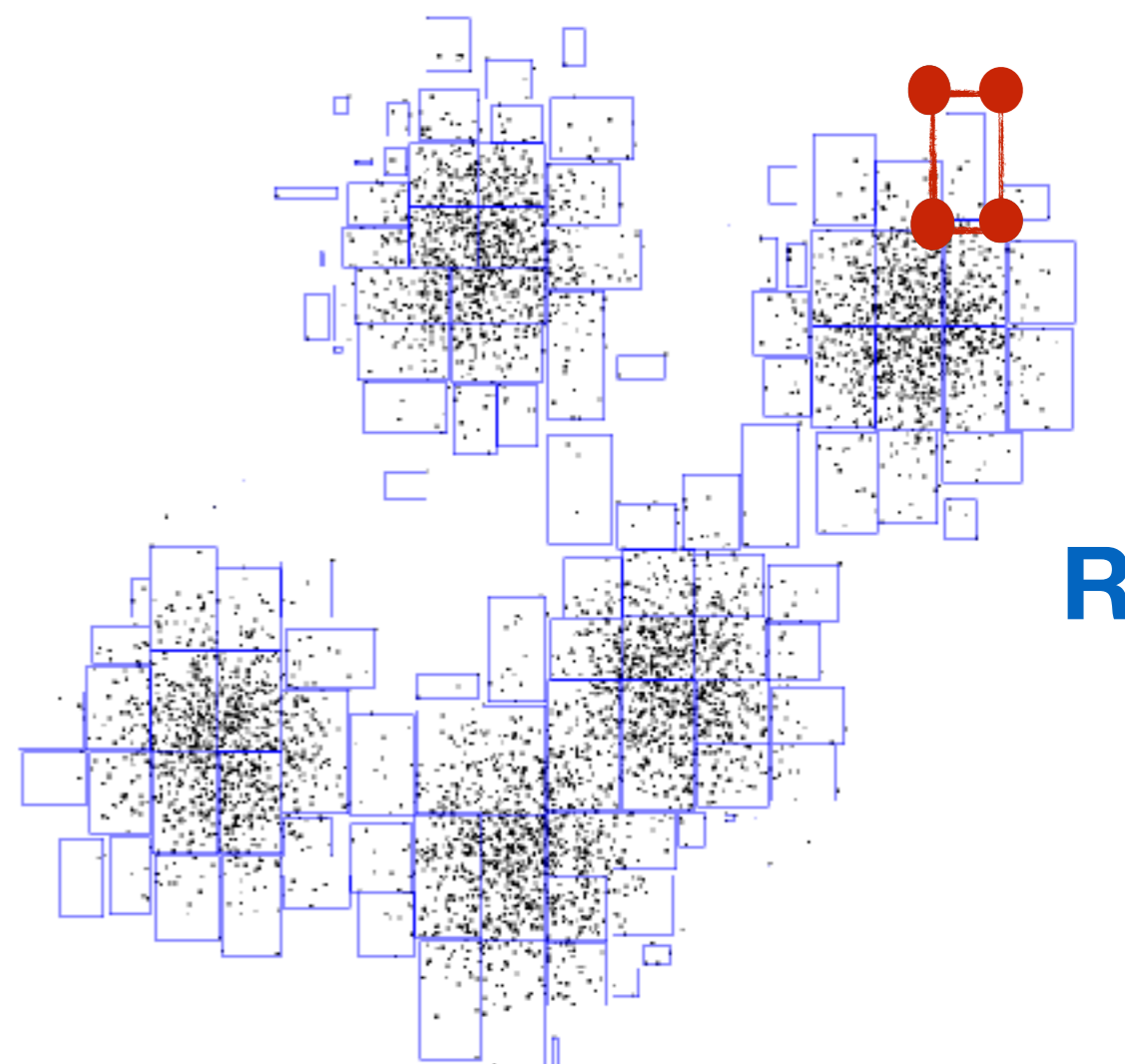
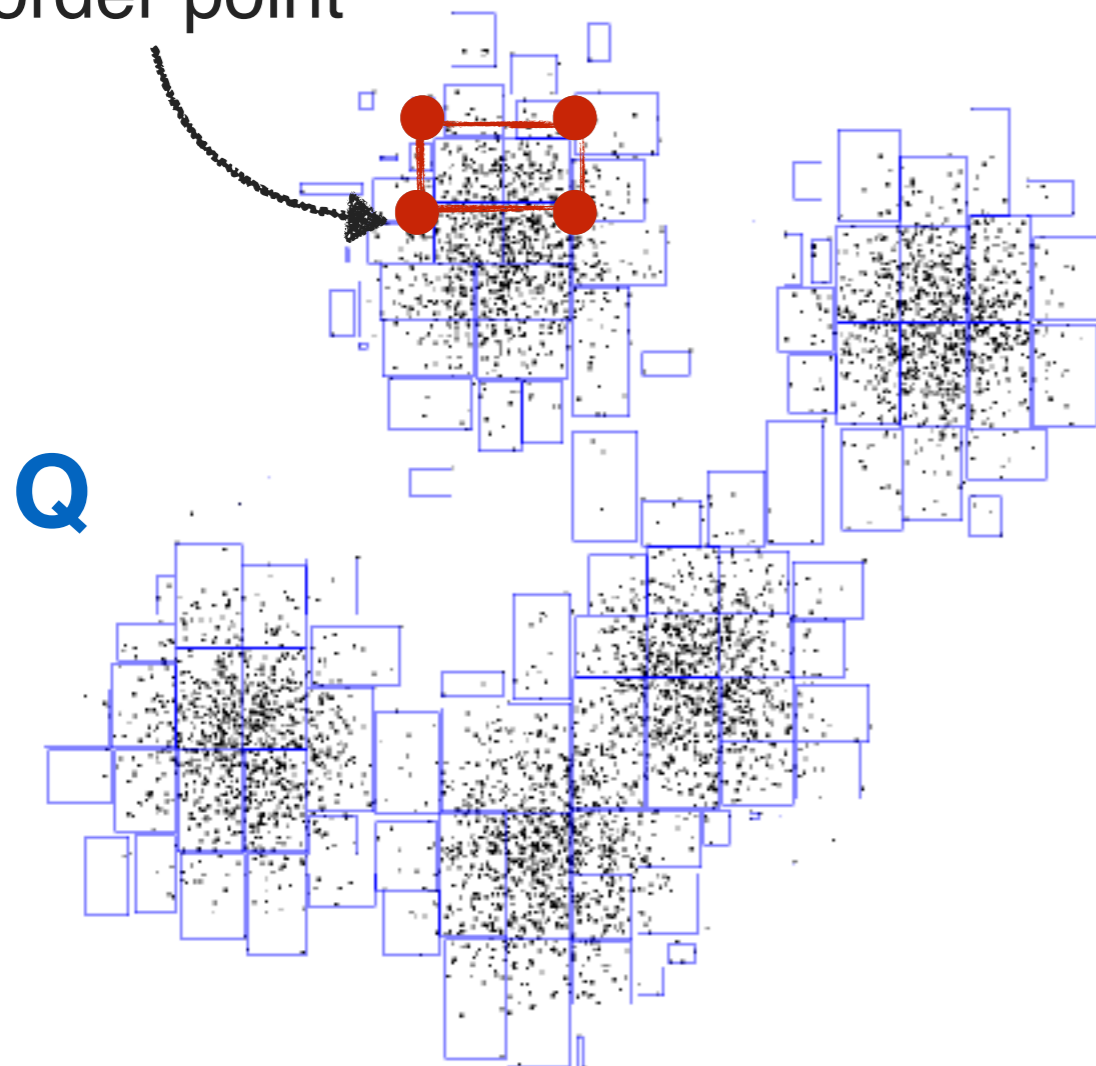


# Prune Condition for Hausdorff distance:

$$\max_q, \min_r \|x_q - x_r\|$$

---

border point

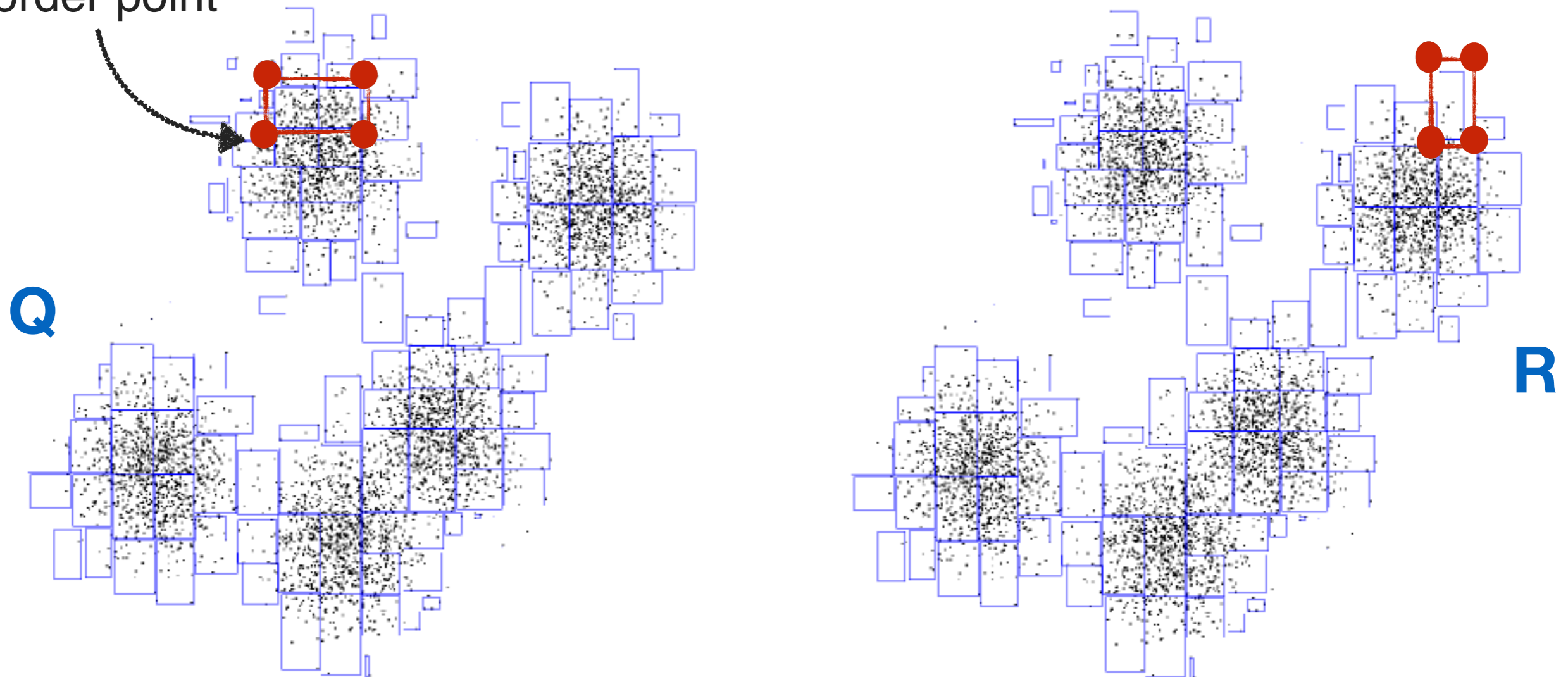


# Prune Condition for Hausdorff distance:

$$\max_q, \min_r \|x_q - x_r\|$$


---

border point



$$op_{\oplus_1}(\tau_1, \mathcal{K}(x_q, x_r) | op_{\oplus_2}(\tau_2, \mathcal{K}(x_q, x_r))) \text{ s.t. } \forall x_q \in \mathcal{N}_q^{\text{border}}, \forall x_r \in \mathcal{N}_r^{\text{border}}$$

# Outline

---

- Introduction
- PASCAL Framework
  - Space Partitioning Trees
  - Tree Traversal
  - Prune/Approximate Generators
- Optimizations & Parallelization
- Experiments & Results
- Conclusions & Future Work

# Optimizations

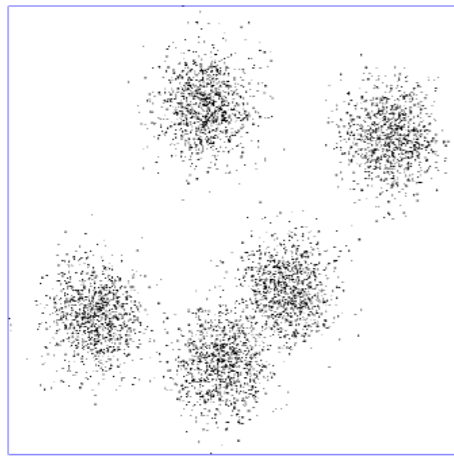
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- Incremental bounding box calculation

# Optimizations

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- Incremental bounding box calculation

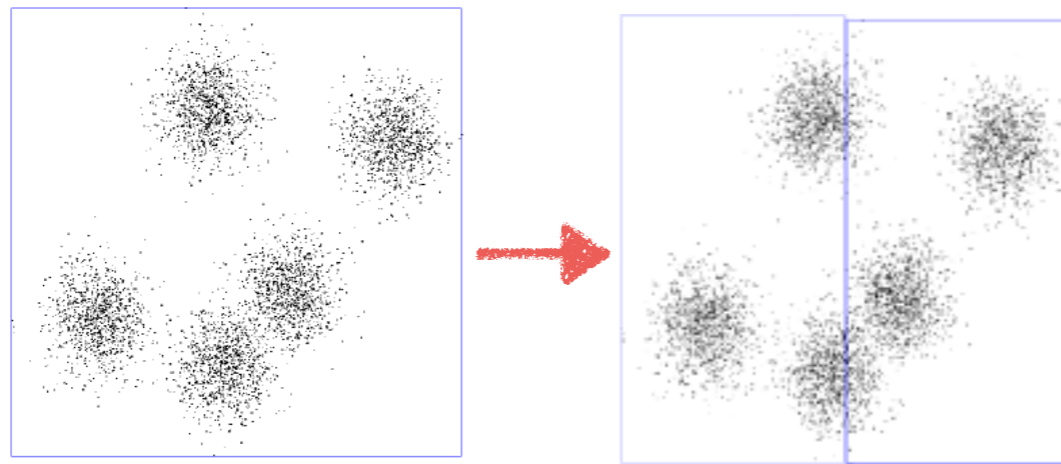




# Optimizations

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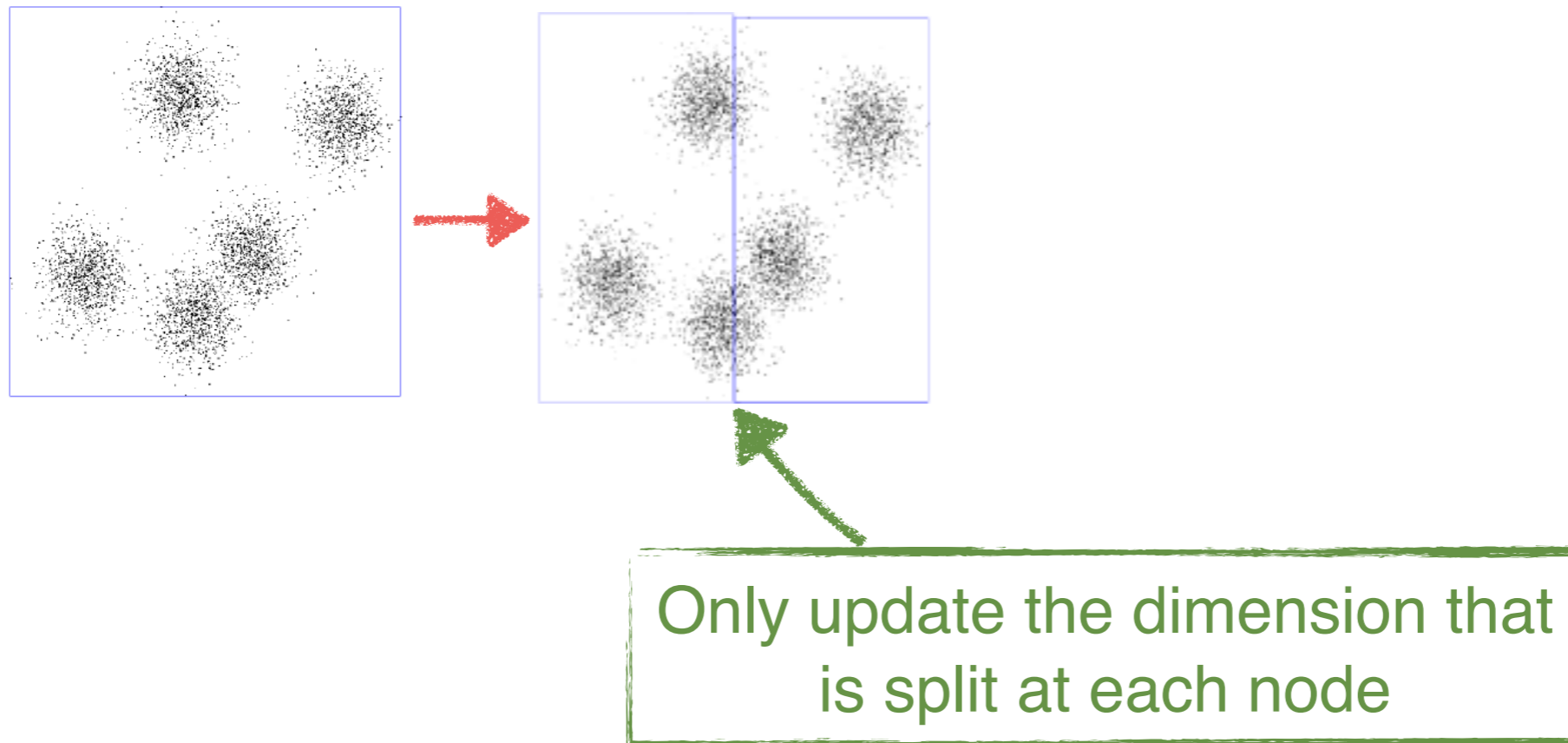
- Incremental bounding box calculation



# Optimizations

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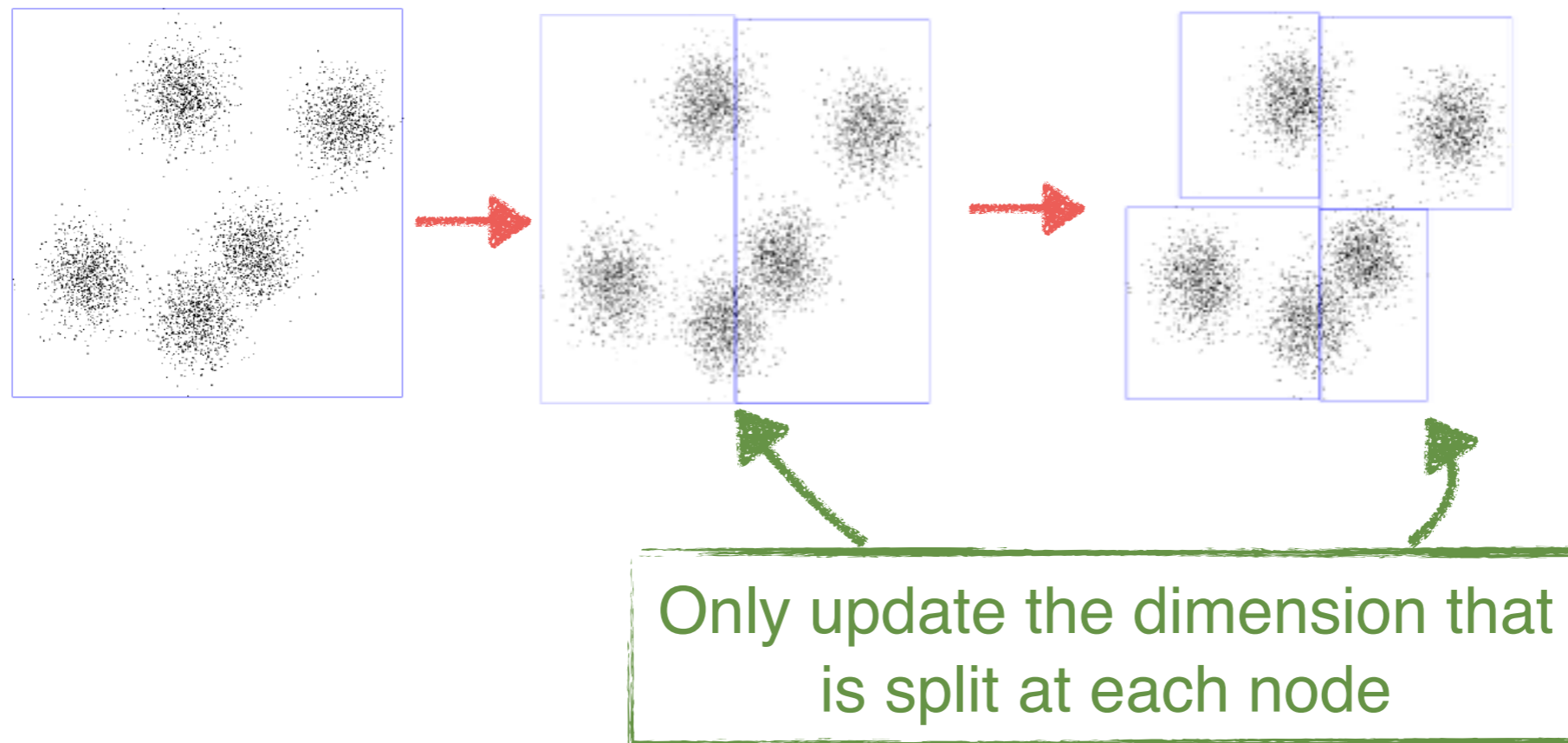
- Incremental bounding box calculation



# Optimizations

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- Incremental bounding box calculation



# Optimizations

---

- Incremental bounding box calculation
- Optimal Metric Calculation
  - Reduced distance
    - *e.g.*, squared Euclidean distance
    - Eliminates expensive **sqrt** instruction with long latencies
  - Partial distance
    - Big payoff for large dimensional datasets

# Optimizations

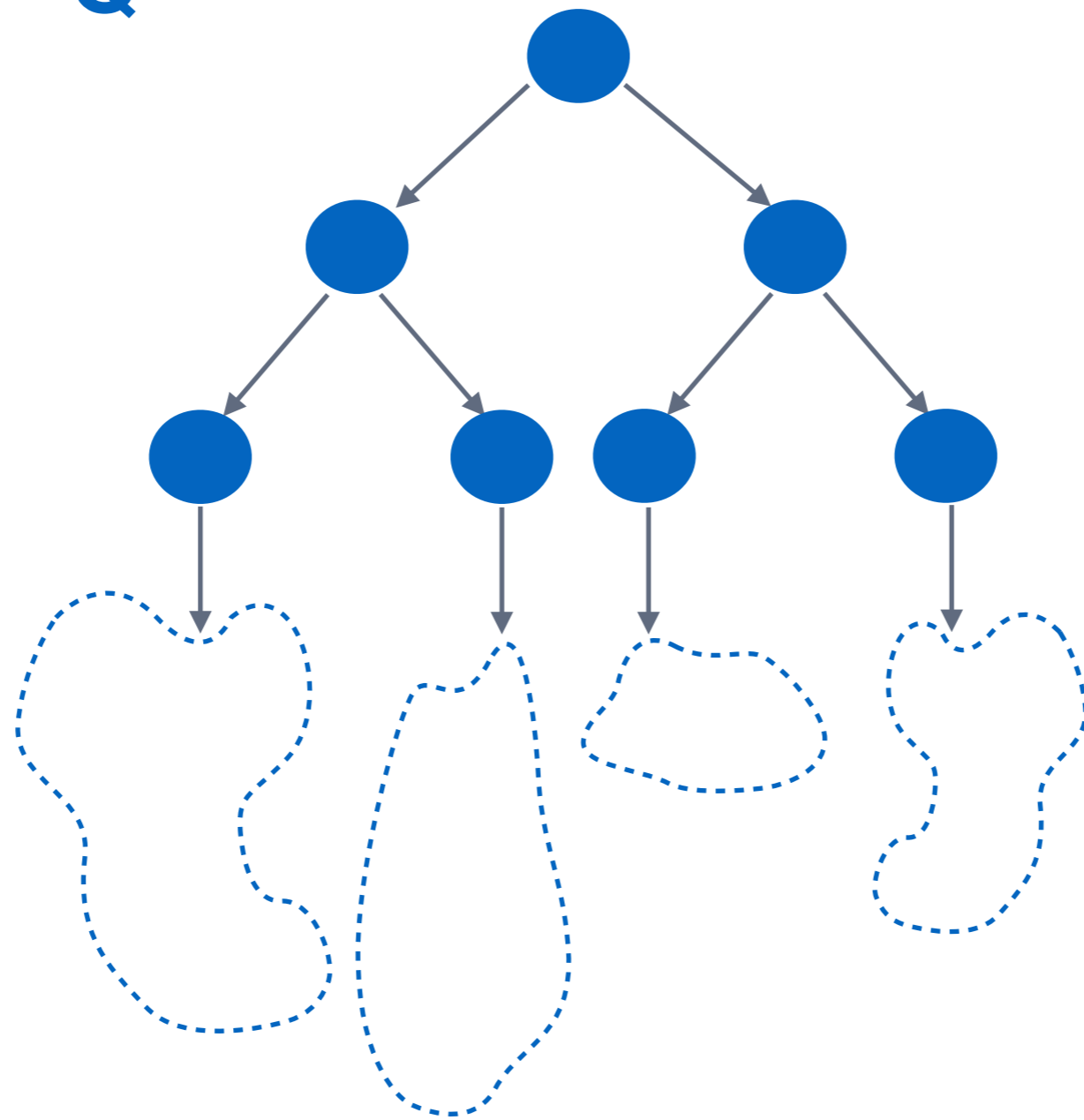
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- Incremental bounding box calculation
- Optimal Metric Calculation
  - Reduced distance
    - *e.g.*, squared Euclidean distance
    - Eliminates expensive **sqrt** instruction with long latencies
  - Partial distance
    - Big payoff for large dimensional datasets
- Incremental distance calculation
  - Node-to-node distance computed incrementally from parent's distance in constant time

# Parallelization

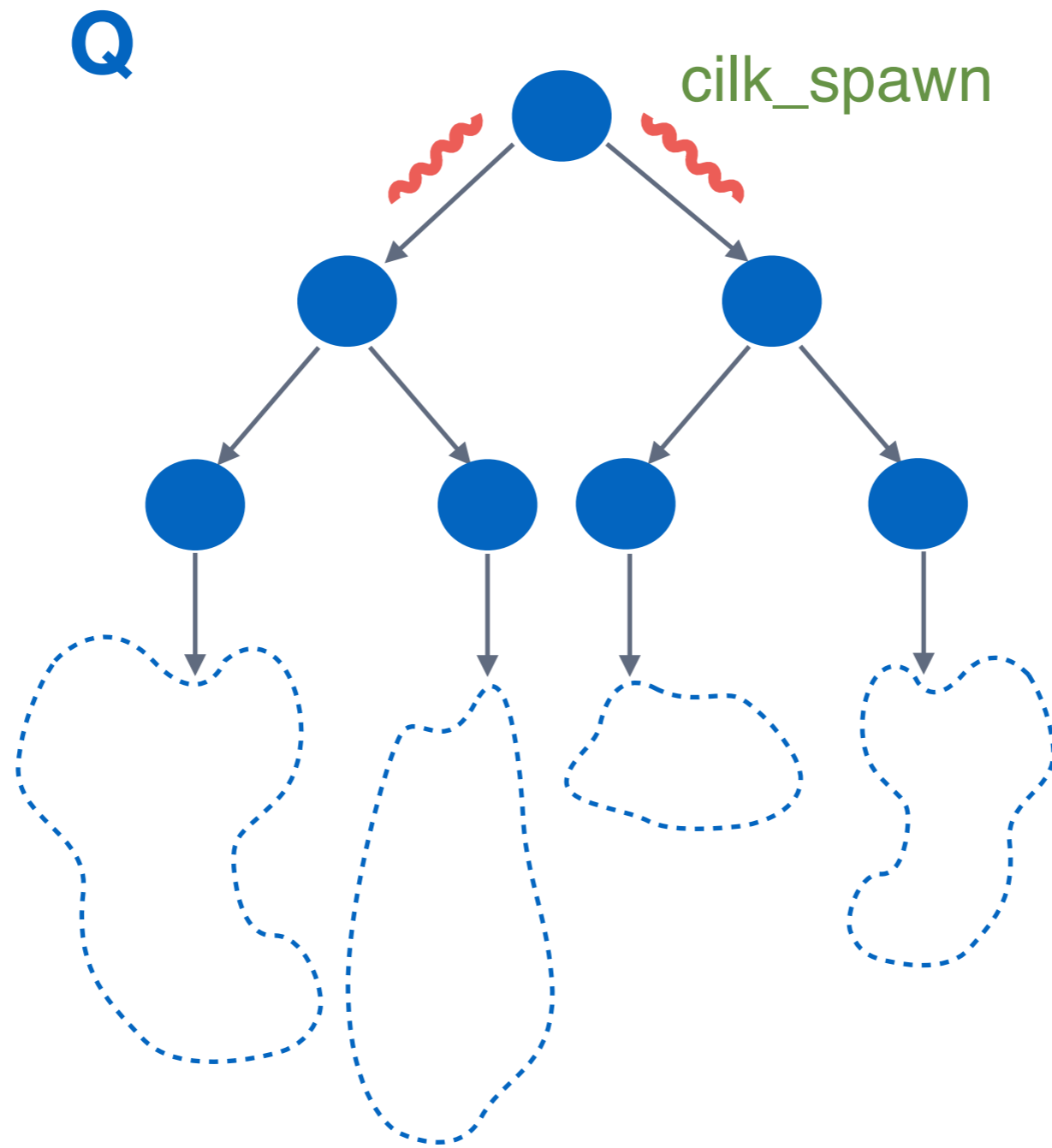
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Q

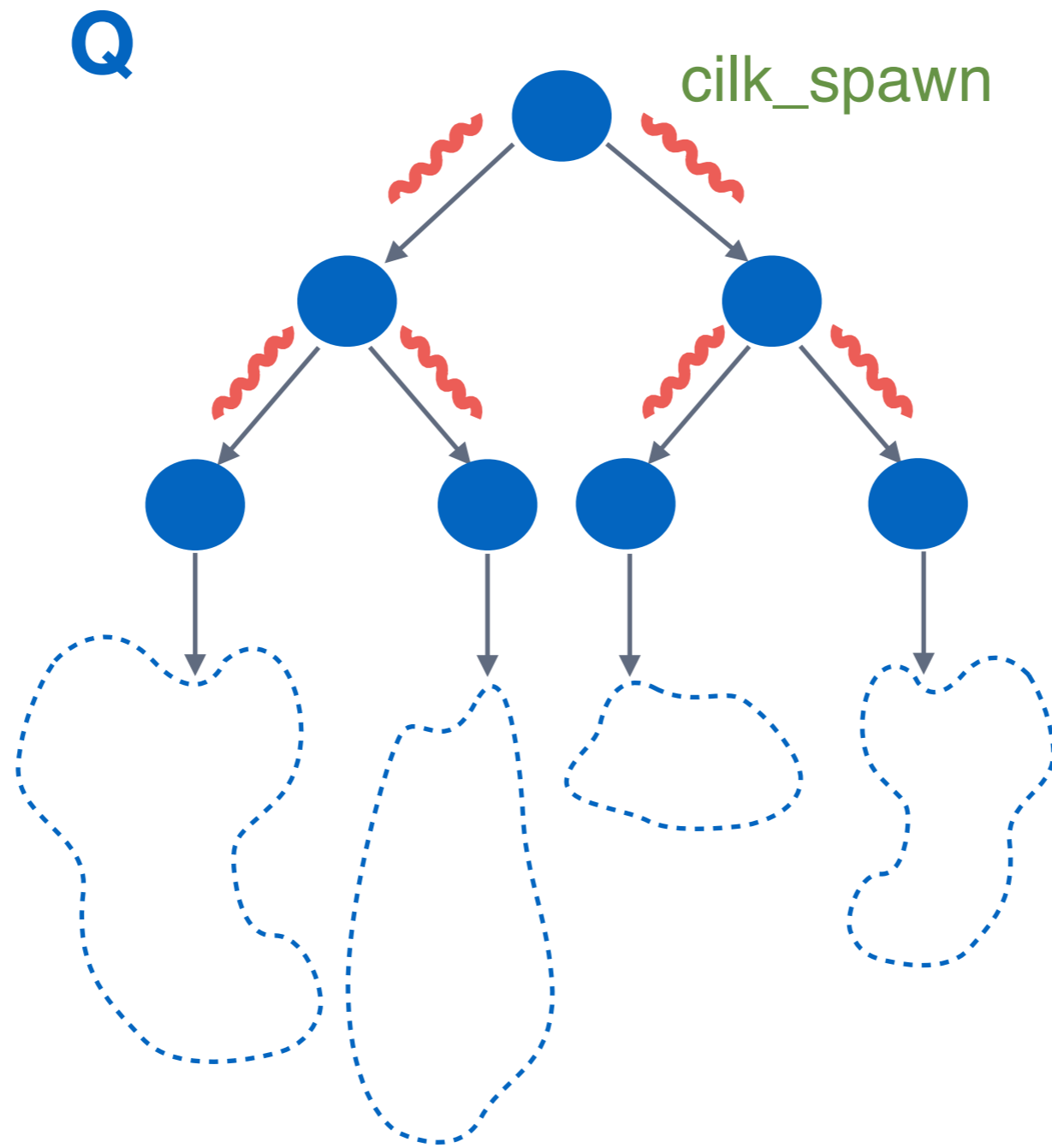


# Parallelization

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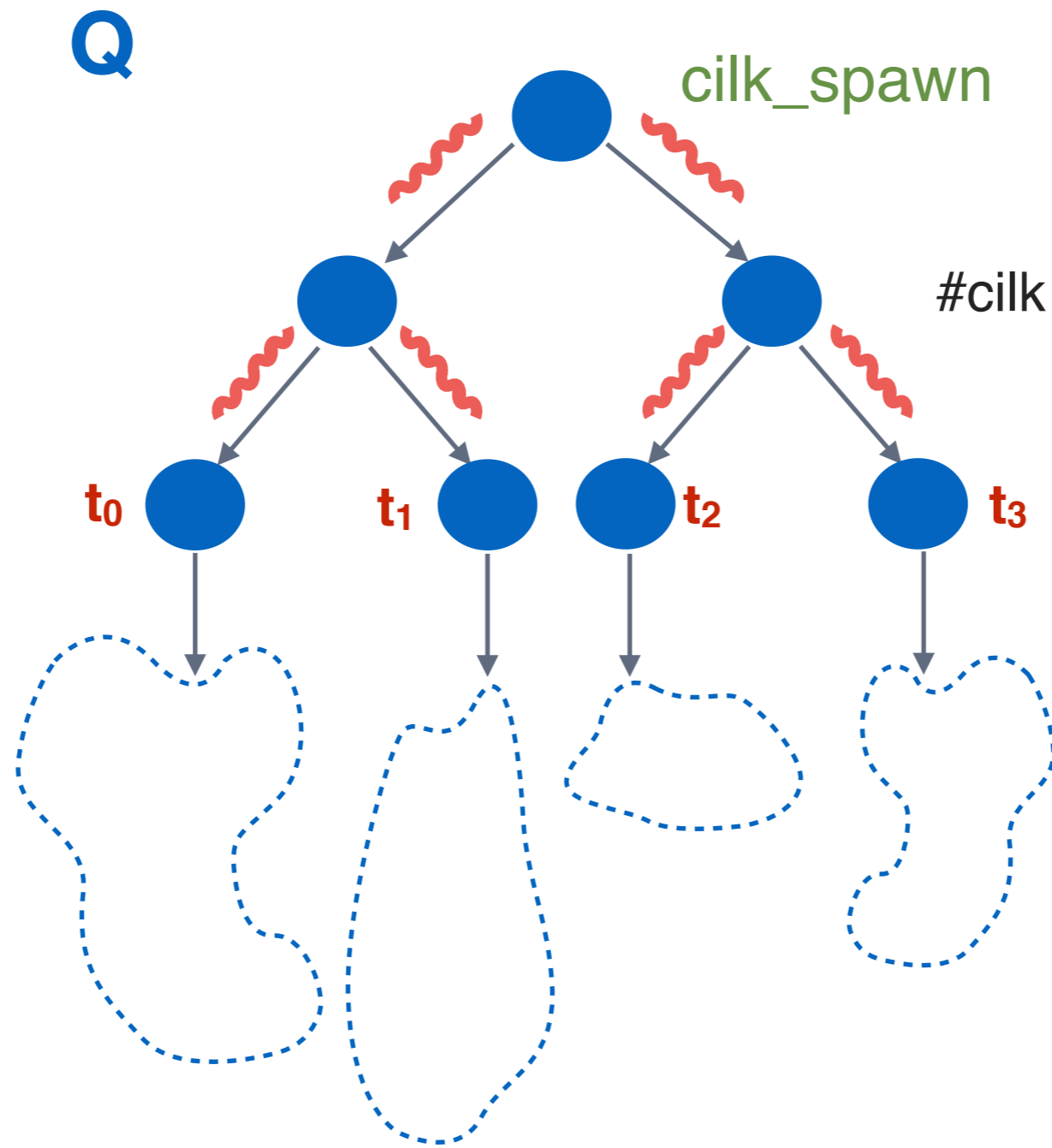


# Parallelization



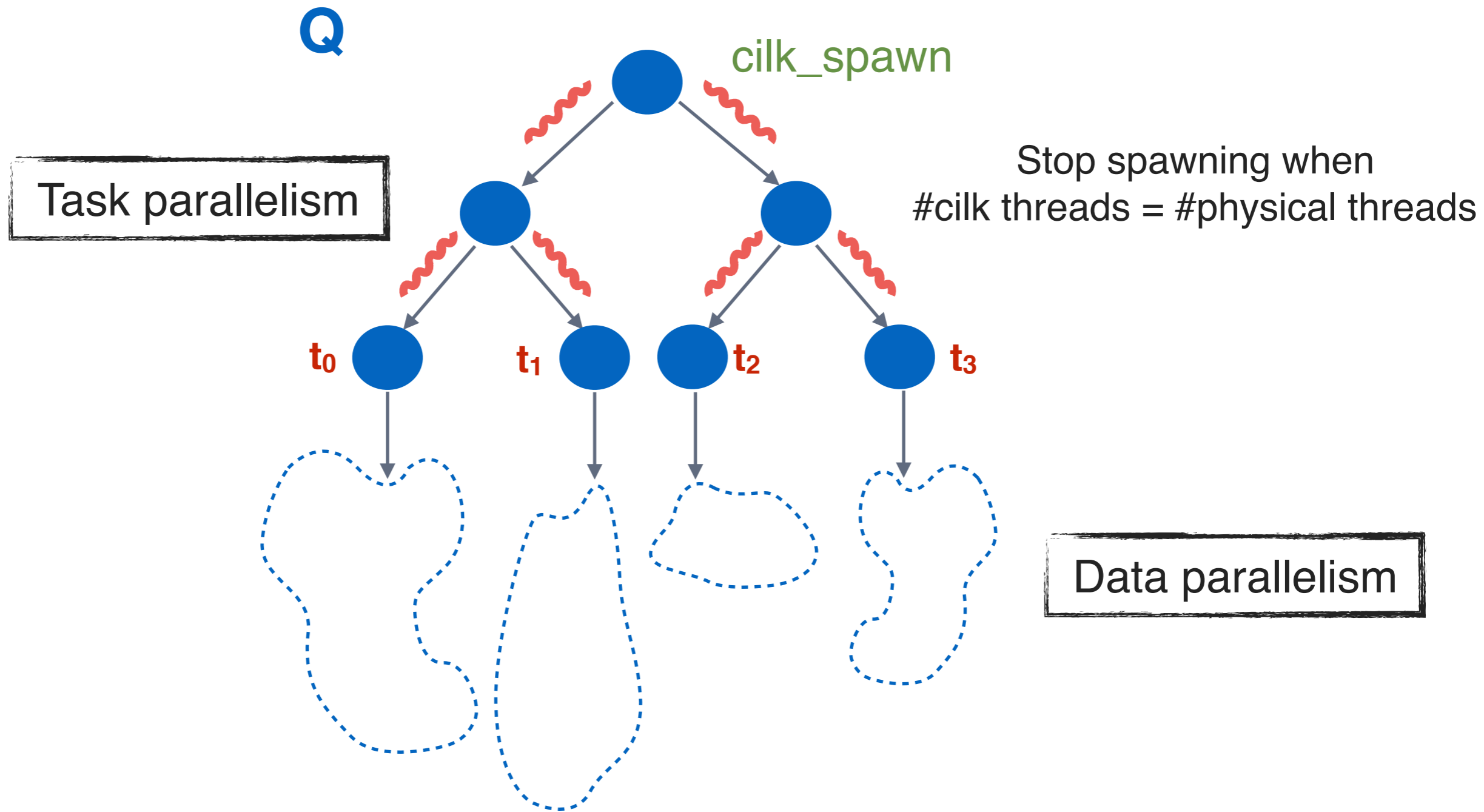


# Parallelization

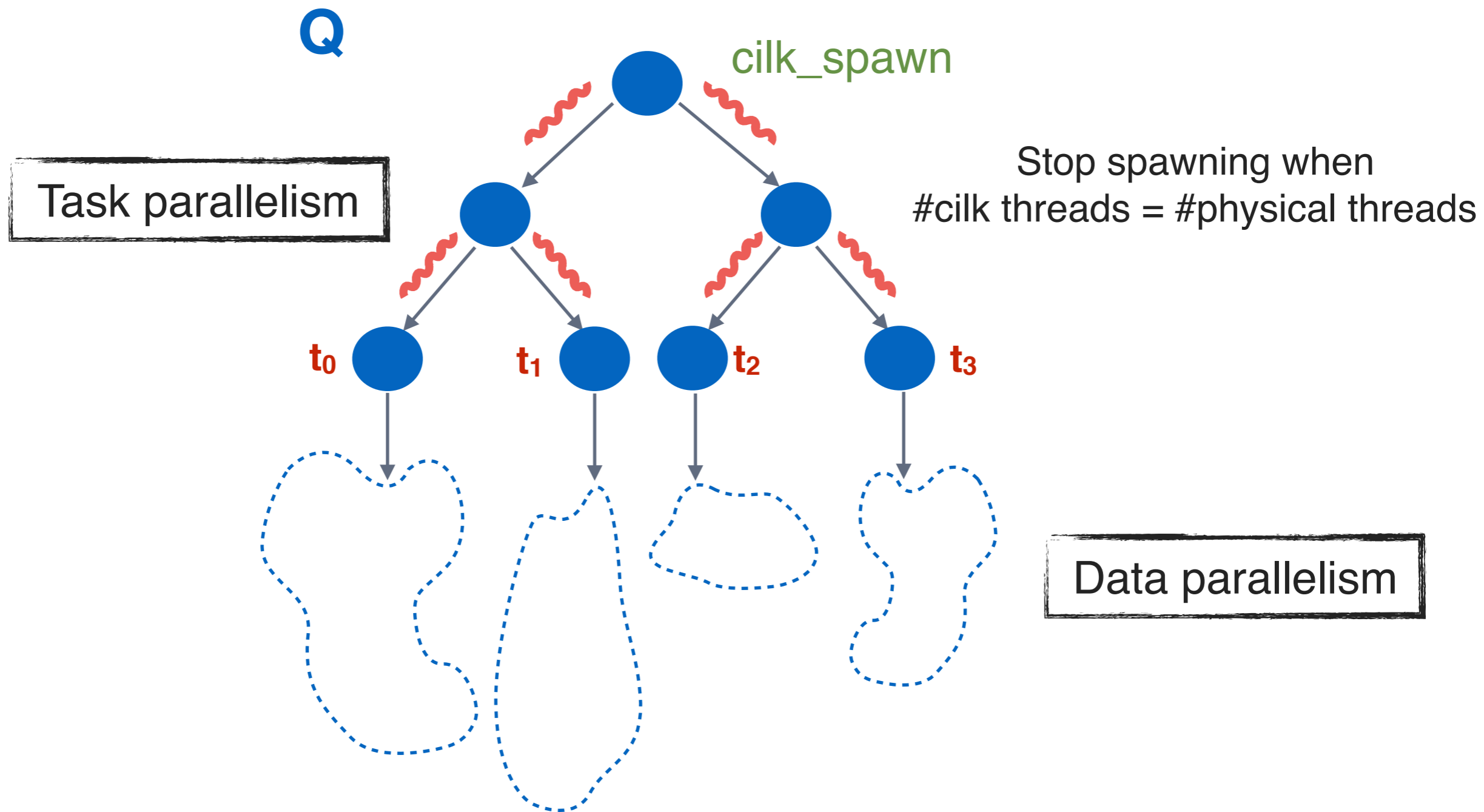


Stop spawning when  
#cilk threads = #physical threads

# Parallelization



# Parallelization



Pruning/Approximation causes load imbalance

# Outline

---

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- PASCAL Framework
  - Space Partitioning Trees
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# Experimental Setup

- Architecture

- Dual-socket Intel Xeon E5-2630 v3 processor (Haswell-EP)
- Each socket has 8 cores
- Theoretical peak performance of 614.4 GFlops

- Compiler

- Intel C++ compiler (icpc v15.0.2)
- Python v2.7.6 (Scikit-learn)
- Java v1.8.0 (Weka)

Dataset	$N$	$d$
Yahoo!	41904293	11
IHEPC	2075259	9
HIGGS	11000000	28
Census	2458285	68
KDD	4898431	42

# Case Studies (Direct)

---

- Nearest Neighbors  $\forall q, \arg \min_r \|x_q - x_r\|$
- Range-Search  $\forall q, \bigcup \arg_r I(\|x_q - x_r\| \leq h)$
- Kernel Density Estimation  $\forall q, \frac{1}{N_r} \sum_r K\left(\frac{\|x_q - x_r\|}{\sigma}\right)$
- Hausdorff Distance  $\max_q, \min_r \|x_q - x_r\|$

# Case Studies (Iterative)

---

- Expectation Maximization (EM)

E-step  $\forall q, \forall r, \frac{\pi_k \mathcal{N}(x_n | \mu_k, \Sigma_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(x_n | \mu_j, \Sigma_j)}$

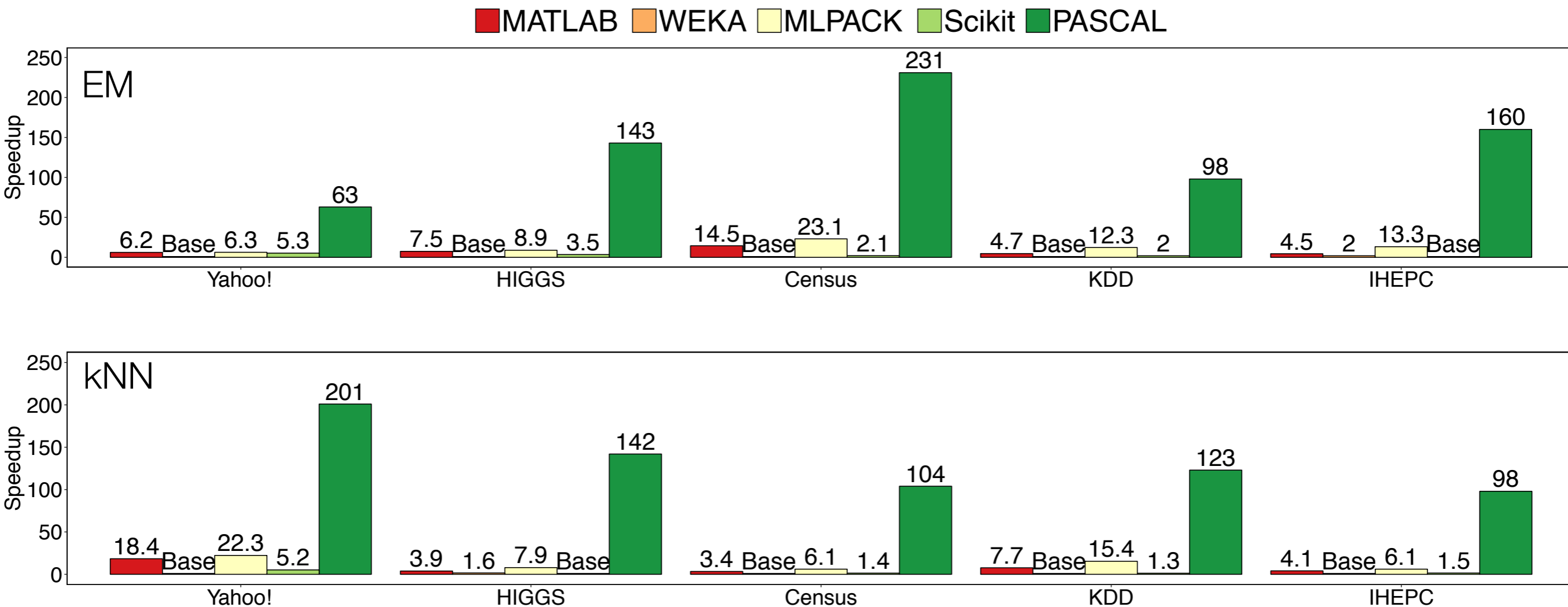
M-step

Log-likelihood  $\sum_{n=1}^N \log \sum_{k=1}^K \pi_k \mathcal{N}(x_n | \mu_k, \Sigma_k)$

- Euclidean Minimum Spanning Tree  $\forall q, \arg \min_r \|x_q - x_r\|$

# Library Comparison

- **Weka:** 6,677,053 downloads, written in Java
- **Scikit-learn:** 121,841 downloads, written in Python
- **MATLAB:** over 1,000,000 licensed users, uses C in backend
- **MLPACK:** exploits C++ language features to provide maximum performance

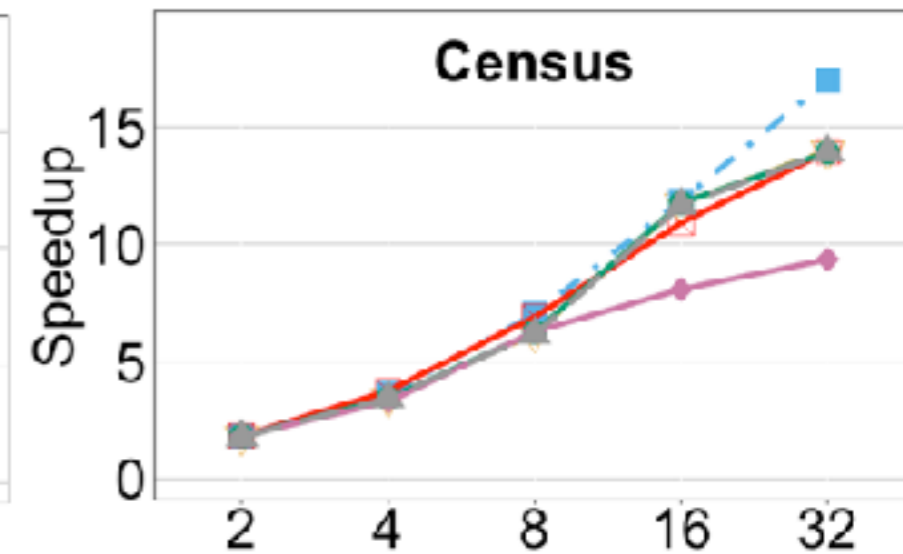
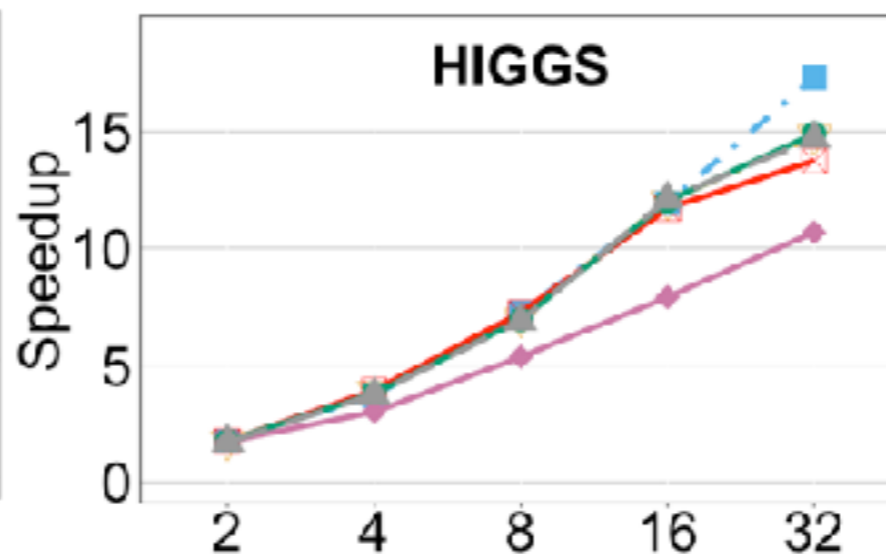
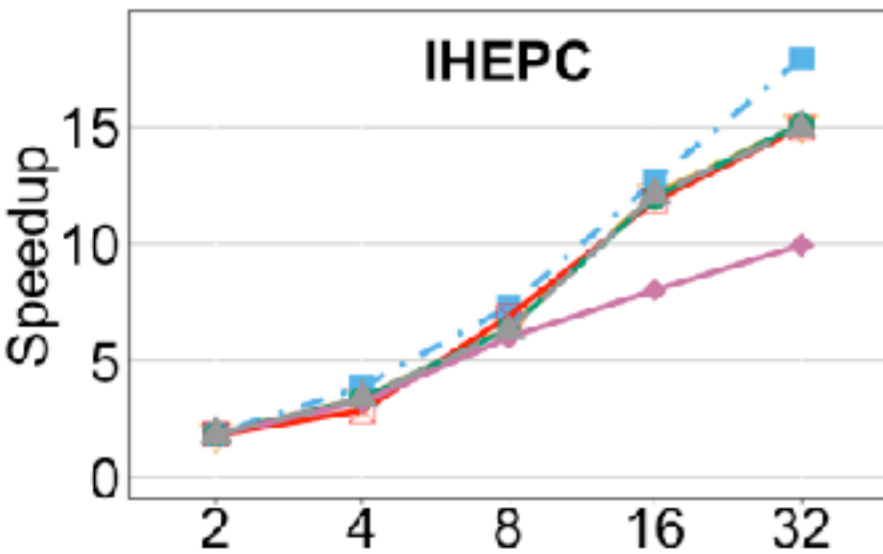
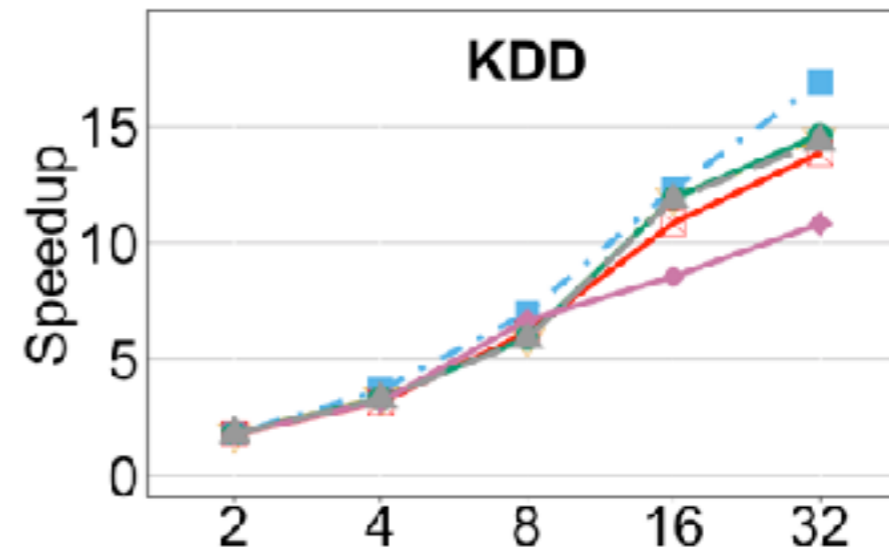
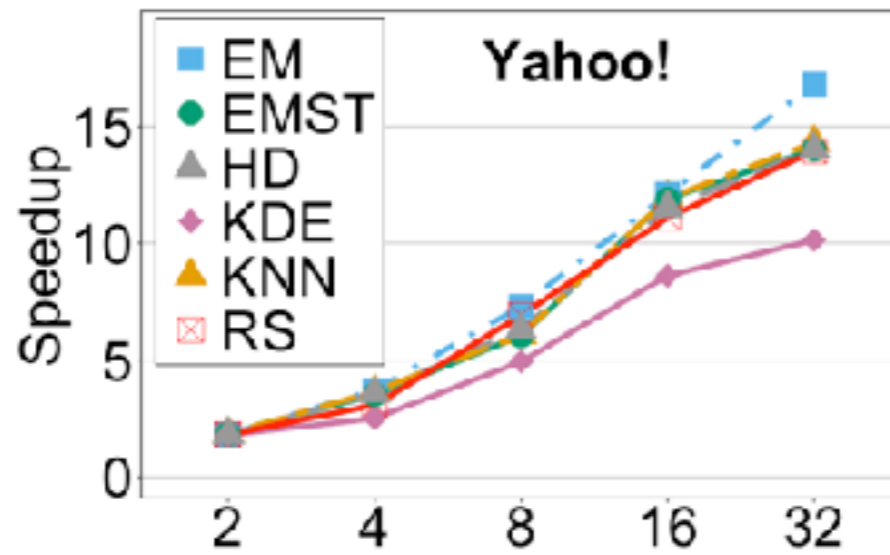




# Speedup Breakdown

	KNN			EM			KDE			HD			RS			EMST		
	Alg	+Opt	+Par	Alg	+Opt	+Par	Alg	+Opt	+Par	Alg	+Opt	+Par	Alg	+Opt	+Par	Alg	+Opt	+Par
Yahoo!	3.1	12.1	173.1	1.6	3.2	53.7	2.1	9.1	92.1	2.5	11.5	161.1	2.2	9.1	126.8	2.9	11.9	166.7
HIGGS	2.1	7.3	108.1	1.5	6.8	117.6	1.7	4.7	50.1	1.9	6.1	89.6	1.9	6.3	86.5	2.0	6.9	102.8
Census	1.4	6.5	90.8	1.3	11.2	190.0	1.4	8.1	75.6	1.3	10.2	141.8	1.3	10.4	144.9	1.4	10.9	151.6
KDD	1.6	6.8	100.7	1.4	4.1	70.9	1.5	3.1	33.5	1.4	3.8	54.4	1.4	5.1	70.5	1.5	3.8	55.5
IHEPC	3.0	4.3	61.5	1.5	7.6	127.6	2.0	5.4	53.6	2.5	6.8	101.3	2.1	6.3	94.1	2.9	7.1	107.1

# Scalability



# Summary and Status

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- First generalized algorithmic framework for N-body problems
  - Out-of-the-box new optimal algorithms
    - $O(N \log N)$  EM algorithm
    - $O(N)$  Hausdorff distance algorithm
  - Generalizes to more than two operators
  - 10-230x speedup from optimal tree algorithm, domain-specific optimizations and parallelization
- Short-term: DSL + code generator for base-case, optimizations and parallelization
- Long-term: Extend to GPUs and distributed memory systems